

Shi-type estimates of the Ricci flow based on Ricci curvature

CHIH-WEI CHEN

Dedicated to Professor Gérard Besson on the occasion of his 60th birthday

Abstract. We prove that the magnitude of the derivative of Ricci curvature can be uniformly controlled by the bounds of Ricci curvature and injectivity radius along the Ricci flow. As a consequence, a precise uniform local bound of curvature operator can be constructed from local bounds of Ricci curvature and injectivity radius among all n -dimensional Ricci flows. In particular, we show that every Ricci flow with $|\text{Ric}| \leq K$ must satisfy $|\text{Rm}| \leq Ct^{-1}$ for all $t \in (0, T]$, where C depends only on the dimension n , and T depends on K and the injectivity radius $\text{inj}_{g(t)}$.

In the second part of this paper, we discuss the behavior of Ricci curvature and its derivative when the injectivity radius is thoroughly unknown. In particular, another Shi-type estimate for Ricci curvature is derived when the derivative of Ricci curvature is controlled by the derivative of scalar curvature.

Mathematics Subject Classification (2010): 53C44 (primary); 58J05 (secondary).

1. Introduction

The Ricci flow on a Riemannian manifold (M, g_0) , which was proposed by R. Hamilton in [16], is defined by

$$\begin{cases} \frac{\partial}{\partial t}g(x, t) = -2\text{Ric}_g(x, t) \\ g(x, 0) = g_0 \end{cases}$$

and is presumed to be able to improve the Riemannian metric g_0 . Hamilton showed that a Riemannian metric with positive Ricci curvature on a closed 3-dimensional

I am grateful to NCTS and TIMS in Taiwan for the constant generous supports. This is a project supported by MOST, no. 107-2115-M-110-007-MY2.

Received April 06, 2018; accepted in revised form December 05, 2018.
Published online December 2020.

manifold can be deformed to be rounder and rounder along the Ricci flow. Indeed, by using interpolation techniques, he derived bounds for all derivatives of the curvature tensor and showed that the metrics $g(t)$, after rescaling, converge in C_{loc}^∞ -topology to the standard metric on sphere. Later in [30], W.-X. Shi showed that, for general Ricci flows, all derivatives of curvature are bounded a priori by the bound of the curvature itself. Precisely, if a Ricci flow $g(t)$ satisfies $|Rm| \leq K$ for all $t \in [0, \frac{1}{K}]$ on a closed manifold M^n , then $|\nabla^l Rm| \leq C_{n,l} K t^{-l/2}$ for all $t \in (0, \frac{1}{K}]$, where $C_{n,l}$ denotes a constant depending only on n and l . This estimate, which is called Shi's estimate, even holds locally for complete non-compact Ricci flows. That is, there exists a constant θ depending only on the dimension n such that if a Ricci flow $g(t)$ satisfies $|Rm| \leq K$ on $B_{2r} \times [0, \frac{\theta}{K}]$, then $|\nabla^l Rm| \leq C_{n,l} K (K + r^{-2} + t^{-1})^{l/2}$ on $B_r \times (0, \frac{\theta}{K}]$. Thus, along the Ricci flow, C^2 -boundedness implies C^∞ -boundedness of metrics.

Some other works revealed that merely the Ricci curvature can control the curvature operator in certain circumstances. For instance, by blow-up arguments, N. Šešum [32] and L. Ma and L. Cheng [24] showed that along the Ricci flow $|Rm|$ maintains finite value as long as $|\text{Ric}|$ does. For compact manifolds, B. Wang improved the result of Šešum by showing that $|Rm|$ is bounded whenever Ric has a lower bound and the scalar curvature R has certain space-time integral bound [33]. He also showed that R must blow up whenever $|Rm|$ blows up at T in the order $o((T-t)^{-2})$ [34, Theorem 1.3]. See also [12, 23, 38] for related results. The estimates of $|Rm|$ in their results depend on the generic behavior of the metrics $g(t)$. On the other hand, a classical result due to M. Anderson [1] says that $|Rm|$ of a Riemannian manifold can be controlled by the bound of $|\text{Ric}|$, $|\nabla \text{Ric}|$ and the lower bound of injectivity radius. Therefore, it is natural to ask whether $|\nabla \text{Ric}|$, or $|Rm|$, can be controlled by $|\text{Ric}|$ along the Ricci flow. This is the main theme of this article.

First, we confirm that a Shi-type estimate for Ricci tensor holds provided that the injectivity radius $\text{inj} : M \times [0, T] \rightarrow \mathbb{R}_+$ is bounded from below.

Theorem 1.1 (Standard version). *For any $\delta, \eta > 0$ and $n \in \mathbb{N}$, there exist positive constants α , C and ρ such that for any $K > 0$ and any smooth Ricci flow $(M^n, g(t))_{t \in [0, T]}$ with $T \geq \frac{\eta}{K} > 0$, if*

$$|\text{Ric}| \leq K \quad \text{and} \quad \text{inj} \geq \delta K^{-\frac{1}{2}} \quad \text{on } B_{4\sqrt{T}}(x_0, t) \text{ for all } t \in [0, T],$$

then

$$|\nabla \text{Ric}| \leq \alpha \left(K T t^{-1} \right)^{\frac{3}{2}} \quad \text{on } B_{2\sqrt{T}}(x_0, t) \text{ for all } t \in (0, T]$$

and

$$|Rm| \leq C K T t^{-1} \quad \text{on } B_{\rho\sqrt{K^{-1}T^{-1}t}}(x_0, t) \text{ for all } t \in (0, T].$$

Recently, B. Kotschwar, O. Munteanu and J. Wang [21] improved the aforementioned results of Šešum and Wang by a different approach based on Moser's iteration. They can clarify the dependency of the bound, which eventually involves only

$|\text{Ric}|$ and the initial bound of curvature operator. Moser's iteration has been used before for similar purpose in [36], and later in [10] where X. Dai, G. Wei and R. Ye showed that $|Rm|$ can be controlled by initial $|\text{Ric}|$ and the initial conjugate radius up to a short time. However, all of these bounds do not link to the bound of $|\text{Ric}|$ in a clear manner as the bound given by our theorem. For instance, when $|\text{Ric}|$ is arbitrarily small, our theorem ensures that so is $|Rm|$.

Furthermore, our proof of Theorem 1.1 can be modified so that the scale of injectivity radius can unhook with the bound of Ricci curvature. Thus, we do not need a huge injective region to get the estimate of $|Rm|$ when K is small. In particular, our theorem can be applied to flows with arbitrarily small initial injectivity radius and the resulting bound depends mainly on the growth of inj with respect to time (cf. the parameter m in the next theorem).

Theorem 1.2 (Strong version). *For any $\delta, \eta > 0$ and $m, n \in \mathbb{N}$, there exist positive constants α, C, ρ such that for any $K > 0$ and any smooth Ricci flow $(M^n, g(t))_{t \in [0, T]}$ with $T \geq \frac{\eta}{K} > 0$, if*

$$|\text{Ric}| \leq K \quad \text{and} \quad \text{inj} \geq \delta \cdot \min \left\{ K^{-\frac{1}{2}}, h^{\frac{1}{2}}(t) \right\} \text{ on } B_{4\sqrt{T}}(x_0, t) \text{ for all } t \in [0, T],$$

where $h(t) \leq t$ is any positive function defined on $(0, T)$ such that for all $t^* \in (0, T)$, $h(t) \geq m^{-1}h(t^*)$ on $t \in [\frac{1}{2}t^*, t^*]$, then

$$|\nabla \text{Ric}| \leq \alpha \left(K T h^{-1} \right)^{\frac{3}{2}} \text{ on } B_{2\sqrt{T}}(x_0, t) \text{ for all } t \in (0, T]$$

and

$$|Rm| \leq CKTh^{-1} \text{ on } B_{\rho\sqrt{K^{-1}T^{-1}h(t)}}(x_0, t) \text{ for all } t \in (0, T].$$

Remark. The reader may take $h(t) = t$ or $\frac{T}{\pi} \sin \frac{\pi t}{T}$ to obtain some intuitions. The proof of this version can be found in Section 3. We note that the assumptions do not directly involve any information of inj at the initial time since $\lim_{t \rightarrow 0^+} h(t) = 0$. This does not mean that our theorem can be applied to a Ricci flow with singular initial data. The initial metric is required to be at least C^3 .

The growth or boundedness of curvature operator are important issues in the study of gradient Ricci solitons. Several a priori curvature estimates have been derived before (cf. [2, 7, 9, 11, 25–27] among others). Using our Theorem 1.1, we derive a new boundedness result for all types of gradient Ricci solitons.

Theorem 1.3. *For any class of complete non-compact n -dimensional gradient Ricci solitons of either shrinking or steady or expanding type, if the Ricci curvature is bounded and the injectivity radius is bounded away from zero, then the curvature operator is bounded by a uniform constant.*

We further derive a compactness theorem which shows that gradient Ricci solitons have compactness property analogue to Einstein manifolds. Note that the limiting soliton might be a trivial soliton.

Corollary 1.4. *Let $\lambda \in \{\pm\frac{1}{2}, 0\}$ and $A \in \mathbb{R}$. For any sequence of gradient Ricci solitons $(M_k, g_k, f_k, p_k)_{k \in \mathbb{N}}$ satisfying $\text{Ric}_{g_k} + \text{Hess}(f_k) = \lambda g_k$, if*

$$|\text{Ric}|_{g_k} \leq K, \quad \text{inj}_{g_k} \geq I > 0 \quad \text{and} \quad |\nabla f|_{g_k}(p_k) \leq A,$$

then there exists a subsequence converging smoothly to $(M_\infty, g_\infty, f_\infty, p_\infty)$, which satisfies $\text{Ric}_{g_\infty} + \text{Hess}(f_\infty) = \lambda g_\infty$ with $f_\infty = \lim_{k \rightarrow \infty} f_k$.

Besides the applications to Ricci solitons, we derive a curvature taming result which can be applied to general Ricci flows whose initial curvature might not have a uniform bound. We say that the curvature operator is *k-tamed* by a constant C along a complete non-compact Ricci flow if $|Rm| \leq Ct^{-k}$ for all small $t \geq 0$. In [20], S. Huang and L.-F. Tam showed that if a Ricci flow $g(t)$ starting from a non-compact Kähler manifold is 1-tamed by some constant C , then $g(t)$ remains Kähler for $t > 0$. Moreover, if C is small enough, then the nonnegativity of holomorphic bisectional curvature can also be preserved. Therefore, it is rather important to find criterions for the taming phenomenon. Note that such estimate is twofold: we would like to have a uniform bound C on a uniform time interval. For lower dimensional closed manifolds (dimension $n = 2$ or 3), M. Simon [31, Theorem 2.1] proved that every (M^n, g) satisfying $\text{diam} < D$, $\text{Vol} > V > 0$ and $\text{Ric} \geq -Kg$ with sufficiently small K can generate a solution of the Ricci flow which exists up to a maximal time $T = T(D, V)$. Moreover, $|Rm|$ is 1-tamed by a constant depending only on D and V . In [10], Dai, Wei and Ye showed that every closed (M^n, g) satisfying $|\text{Ric}| \leq 1$ and conjugate radius $\geq r_0$ can generate a solution of the Ricci flow which exists up to a maximal time $T = T(n, r_0)$ and Rm is $\frac{1}{2}$ -tamed by $C = C(n, r_0)$. When $|\text{Ric}| \leq K$, their theorem holds with $C = C(n, r_0\sqrt{K})$ and $T = T(n, r_0\sqrt{K})$. For complete non-compact (M^n, g) with $n \geq 3$, G. Xu [35, Corollary 1.2] showed that, if $\text{Ric} \geq -Kg$ and the averaged L^p -norm ($p > \frac{n}{2}$) of Rm has a uniform bound K_1 for all geodesic balls $B_{r_0}(x)$ with some radius $r_0 > 0$, then the Ricci flow must exist and Rm is $\frac{n}{2p}$ -tamed by a constant $C = C(K, K_1, r_0, n, p)$ up to $t = T(K, K_1, r_0, n, p)$.

Thanks to the explicit bound in Theorem 1.2, we can derive a taming theorem.

Theorem 1.5. *There exists a universal constant $C = C(n)$ such that for any smooth Ricci flow $(M^n, g(t))$ and any point $x_0 \in M$,*

$$|Rm|(x, t) \leq Ct^{-1} \quad \text{on } B_{4r}(x_0, t) \text{ for all } t \in (0, K^{-1}],$$

and

$$|Rm|(x, t) \leq CK \quad \text{on } B_{4r}(x_0, t) \text{ for all } t \in [K^{-1}, r^2],$$

where $r^2 := \inf\{t > 0 \mid \inf_{B_{8r}(x_0, t)} \text{inj} < \sqrt{t}\}$ and K denotes the maximum of r^{-2} and $\sup |\text{Ric}|$ on $\bigcup_{[0, r^2]} B_{8r}(x_0, t)$.

Before Section 5, where more applications of our main theorems are demonstrated, we discuss the approach towards our aim via Moser's iteration in Section 4. In particular, we derive the following theorem by using Kotschwar-Munteanu-Wang's L^p -estimate [21, Proposition 1]. To abbreviate the notation, we denote the parabolic region emanated from $B_r(x_0, 0)$ up to $t = T$ by $\mathcal{P}(r; x_0, T)$, namely, $\mathcal{P}(r; x_0, T) := \Omega \times (0, T]$, where $\Omega \subset M$ is the topological region defined by $B_r(x_0, 0)$. Furthermore, $\overline{\mathcal{P}(r; x_0, T)}$ is defined to be $\Omega \times [0, T]$.

Theorem 1.6. *Let $(M^n, g(t))_{t \in [0, T]}$ be a smooth solution of the Ricci flow. If*

$$|\text{Ric}| \leq K \text{ in } \overline{\mathcal{P}(4r; x_0, T)} \text{ and } \inf_{B_{4r}(x_0, 0)} \text{inj} \geq I > 0$$

for some $K, I, r > 0$, then there exists C depending on K, I, r, T and the dimension n such that $|\text{Rm}|(x_0, t) \leq C$ in $\mathcal{P}(r; x_0, T) \setminus \overline{\mathcal{P}(r; x_0, \frac{1}{2}T)}$.

Injectivity radius is a classical quantity used in convergence theories of Riemannian manifolds. A uniform lower bound of it prevents the sequence of manifolds from developing local collapsing. Although there is no analytical method to compute the injectivity radius directly, one can derive a lower bound from local volume bound provided that the curvature operator is bounded. This was proved for sequences of manifolds and, furthermore, for sequences of solutions of the Ricci flow (See Section 5.1 for more details). Combining with a celebrated theorem of Perelman which states that the local volume can be controlled along the Ricci flow with locally bounded curvature, one obtains the legitimacy of taking blow-up limits. However, in this article we only assume a Ricci curvature bound, which is too weak to derive a lower bound for injectivity radius from local volume bounds. It is still interesting to ask whether the injectivity radius condition can be replaced by volume condition plus certain integral curvature bound. Even more, can we prove our theorems when lacking information of injectivity radius? We derive some answers in the second part of this paper, Sections 6 and 7.

Suppose that Ricci curvature is bounded by K and its derivative $|\nabla \text{Ric}|$ is controlled by the derivative of scalar curvature $|\nabla R|$, we prove that both $|\nabla \text{Ric}|$ and $|\nabla R|$ are bounded for all $t \in (0, \frac{1}{K}]$. Precisely, we derive

Theorem 1.7 (Global estimate). *There exists a constant $C > 0$, depending only on α, β and n such that for every n -dimensional closed solution $(M^n, g(t))_{t \in [0, T]}$ of the Ricci flow, if the Ricci curvature and its derivative satisfy that $|\text{Ric}| \leq K$ and $|\nabla \text{Ric}| \leq \alpha K t^{-\frac{1}{2}} + \beta |\nabla R|$ for all $t \in [0, \frac{1}{K}] \subset [0, T)$, where K is a positive constant, then*

$$|\nabla \text{Ric}|^2 \leq C K^2 t^{-1}$$

for all $t \in (0, \frac{1}{K}]$.

Theorem 1.8 (Local estimate). *There exist positive constants θ_0 and C depending only on α, β, n and Λ such that for every solution $(M^n, g(t))_{t \in [0, \theta_0/K]}$ of the Ricci flow, if $|Rm| \leq \Lambda$ on $B_r(x_0, 0)$, $|\text{Ric}| \leq K$ and $|\nabla \text{Ric}| \leq \alpha K \left(\frac{1}{r^2} + \frac{1}{t} + K \right)^{\frac{1}{2}} + \beta |\nabla R|$ on $\overline{\mathcal{P}(r; x_0, t_0)}$ for some $r \leq \sqrt{\theta_0/K}$ and $t_0 \leq \theta_0/K$, then*

$$|\nabla \text{Ric}|^2 \leq CK^2 \left(\frac{1}{r^2} + \frac{1}{t} + K \right)$$

on $\mathcal{P}(\frac{r}{\sqrt{2}}; x_0, t_0)$.

We doubt that $|\nabla \text{Ric}|$ can be controlled by $|\nabla R|$ for generic solutions of the Ricci flow. However, we believe that it is true for a large variety of solutions including Ricci solitons. A related result appeared earlier in a collaborated work of A. Deruelle and the author [4, Theorem 2.10]. The reader could find more discussions in the last section.

ACKNOWLEDGEMENTS. The main part of this article was done when I visited Ovidiu Munteanu in University of Connecticut in September 2015. I appreciate the hospitality of the university and precious discussions with Ovidiu. Some part of the work was done when I was a doctoral student at l’Institut Fourier. I would like to thank my advisor Gérard Besson for his encouragement and all kinds of helps.

2. Global estimate of Rm

Given an n -dimensional Riemannian manifold (M, g) and a point $p \in M$, we can find a local chart (\mathcal{U}, φ) , $\varphi : \mathcal{U} \rightarrow \mathbb{R}^n$, such that $p \in \mathcal{U} \subset M$ and $\varphi = (\varphi_1, \dots, \varphi_n)$ consists of harmonic functions, *i.e.*, $\Delta_g \varphi_k = 0$ for all $k = 1, \dots, n$. Under these coordinates, the Laplacian of a function f which is defined by $\Delta_g f = \frac{1}{\sqrt{\det g}} \partial_i (\sqrt{\det g} \cdot g^{ij} \cdot \partial_j f)$ can be reduced to

$$\Delta_g f = g^{ij} \partial_i \partial_j f.$$

Moreover, if on a geodesic ball $B_r(p) \subset \mathcal{U}$ one has $|\text{Ric}| \leq K$ and $\text{inj} \geq I$, then M. Anderson [1, Lemma 2.2] showed that for any $\sigma \in (0, 1)$, there exist $\epsilon = \epsilon(K, n, \sigma)$ and $C_0 = C_0(\epsilon, I)$ such that harmonic coordinates φ_k ’s exist on $B_{\epsilon I}$ with

$$g_{ij}(p) = \delta_{ij} \quad \text{and} \quad |g_{ij}|'_{C^{1,\sigma}} \leq C_0 \text{ on } B_{\epsilon I},$$

where

$$\begin{aligned} |g_{ij}|'_{C^{1,\sigma}} &:= \sup_{B_r} |g_{ij}| + \sup_{B_r; k=1, \dots, n} r |\partial_k g_{ij}| \\ &+ \sup_{x \neq y; k=1, \dots, n} \left(r^{1+\sigma} \frac{|\partial_k g_{ij}(x) - \partial_k g_{ij}(y)|}{|x-y|^\sigma} \right) \end{aligned}$$

and $r := \epsilon I$. (The notation $|\cdot|'$ is adopted from [14, Page 53].) On the other hand, one can compute the Laplacian of g_{ij} under harmonic coordinates and derive

$$\Delta_g g_{ij} = -2R_{ij} + P(g_{ij}, \partial g_{ij}),$$

where P is a certain quasi-polynomial of g_{ij} and ∂g_{ij} (cf. [29, Chapter 10]). Hence the standard elliptic regularity theory (cf. [14, Theorem 4.6]) tells that

$$|g_{ij}|'_{C^{2,\sigma}} \leq C \left(|R_{ij}|'_{C^{0,\sigma}} + |g_{ij}|'_{C^{1,\sigma}} \right). \quad (2.1)$$

Note that when the Ricci curvature and its derivative are bounded in the sense that $|\text{Ric}|^2 = g^{ik}g^{jl}R_{ij}R_{kl} \leq K^2$ and $|\nabla \text{Ric}|^2 = g^{pq}g^{ik}g^{jl}\nabla_p R_{ij}\nabla_q R_{kl} \leq L$, then the norm of coefficients R_{ij} and its derivatives shall satisfy $|R_{ij}|'_{C^{0,\sigma}} \leq C = C(K, \epsilon I, L)$. Therefore, one can use harmonic coordinates and (1) to derive a bound for $|g|'_{C^{2,\sigma}}$. In particular, the coefficients of curvature tensor are bounded. Since the tensor norm does not depend on coordinate choosing, the curvature $R_{ij}^k{}_l$ is bound in the tensor sense. It is also equivalent to say that curvature operator Rm is bounded. Such strategy will be used several times in this article. One should be cautious that, for the elliptic regularity on Riemannian manifolds, the constant C depends not only on n, σ , but also on the upper bound of $|g^{ij}|$. (One can see this when adapting proofs of theorems in [14, Chapter 2, 3 and 4] into the Riemannian case.) Hence $C = C(n, \sigma, \epsilon, I)$.

For the reader's convenience, we prove the following compact version of Theorem 1.1 first. The proof of the standard version of Theorem 1.1 is more subtle and will be demonstrated in the next section.

Theorem 2.1 (Compact version). *For any $\delta, \eta > 0$ and $n \in \mathbb{N}$, there exist positive constants α and C such that for any $K > 0$ and any closed smooth Ricci flow $(M^n, g(t))_{t \in [0, T]}$ with $T \geq \frac{\eta}{K} > 0$, if*

$$|\text{Ric}| \leq K \quad \text{and} \quad \text{inj} \geq \delta K^{-\frac{1}{2}} \quad \text{for all } t \in (0, T],$$

then

$$|\nabla \text{Ric}| \leq \alpha \left(K T t^{-1} \right)^{\frac{3}{2}} \quad \text{and} \quad |Rm| \leq C K T t^{-1} \quad \text{for all } t \in (0, T].$$

Lemma 2.2. *For any $\delta, \eta > 0$ and $n \in \mathbb{N}$, there exists $\alpha > 0$ such that for any smooth Ricci flow $g(t)_{t \in [0, T]}$ on a closed manifold M^n , if $|\text{Ric}| \leq K$, $\text{inj} \geq \frac{\delta}{\sqrt{K}}$ and $T \geq \frac{\eta}{K}$, then*

$$|\nabla \text{Ric}| \leq \alpha \left(K T t^{-1} \right)^{\frac{3}{2}}$$

for all $t \in (0, T]$.

Proof. Suppose no such α exists, then we can find a sequence of Ricci flows $g_k(t)_{t \in [0, T_k]}$, points $p_k = (x_k, t_k)$, and $\alpha_k \nearrow \infty$ such that $t_k > 0$ and $|\nabla \text{Ric}|_{g_k}(p_k) > \alpha_k (K_k T_k t_k^{-1})^{\frac{3}{2}}$. By the point-picking lemma afterwards, we can find $\bar{p}_k = (\bar{x}_k, \bar{t}_k)$ associated to p_k such that:

- $|\nabla \text{Ric}|_{g_k}(\bar{p}_k) > \alpha_k (K_k T_k \bar{t}_k^{-1})^{\frac{3}{2}}$;
- $|\nabla \text{Ric}|_{g_k} \leq 8 \bar{Q}_k := 8 |\nabla \text{Ric}|_{g_k}(\bar{p}_k)$ on $M \times [\bar{t}_k - \beta_k \bar{Q}_k^{-\frac{2}{3}}, \bar{t}_k]$, where $\beta_k := \frac{1}{2} \alpha_k^{\frac{2}{3}} \eta$.

Consider the rescaling Ricci flows $\tilde{g}_k := \bar{Q}_k^{\frac{2}{3}} g_k$ with $\tilde{t} := \bar{Q}_k^{\frac{2}{3}} (t - \bar{t}_k) \in [-\beta_k, 0]$.

Then $|\text{Ric}_{\tilde{g}_k}|_{\tilde{g}_k} \leq K_k \bar{Q}_k^{-\frac{2}{3}} \leq \alpha_k^{-\frac{2}{3}} \frac{t_k}{T_k} \searrow 0$ and $|\nabla \text{Ric}_{\tilde{g}_k}|_{\tilde{g}_k} \leq 8$ on $M \times [-\beta_k, 0]$.

In particular, Ric has a uniform $C^{0,\sigma}$ -bound.

Using Anderson's lemma mentioned before,

$$\text{inj}_{\tilde{g}_k} \geq \frac{\delta}{\sqrt{K_k}} \bar{Q}_k^{\frac{1}{3}} = \frac{\delta}{\sqrt{K_k}} \alpha_k^{\frac{1}{2}} (K_k T_k \bar{t}_k^{-1})^{\frac{1}{2}} \nearrow \infty$$

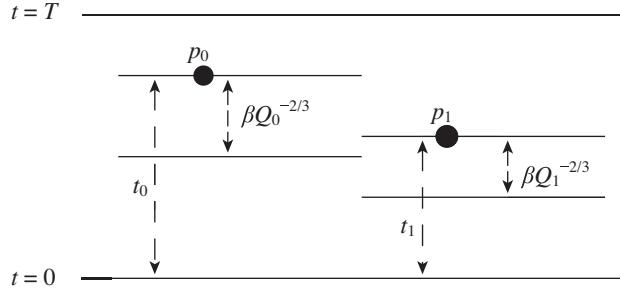
and the boundedness of $|\text{Ric}_{\tilde{g}_k}|_{\tilde{g}_k}$ ensures the existence of harmonic coordinates on a domain of uniform size. Moreover, \tilde{g}_k 's may have a uniform $C^{1,\sigma}$ -bound in this domain. By elliptic regularity, \tilde{g}_k 's, which satisfy $\Delta \tilde{g}_k = -2 \text{Ric}_{\tilde{g}_k} + P(\tilde{g}_k, \partial \tilde{g}_k)$, have a uniform $C^{2,\sigma}$ -bound. Namely, $|Rm_{\tilde{g}_k}|_{\tilde{g}_k}$'s are uniformly bounded on $M \times (-\beta_k, 0]$. Applying Shi's estimate, all higher derivatives of $Rm_{\tilde{g}_k}$'s are uniformly bounded on $M \times [-\frac{1}{2} \beta_k, 0]$. So the marked metrics (\tilde{g}_k, \bar{p}_k) converge smoothly to a Ricci flat metric (g_∞, p_∞) . This contradicts $|\nabla \text{Ric}|_{g_\infty}(p_\infty) = 1$. Therefore, we have $|\nabla \text{Ric}| \leq \alpha (K T t^{-1})^{\frac{3}{2}}$. \square

Lemma 2.3 (Point-picking lemma). *For any $\alpha > 0$ and any closed smooth Ricci flow $(M, g(t))_{t \in [0, T]}$ with $|\text{Ric}| \leq K$ and $T \geq \frac{\eta}{K}$, if $|\nabla \text{Ric}|(p_0) > \alpha (K T t_0^{-1})^{\frac{3}{2}}$ at some point $p_0 = (x_0, t_0)$ with $t_0 > 0$, then there exists $\bar{p} = (\bar{x}, \bar{t})$, $\bar{t} > 0$, such that*

$$|\nabla \text{Ric}|(\bar{p}) > \alpha (K T \bar{t}^{-1})^{\frac{3}{2}} \quad \text{and} \quad |\nabla \text{Ric}| \leq 8 \bar{Q} := 8 |\nabla \text{Ric}|(\bar{p})$$

on $M \times [\bar{t} - \beta \bar{Q}^{-\frac{2}{3}}, \bar{t}]$, where $\beta := \frac{1}{2} \alpha^{\frac{2}{3}} \eta$.

Proof. Here we use Perelman's method for proving his pseudo-locality theorem (cf. [28, Theorem 10.1]). Start from the point p_0 with $Q_0 := |\nabla \text{Ric}|(p_0) > \alpha(KT t_0^{-1})^{\frac{3}{2}}$. If $|\nabla \text{Ric}| \leq 8Q_0$ on $M \times [t_0 - \beta Q_0^{-\frac{2}{3}}, t_0]$, then we are done. Suppose this is not the case, then there exists a point $p_1 = (x_1, t_1)$ with $t_1 \in [t_0 - \beta Q_0^{-\frac{2}{3}}, t_0]$ and $Q_1 := |\nabla \text{Ric}|(p_1) > 8Q_0$. Note that $\beta = \frac{1}{2}\alpha^{\frac{2}{3}}\eta$ implies that $\beta Q_0^{-\frac{2}{3}} \leq \frac{1}{2}t_0$.



Thus, $t_1 \geq t_0 - \beta Q_0^{-\frac{2}{3}} \geq \frac{1}{2}t_0$. In particular,

$$Q_1 > 8Q_0 > 8\alpha(KT t_0^{-1})^{\frac{3}{2}} \geq \alpha(KT t_1^{-1})^{\frac{3}{2}}$$

and thus

$$\beta Q_1^{-\frac{2}{3}} \leq \frac{1}{2}t_1.$$

If $|\nabla \text{Ric}| \leq 8Q_1$ on $M \times [t_1 - \beta Q_1^{-\frac{2}{3}}, t_1]$, then we are done. Suppose not, then we can further find p_2 so that $Q_2 > 8Q_1 > \alpha(KT t_1^{-1})^{\frac{3}{2}}$ by similar process. Similarly, $\beta Q_2^{-\frac{2}{3}} \leq \frac{1}{2}t_2$ and so on. So t_k always stays in $(0, T]$. Therefore, such process could be continued until we find a p_k so that $|\nabla \text{Ric}| \leq 8Q_k$ in $M \times [t_k - \beta Q_k^{-\frac{2}{3}}, t_k]$. Such p_k must exist because $|\nabla \text{Ric}|(p_k) > 8^k Q_0$ must be bounded in $M \times [0, T]$. \square

Now we are able to finish the proof of the compact version of Theorem 1.1.

Proof. For a Ricci flow $(M^n, g(t))$ with $|\text{Ric}| \leq K$ and $\text{inj} \geq \delta K^{-\frac{1}{2}} > 0$ for all $t \in [0, T]$, by Lemma 2.2, we have $|\nabla \text{Ric}| \leq \alpha(KT t^{-1})^{\frac{3}{2}}$ for all $t \in (0, T]$. For each fixed $t \in (0, T]$, we consider $\tilde{g} := (KT t^{-1})g(t)$ and obtain

$$\text{inj}_{\tilde{g}} \geq \delta(T t^{-1})^{\frac{1}{2}} \geq \delta, \quad |\text{Ric}_{\tilde{g}}|_{\tilde{g}} \leq T^{-1}t \leq 1 \quad \text{and} \quad |\nabla \text{Ric}_{\tilde{g}}|_{\tilde{g}} \leq \alpha.$$

So by the elliptic regularity (1), the metric tensor \tilde{g} has a uniform $C^{2,\sigma}$ -bound which depends on n, σ, δ and α . By choosing an arbitrary $\sigma \in (0, 1)$, $|Rm_{\tilde{g}}|_{\tilde{g}}$ is bounded by a constant depending only on n, δ and α . After rescaling back, we see that the curvature of $g(t)$ satisfies $|Rm| \leq CKTt^{-1}$ with $C = C(n, \delta, \alpha)$. Since t is arbitrary in $(0, T]$ and $\alpha = \alpha(\delta, \eta, n)$, the theorem is proved. \square

3. Local estimate of Rm

The estimate in the previous section also holds locally. Namely, the curvature operator can be bounded if $|\text{Ric}|$ and inj are bounded in a parabolic neighborhood of uniform size. To prove this, we need the following local point-picking lemma which shows that for any point with large $|\nabla \text{Ric}|$, one can find another point nearby equipped with a controlled parabolic neighborhood.

Lemma 3.1 (point-picking lemma, local version). *For any $\eta, \alpha > 0$ and any Ricci flow $(B_{4\sqrt{T}}(x_0, t), g(t))_{t \in [0, T]}$ with $|\text{Ric}| \leq K$ and $T \geq \frac{\eta}{K}$, which is smooth up to boundary, if $|\nabla \text{Ric}|(p) > \alpha (KTt^{-1})^{\frac{3}{2}}$ at some point $p = (x, t)$ in $(B_{2\sqrt{T}}(x_0, t), g(t))_{t \in (0, T]}$, then there exist $\epsilon = \epsilon(\eta) > 0$ and $\bar{p} = (\bar{x}, \bar{t})$ with $d_{\bar{t}}(\bar{x}, x_0) < 4\sqrt{T}$ and $\bar{t} > 0$, such that*

$$|\nabla \text{Ric}|(\bar{p}) > \alpha \left(KT\bar{t}^{-1} \right)^{\frac{3}{2}} \quad \text{and} \quad |\nabla \text{Ric}| \leq 8\bar{Q} := 8|\nabla \text{Ric}|(\bar{p})$$

in $B_{\beta^{\frac{1}{2}}\bar{Q}^{-\frac{1}{3}}}(\bar{x}, t), t \in [\bar{t} - \beta\bar{Q}^{-\frac{2}{3}}, \bar{t}]$, where $\beta := \frac{1}{2}\epsilon^2\alpha^{\frac{2}{3}}\eta$. In particular, $B_{\beta^{\frac{1}{2}}\bar{Q}^{-\frac{1}{3}}}(\bar{x}, t) \subset B_{4\sqrt{T}}(x_0, t)$ for each $t \in [\bar{t} - \beta\bar{Q}^{-\frac{2}{3}}, \bar{t}]$.

Proof. To abbreviate the notation, we define the backward parabolic metric ball based at (x_*, t_*) by

$$\begin{aligned} \mathcal{B}(r; x_*, t_*) &:= \bigcup_{t \in (t_* - r^2, t_*]} B_r(x_*, t) \\ &= \left\{ (x, t) \mid \text{dist}_{g(t)}(x, x_*) < r, t \in (t_* - r^2, t_*] \right\}. \end{aligned}$$

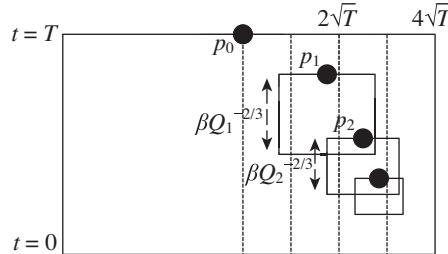
We use the same induction argument as in the proof of the global point-picking lemma. In the proof of the global version, we have seen that to proceed the argument, we need to justify that p_k 's can stay in a finite time-region. Here the situation is more subtle: we need to make sure that there exists an $\epsilon > 0$ such that $\mathcal{B}(\beta^{\frac{1}{2}}Q_k^{-\frac{1}{3}}; x_k, t_k)$ is contained in $\bigcup_{t \in (0, T]} B_{4\sqrt{T}}(x_0, t)$, where $\beta := \frac{1}{2}\epsilon^2\alpha^{\frac{2}{3}}\eta$.

Now we start from $p = (x, t)$ and look at the parabolic region $\mathcal{B}(\beta^{\frac{1}{2}}Q^{-\frac{1}{3}}; x, t)$. If $\mathcal{B}(\beta^{\frac{1}{2}}Q^{-\frac{1}{3}}; x, t) \subset \bigcup_{t \in (0, T]} B_{4\sqrt{T}}(x_0, t)$ and $|\nabla \text{Ric}| \leq 8Q := 8|\nabla \text{Ric}|(p)$ in this region, then we are done. If not, then there is a $p_1 \in \mathcal{B}(\beta^{\frac{1}{2}}Q^{-\frac{1}{3}}; x, t)$ such that

$Q_1 := |\nabla \text{Ric}|(p_1) > 8Q$. Similar to the proof of the compact version, we wish to go on finding successive p_k 's until we acquire \bar{p} . So we should check

- t_k 's will not reach 0: $\beta \cdot Q_k^{-\frac{2}{3}} \leq \frac{1}{2}\epsilon^2\alpha^{\frac{3}{2}}\eta \cdot \alpha^{-\frac{2}{3}}K_k^{-1}T_k^{-1}t_k \leq \frac{1}{2}\epsilon^2t_k$;
- x_k 's stay in a distance less than $3\sqrt{T}$ from the center x_0 at each time t_k :

$$\begin{aligned}
d_{t_k}(x_k, x_0) &\leq d_{t_{k-1}}(x_{k-1}, x_0) + \sqrt{\beta Q_{k-1}^{-\frac{2}{3}}} \\
&\leq d_{t_{k-2}}(x_{k-2}, x_0) + \sqrt{\beta Q_{k-2}^{-\frac{2}{3}}} + \sqrt{\beta Q_{k-1}^{-\frac{2}{3}}} \\
&\leq d_{t_1}(x_1, x_0) + \sqrt{\beta Q_1^{-\frac{2}{3}}} + \cdots + \sqrt{\beta Q_{k-1}^{-\frac{2}{3}}} \\
&\leq 2\sqrt{T} + \sqrt{\beta Q^{-\frac{2}{3}}} + \sqrt{\beta Q_1^{-\frac{2}{3}}} + \cdots + \sqrt{\beta Q_{k-1}^{-\frac{2}{3}}} \\
&< 2\sqrt{T} + \sqrt{\beta Q^{-\frac{2}{3}}} + \sqrt{\frac{1}{4}\beta Q^{-\frac{2}{3}}} + \cdots + \sqrt{\frac{1}{4^{k-1}}\beta Q^{-\frac{2}{3}}} \\
&< 2\sqrt{T} + 2\sqrt{\beta Q^{-\frac{2}{3}}} \\
&< 2\sqrt{T} + 2\epsilon\sqrt{\frac{1}{2}t} \\
&< 3\sqrt{T}, \text{ if } \epsilon \text{ is small enough, for instance, less than } \frac{1}{\sqrt{2}};
\end{aligned}$$



- $\mathcal{B}(\beta^{\frac{1}{2}}Q_k^{-\frac{1}{3}}; x_k, t_k) \subset \bigcup_{t \in (0, T]} B_{4\sqrt{T}}(x_0, t)$:
For any $q = (\xi, \tau) \in \mathcal{B}(\beta^{\frac{1}{2}}Q_k^{-\frac{1}{3}}; x_k, t_k)$, since

$$K|t_k - \tau| \leq K\beta \cdot Q_k^{-\frac{2}{3}} \leq \frac{1}{2}\epsilon^2\eta T^{-1}t_k \leq \frac{1}{2}\epsilon^2\eta,$$

we have

$$\begin{aligned}
d_\tau(\xi, x_0) &\leq d_\tau(\xi, x_k) + d_\tau(x_k, x_0) \\
&\leq \beta^{\frac{1}{2}} Q_k^{-\frac{1}{3}} + d_{t_k}(x_k, x_0) \cdot e^{K|t_k - \tau|} \\
&\leq \epsilon \sqrt{\frac{1}{2} t_k} + 3\sqrt{T} \cdot e^{\frac{1}{2}\epsilon^2 \eta} \\
&\leq \sqrt{T} \left(\sqrt{\frac{1}{2}} \epsilon + 3 \cdot e^{\frac{1}{2}\epsilon^2 \eta} \right) \\
&\leq 4\sqrt{T}, \text{ if } \epsilon = \epsilon(\eta) \text{ is small enough.}
\end{aligned}$$

Therefore, this local point-picking lemma follows by the same argument of induction as in the proof of Lemma 2. \square

Now we demonstrate the proof of Theorem 1.1 and Theorem 1.2.

Proof of Theorem 1.1. The idea of proof is the same to the compact version, so we will be a bit sketchy on the whole process but focus on the crucial steps. Suppose there exist $(B_{4\sqrt{T}}(x_0, t), g_k(t))_{t \in [0, T]}$, with points $x_k \in B_{2\sqrt{T}}(x_0, t_k)$ and $\alpha_k \rightarrow \infty$ such that the first conclusion is not true, *i.e.*, $Q_k := |\nabla \text{Ric}|_{g_k}(p_k) > \alpha_k (K_k T_k t_k^{-1})^{\frac{3}{2}}$. By the local point-picking lemma, we can find \bar{p}_k 's and the associated parabolic regions $\mathcal{B}(\beta^{\frac{1}{2}} \bar{Q}_k^{\frac{1}{3}}; \bar{x}_k, \bar{t}_k)$'s to run the blow-up procedure, where $\beta := \frac{1}{2}\epsilon^2 \alpha^{\frac{2}{3}} \eta$. Indeed, we rescale the metric $g_k(t)$ on $\mathcal{B}(\beta^{\frac{1}{2}} \bar{Q}_k^{\frac{1}{3}}; \bar{x}_k, \bar{t}_k)$ by $\bar{Q}_k^{\frac{2}{3}} := (|\nabla \text{Ric}|_{g_k}(\bar{p}_k))^{\frac{2}{3}} > \alpha_k^{\frac{2}{3}} K_k T_k t_k^{-1}$ and obtain

$$|\text{Ric}_{\tilde{g}_k}|_{\tilde{g}_k} \leq K_k \bar{Q}_k^{-\frac{2}{3}} \leq \alpha_k^{-\frac{2}{3}} \frac{\bar{t}_k}{T_k} \searrow 0$$

and

$$\text{inj}_{\tilde{g}_k} \geq \delta \cdot \alpha_k^{\frac{1}{3}} \left(T_k t_k^{-1} \right)^{\frac{1}{2}} \geq \delta \alpha_k^{\frac{1}{3}} \nearrow \infty$$

on $\tilde{\mathcal{B}}(\beta^{\frac{1}{2}}; \bar{x}_k, \bar{t}_k)$, as $\alpha_k \nearrow \infty$.

As in the proof of the compact version, we encounter a contradiction on a subsequential limit. Therefore, there exists $\alpha > 0$ such that $|\nabla \text{Ric}| \leq \alpha (K T t^{-1})^{\frac{3}{2}}$ for all Ricci flows $(B_{2\sqrt{T}}(x_0, t), g(t))_{t \in [0, T]}$.

Fix an arbitrary t and rescale the metric by letting $\tilde{g} := K T t^{-1} g(t)$, as in the proof of the compact version, one obtains

$$\text{inj}_{\tilde{g}} \geq \delta \left(T t^{-1} \right)^{\frac{1}{2}} \geq \delta, \quad |\text{Ric}_{\tilde{g}}|_{\tilde{g}} \leq T^{-1} t \leq 1 \text{ and } |\nabla \text{Ric}_{\tilde{g}}|_{\tilde{g}} \leq \alpha$$

in $\tilde{B}_{2\sqrt{\eta}}(x_0, t)$. So by the elliptic regularity (1), $|Rm_{\tilde{g}}|_{\tilde{g}} \leq C$ in $\tilde{B}_\rho(x_0, t)$ where $C = C(n, \delta, \alpha)$ and $\rho = \rho(n, \delta, \eta)$. After rescaling back, we see that the curvature of $g(t)$ satisfies $|Rm| \leq CKTt^{-1}$ in $B_{\rho\sqrt{K^{-1}T^{-1}t}}(x_0, t)$ with $C = C(n, \delta, \alpha)$ and thus prove the theorem. \square

Proof of Theorem 1.2. The key of this proof is the following observation: in the proof of local point-picking lemma, one can see that the parabolic neighborhood associated to \bar{p} must be small if \bar{t} is close to 0. Precisely, the radius is $\beta^{\frac{1}{2}}\bar{Q}^{-\frac{1}{3}}$ and its square is less than $\frac{1}{2}\bar{t}$. Hence, when performing the blow-up argument along these picked points, we do not need a uniform lower bound of injectivity radius. Instead, the injectivity radius is allowed to decay at a rate proportional to $\bar{Q}^{-\frac{1}{3}} := \alpha_k^{-\frac{1}{3}}(K_k T_k h_k^{-1}(\bar{t}_k))^{-\frac{1}{2}}$, i.e., either $\text{inj} \geq K_k^{-\frac{1}{2}}$ or $\text{inj}(x, t) \geq h_k^{\frac{1}{2}}(t)$ is enough. It is not hard to check that, if the condition $|\nabla \text{Ric}|(p) \leq (\alpha K T t^{-1})^{\frac{3}{2}}$ in the local point-picking lemma is replaced by $|\nabla \text{Ric}|(p) \leq (\alpha K T h^{-1}(t))^{\frac{3}{2}}$, for some positive function $h(t) \leq t$ for all $t \in (0, T]$, then the lemma still holds with the conclusion replaced by $|\nabla \text{Ric}|(\bar{p}) \leq (\alpha K T h^{-1}(\bar{t}))^{\frac{3}{2}}$. Now we use this modified version to prove Theorem 1.2.

Again we argue by contradiction. Suppose there exist $(B_{4\sqrt{T}}(x_0, t), g_k(t))_{t \in [0, T]}$, with points $x_k \in B_{2\sqrt{T}}(x_0, t_k)$ and $\alpha_k \rightarrow \infty$ such that $Q_k := |\nabla \text{Ric}|_{g_k}(p_k) > \alpha_k(K_k T_k h_k^{-1})^{\frac{3}{2}}$. By the local point-picking lemma (with t being replaced by h in the bound of ∇Ric), we can find \bar{p}_k 's and the associated parabolic regions $\mathcal{B}(\beta^{\frac{1}{2}}\bar{Q}_k^{\frac{1}{3}}; \bar{x}_k, \bar{t}_k)$'s to run the blow-up procedure, where $\beta := \frac{1}{2}\epsilon^2\alpha^{\frac{2}{3}}\eta$. Indeed, we rescale the metric $g_k(t)$ on $\mathcal{B}(\beta^{\frac{1}{2}}\bar{Q}_k^{\frac{1}{3}}; \bar{x}_k, \bar{t}_k)$ by $\bar{Q}_k^{\frac{2}{3}} := (|\nabla \text{Ric}|_{g_k}(\bar{p}_k))^{\frac{2}{3}} > \alpha_k^{\frac{2}{3}}K_k T_k h_k^{-1}(\bar{t}_k)$ and obtain

$$|\text{Ric}_{\tilde{g}_k}|_{\tilde{g}_k} \leq K_k \bar{Q}_k^{-\frac{2}{3}} \leq \alpha_k^{-\frac{2}{3}} \frac{\bar{h}_k}{T_k} \leq \alpha_k^{-\frac{2}{3}} \frac{\bar{t}_k}{T_k} \searrow 0$$

and

$$\text{inj}_{\tilde{g}_k} \geq \delta \cdot \min \left\{ K_k^{-\frac{1}{2}}, h_k^{\frac{1}{2}}(t) \right\} \cdot \alpha_k^{\frac{1}{3}} \left(K_k T_k h_k^{-1}(\bar{t}_k) \right)^{\frac{1}{2}}.$$

To derive a uniform lower bound from the second inequality, we study the following two cases:

- At points where $\text{inj}_{g_k} \geq \delta K_k^{-\frac{1}{2}}$, we have

$$\text{inj}_{\tilde{g}_k} \geq \delta \cdot K_k^{-\frac{1}{2}} \cdot \alpha_k^{\frac{1}{3}} (K_k T_k h_k^{-1}(\bar{t}_k))^{\frac{1}{2}} \geq \delta \cdot \alpha_k^{\frac{1}{3}} (T_k h_k^{-1}(\bar{t}_k))^{\frac{1}{2}} \nearrow \infty;$$

- At points where $\text{inj}_{g_k(t)} \geq \delta h_k^{\frac{1}{2}}(t)$, we have

$$\text{inj}_{\tilde{g}_k} \geq \delta h_k^{\frac{1}{2}}(t) \cdot \alpha_k^{\frac{1}{3}} (K_k T_k h_k^{-1}(\bar{t}_k))^{\frac{1}{2}} \geq m^{-\frac{1}{2}} \delta \eta^{\frac{1}{2}} \alpha_k^{\frac{1}{3}} \nearrow \infty$$

by the assumption of $h_k(t)$.

In either case, the rescaled injectivity radius has a uniform lower bound on $\tilde{\mathcal{B}}(\beta^{\frac{1}{2}}; \bar{x}_k, \bar{t}_k)$. So a contradiction can be derived as before and one can conclude that $|\nabla \text{Ric}| \leq \alpha(KTh^{-1})^{\frac{3}{2}}$. At last, by using a rescaling argument as in the proof of Theorem 1.1, one achieves $|Rm| \leq CKTh^{-1}$ for some $C = C(n, \delta, \eta, m)$ in $B_{\rho\sqrt{K^{-1}T^{-1}h(t)}}(x_0, t)$ for every fixed t and thus the theorem is proved. \square

Remark 3.2. The prototype for the function h is $h(t) = t$. In general, if $h(t)$ is a concave function or a decreasing function, or a conjunction of them, then it satisfies the assumption that there exists $m > 0$ such that for all $t^* \in (0, T]$, $h(t) \geq m^{-1} \cdot h(t^*)$ for all $t \in [\frac{1}{2}t^*, t^*]$. For instance, $h(t)$ could be $\frac{T}{\pi} \sin \frac{\pi t}{T}$.

Remark 3.3. By examining the proof step by step, one sees that the injectivity radius assumption in our theorem can be replaced by a lower bound of $C^{1,\sigma}$ - or $W^{2,p}$ -harmonic radius. This is more explicit than the original assumption because harmonic coordinates can be constructed by using analytic method (e.g., [15]). It is possible, but still a challenge, to estimate harmonic radius along the Ricci flow.

4. A geometrical alternative to De Giorgi-Nash-Moser's iteration

In this section, we compare our geometrical blow-up argument with Moser's iteration technique. In particular, by using Moser's iteration and results in [21], we derive a theorem which requires a weaker injectivity radius assumption, and has weaker conclusion, than Theorem 1.1. We first recall the following crucial lemma [21, Proposition 1].

Proposition 4.1. *Let $(M^n, g(t))$ be a smooth solution to the Ricci flow defined for $0 \leq t \leq T$. Assume that there exist $A, K > 0$ such that $|\text{Ric}| \leq K$ on $\mathcal{P}(\frac{A}{\sqrt{K}}; x_0, T) := B_{\frac{A}{\sqrt{K}}}(x_0, 0) \times [0, T]$. Then, for any $p \geq 3$, there exists $c = c(n, p) > 0$ so that for all $0 \leq t \leq T$*

$$\|Rm\|_{L^p(B')}^p(t) \leq ce^{cKT} \left(\|Rm\|_{L^p(B)}^p(0) + K^p(1 + A^{-2p}) \text{Vol}_{g(t)}(B) \right),$$

where $B' = B_{\frac{A}{2\sqrt{K}}}(x_0, 0)$ and $B = B_{\frac{A}{\sqrt{K}}}(x_0, 0)$.

By using this proposition, Moser's technique and its generalized version for varying metrics (cf. [22, Chapter 19], [36, 37] or [10, Theorem 2.1]), Kotschwar-Munteanu-Wang derived the following bound:

$$|Rm|(x_0, T) \leq ce^{c(KT+A)} \left(1 + \left(\frac{\Lambda_0}{K} \right)^\alpha + \left(\frac{1}{KT} + A^{-2} \right)^\beta \right) (K(1 + A^{-2}) + \Lambda_0).$$

Here α, β, c are constants depending only on n and $\Lambda_0 = \sup_{B_{\frac{A}{\sqrt{K}}}(x_0, 0)} |Rm|$.

To compare their approach with ours, we prove the following theorem based on Kotschwar-Munteanu-Wang's argument.

Theorem 4.2. *Let $(M^n, g(t))_{t \in [0, T]}$ be a smooth solution of the Ricci flow. If*

$$|\text{Ric}| \leq K \text{ in } \overline{\mathcal{P}(4r; x_0, T)} \text{ and } \inf_{B_{4r}(x_0, 0)} \text{inj} \geq I > 0$$

for some $K, I, r > 0$, then there exists C depending on K, I, r, T and the dimension n such that $|Rm|(x_0, t) \leq C$ in $\mathcal{P}(r; x_0, T) \setminus \mathcal{P}(r; x_0, \frac{1}{2}T)$.

Proof. For any point $y \in B_{2r}(x_0, 0)$, consider the harmonic coordinates around it. Since Ricci curvature is bounded and the injectivity radius is bounded from below, these coordinates cover a geodesic ball $B_{\epsilon I}(y, 0)$ for some ϵ depending on K, I and n . Since $\|\text{Ric}\|_{L^p}$ is bounded, elliptic regularity of the equation $\Delta_g g_{ij} = -2R_{ij} + P(g, \partial g)$ shows that $\|Rm\|_{L^p(B_{\epsilon I}(y, 0))}$ is bounded by some constant C for all $p > 1$ (cf. Section 2 or [1]). Furthermore, a standard result due to Gromov says that the lower bound of Ricci curvature implies that $B_{2r}(x_0, 0)$ can be covered by a finite collection of $B_{\epsilon I}(y_i, 0)$'s, say $i = 1, \dots, N$. Note that N only depends on $n, \epsilon I, r$ and K . Hence $\|Rm\|_{L^p(B_{2r}(x_0, 0))}$ must be bounded by some constant $C_L = C_L(n, K, I, r, p)$.

By Proposition 4.1, when $p \geq 3$, the evolving L^p -norm of $|Rm|$ on $B_r(x_0, 0)$ is controlled by

$$\|Rm\|_{L^p(B_r)}^p(t) \leq ce^{cKT} \left(\|Rm\|_{L^p(B_{2r})}^p(0) + K^p \left(1 + (\epsilon I \sqrt{K})^{-2p} \right) \text{Vol}_{g(t)}(B_{2r}) \right),$$

where $B_r = B_r(x_0, 0)$ and $B = B_{2r}(x_0, 0)$. Divide both sides by $\text{Vol}_{g(t)}(B_r)$ and use $\|Rm\|_{L^p(B_{2r})}^p(0) \leq C_L^p$, one obtains

$$\frac{1}{\text{Vol}_{g(t)}(B_r)} \|Rm\|_{L^p(B_r)}^p(t) \leq \frac{ce^{cKT} C_L^p}{\text{Vol}_{g(t)}(B_r)} + ce^{cKT} \left(K^p + (\epsilon I)^{-2p} \right) \cdot \frac{\text{Vol}_{g(t)}(B_{2r})}{\text{Vol}_{g(t)}(B_r)}.$$

To find a lower bound for $\text{Vol}_{g(t)}(B_r)$, we need Berger-Croke's theorem (cf. [8, Proposition 14]): there is a uniform constant C_{inj} which depends only on n such that, for any Riemannian metric and any $r > 0$, $\inf_{B_{2r}} \text{inj} \geq I$ implies that $\text{Vol}(B_r) \geq C_{\text{inj}} I^n$. Thus

$$\begin{aligned} & \frac{1}{\text{Vol}_{g(t)}(B_r)} \|Rm\|_{L^p(B')}^p(t) \\ & \leq ce^{cKT} C_L^p C_{\text{inj}} I^n + ce^{cKT} \left(K^p + (\epsilon I)^{-2p} \right) \cdot \frac{\text{Vol}_{g(t)}(B_{2r})}{\text{Vol}_{g(t)}(B_r)}. \end{aligned}$$

Since $\frac{\partial}{\partial t} d\text{Vol} = -R \cdot d\text{Vol}$ along the Ricci flow, the volume ratio which appears in the last term can be estimated by

$$\frac{\text{Vol}_{g(t)}(B_{2r})}{\text{Vol}_{g(t)}(B_r)} \leq e^{2KT} \frac{\text{Vol}_{g(0)}(B)}{\text{Vol}_{g(0)}(B')} \leq e^{2KT} \cdot ce^K$$

where the last inequality comes from Bishop-Gromov volume comparison theorem. Therefore, $\frac{1}{\text{Vol}_{g(t)}(B_r)} \|Rm\|_{L^p(B_r)}^p(t) \leq ce^{cKT}$ and we may apply Moser's iteration and derive a similar curvature bound as in [21, pages 2620-2623]. \square

As one can observe easily, Theorem 1.6 only involves the initial lower bound of inj , while Theorem 1.2 involves $\text{inj}_{g(t)}$ for $t \neq 0$. On the other hand, the bounds in Theorem 1.1 and 1.2 are much better than the one in Theorem 1.6.

Remark 4.3. After checking the argument carefully, one can see that our geometrical blow-up method is valid for general geometric flow $\frac{\partial}{\partial t}g = \mathcal{R}$ possessing Shi's property, where \mathcal{R} is a symmetric two-tensor defining by Ricci curvature and g . Indeed, if such a flow $\frac{\partial}{\partial t}g = \mathcal{R}$ satisfies $\frac{\partial}{\partial t}|Rm| \leq \Delta|Rm| + C|Rm|^2$, then its curvature can be controlled by Ricci curvature and the injectivity radius in the sense of Theorem 1.1 and 1.2. This shows that our approach is somewhat an alternative argument to Moser's iteration. Note that one more advantage of our approach is that one actually obtains a $C^{0,\sigma}$ -bound, not only an L^∞ -bound.

5. Applications

5.1. Compactness of the Ricci flow

It has been known for decades that a sequence of closed connected Riemannian n -manifolds $\{(M_k, g_k)\}_{k \in \mathbb{N}}$ with bounded curvature, bounded diameter and volume bounded from below by a positive constant must contain a subsequence which converges in $C^{1,\alpha}$ -topology to a Riemannian n -manifold (M_∞, g_∞) (cf. [15]). Thus we say the collection

$$\text{LV} := \{(M^n, g, L, V, D) \mid |Rm| \leq L, \text{Vol} \geq V \text{ and diam} \leq D\}$$

is pre-compact for any given real numbers $L \geq 0, V > 0$ and $D > 0$. In [13], L. Z. Gao showed that the same conclusion holds when the condition $|Rm| \leq L$ is replaced by $|\text{Ric}| \leq K$ and a certain integral bound of $|Rm|$. On the other hand, Anderson [1] showed that, if $\text{inj} := \inf_M \text{inj}(x) \geq I > 0$, then $|Rm| \leq L$ can be replaced by merely $|\text{Ric}| \leq K$. That is, the set

$$\text{KI} := \{(M^n, g, K, I, D) \mid |\text{Ric}| \leq K, \text{inj} \geq I \text{ and diam} \leq D\}$$

is also pre-compact for any given real numbers $K \geq 0, I > 0$ and $D > 0$. As observed by Cheng-Li-Yau [6], and Cheeger-Gromov-Taylor [5] independently, the condition of injectivity radius can be derived from bounds of $|Rm|$ and Vol , thus LV-condition implies KI-condition. Note that the inverse is very likely not true although we do not notice any constructed counter-example in the limited literatures we have surveyed. In particular, one seems not able to improve the convergency from $C^{1,\alpha}$ to C^2 by using merely the KI-conditions.

Such convergence theory plays an important role in the study of singularities of the Ricci flow. Indeed, given a singular portion of the flow, one can blow up the solution around it and characterize the singularity by using the limit of these rescaling solutions. Thus we need the compactness theorem derived by R. S. Hamilton in [18] to ensure the existence of such limiting solution. A particular version of Hamilton's theorem says that if a sequence of marked complete

solutions of the Ricci flow $\{(M_k, g_k(t), x_k)_{t \in [0, T]}\}_{k \in \mathbb{N}}$ satisfies $|Rm|_{g_k}(x, t) \leq L$ for all x, t and $\text{Vol}_{g_k(0)}(B_r(x_k)) \geq V$ for some $r > 0$, then there exists a subsequence converging in C_{loc}^∞ -topology to a marked complete solution of the Ricci flow $(M_\infty, g_\infty(t), x_\infty)_{t \in (0, T]}$. The smooth convergency is due to Shi's estimate, which says that all higher order derivatives of Rm are bounded provided that Rm is bounded along the Ricci flow. Hence Hamilton's theorem can be seen as a LV-compactness theorem for the Ricci flow. By using Theorems 1.2 and 1.6, one can derive a C^∞ KI-compactness theorem without assuming any bound on the curvature operator.

Corollary 5.1. *Let $(M_k, g_k(t), x_k)_{t \in [0, T]}$ be a sequence of marked complete solutions of the Ricci flow. Suppose there are constants K, δ, I such that $|\text{Ric}|_{g_k} \leq K$ on $M_k \times [0, T]$ and*

$$\inf_{M_k \times [0, T]} \text{inj} \geq \delta \sqrt{t} \quad \text{or} \quad \inf_{M_k \times \{0\}} \text{inj} \geq I > 0 \quad \text{for all } k,$$

then there exist a subsequence $S_j := (M_j, g_j(t), x_j)$ and a solution $S_\infty := (M_\infty, g_\infty(t), x_\infty)$ of the Ricci flow over $t \in (0, T]$ such that S_j converges in C^∞ -topology to S_∞ on every time interval $[\epsilon, T]$ with $\epsilon > 0$ as $j \rightarrow \infty$.

5.2. Ricci soliton

Ricci solitons are manifolds (M, g) coupled with a smooth vector field X , which can generate self-similar solutions to the Ricci flow. Indeed, if a Riemannian manifold (M, g) satisfies $\text{Ric}_g + \frac{1}{2}L_Xg = \lambda g$ for some X , then $g(t) = \rho(t)\varphi_t^*g(0)$ solves the Ricci flow, where $\rho(t) = 1 - 2\lambda t$ and $\varphi_t : M \rightarrow M$ is the one parameter family of diffeomorphisms generated by ρX (cf. [3, Chapter 1]). Moreover, if $X = \nabla f$ for some smooth function $f : M \rightarrow \mathbb{R}$, then the soliton is called a gradient Ricci soliton.

Curvature growth is an important issue for the study of gradient Ricci solitons. Some classification results are built on the growth assumptions and, on the other hand, people expect that curvature of solitons should obey certain natural growth/decay laws. In [25], Munteanu and M.-T. Wang proved that every shrinking gradient Ricci soliton with bounded Ricci curvature must have a polynomial bound of its curvature. The following theorem shows that, if the injectivity radius is bounded from below, then the curvature can be uniformly bounded by a constant.

Theorem 5.2. *Given any $\lambda \in \{\pm\frac{1}{2}, 0\}$, all n -dimensional Ricci solitons*

$$\text{Ric} + \frac{1}{2}L_Xg = \lambda g$$

with $|\text{Ric}| \leq K$ and $\text{inj} \geq I > 0$ have the same curvature bound.

Proof. Consider a self-similar solution generated by the soliton on a time interval $[0, t^*]$ for some $t^* > 0$. Since the soliton changes only up to a scaling factor

along the flow (modulo by diffeomorphisms), so the bounds of curvature and injectivity radius are changing according to the scaling factor. Indeed, $\text{Ric}_{g(t)}(x) = \rho^{-1}(t) \text{Ric}_{g(0)}(\varphi_t(x))$ and $\text{inj}_{g(t)}(x) = \rho^{\frac{1}{2}}(t) \text{inj}_{g(0)}(\varphi_t(x))$, where $\rho(t) = 1 - 2\lambda t$, on the self-similar solution. By applying Theorem 2, we know that $|\nabla \text{Ric}|$ is uniformly bounded at $t = t^*$. That means $|Rm| \leq C$ at $t = t^*$, where C depends on K, I, t^*, λ and n . Because $g(0)$ differs to $g(t^*)$ only by a scaling factor, we have $|Rm| \leq C$ at $t = 0$. \square

Based on this curvature estimate, one can further ask for compactness result.

Corollary 5.3. *Let $\lambda \in \{\pm \frac{1}{2}, 0\}$ and $A \in \mathbb{R}$. For any sequence of gradient Ricci solitons $(M_k, g_k, f_k, p_k)_{k \in \mathbb{N}}$ satisfying $\text{Ric}_{g_k} + \text{Hess}(f_k) = \lambda g_k$, if*

$$|\text{Ric}|_{g_k} \leq K, \quad \text{inj}_{g_k} \geq I > 0 \quad \text{and} \quad |\nabla f|_{g_k}(p_k) \leq A,$$

then there exists a subsequence converging smoothly to $(M_\infty, g_\infty, f_\infty, p_\infty)$, which satisfies $\text{Ric}_{g_\infty} + \text{Hess}(f_\infty) = \lambda g_\infty$ with $f_\infty = \lim_{k \rightarrow \infty} f_k$.

Proof. As in the proof of previous corollary, we can evolve these solitons to some time $t^* > 0$ and obtain uniform bounds for Rm and injectivity radius for all $t \in [0, t^*]$. Moreover, all the derivatives of Rm are bounded at $t = t^*$ by Shi's estimate. Hence, all the curvatures and their derivatives are bounded at $t = 0$ and thus there exists a subsequential limit $(M_\infty, g_\infty, p_\infty)$.

To show the convergence of f_k 's, we normalize f by subtraction such that $f(p_k) = 0$ and then use $|\text{Hess}(f_k)| = |\lambda g_k - \text{Ric}_{g_k}| \leq n|\lambda| + K$. Indeed, the bound of $\text{Hess}(f_k)$ shows that $|\nabla f_k|$ grows at most linearly and $|f_k|$ grows at most quadratically from the point p_k , where $f_k = 0$ and $|\nabla f_k| \leq A$. In particular, for any given $r < \infty$, there are uniform bounds for f_k 's and $|\nabla f_k|$'s on the geodesic balls $B_r(p_k)$. So f_k 's have a uniform C^2 -bound for every fixed r . Moreover, all higher derivatives of f_k depend only on the derivatives of Ric and lower derivatives of f_k , thus are uniformly bounded. Therefore, there exists a subsequence of (M_k, g_k, f_k, p_k) converging smoothly to a Ricci soliton $(M_\infty, g_\infty, f_\infty, p_\infty)$ satisfying $\text{Ric}_{g_\infty} + \text{Hess}(f_\infty) = \lambda g_\infty$. \square

5.3. Curvature taming around the initial time

In Theorem 1.2, if we set $T = \frac{\eta}{K}$, then we obtain an estimate $|Rm| \leq Ch^{-1}(t)$ where C is a constant depending only on n, δ and η . Surprisingly, this bound does not involve the bound of Ricci curvature. Combining with the fact that $\text{inj}_{g(0)}$ is not involved in Theorem 1.2, we can prove that every Ricci flow is 1-tamed by a universal constant up to a certain time.

Theorem 5.4. *There exists a universal constant $C = C(n)$ such that for any smooth Ricci flow $(M^n, g(t))$ and any point $x_0 \in M$,*

$$|Rm|(x, t) \leq Ct^{-1} \quad \text{on } B_{4r}(x_0, t) \text{ for all } t \in (0, K^{-1}],$$

and

$$|Rm|(x, t) \leq CK \text{ on } B_{4r}(x_0, t) \text{ for all } t \in [K^{-1}, r^2],$$

where $r^2 := \inf\{t > 0 \mid \inf_{B_{8r}(x_0, t)} \text{inj} < \sqrt{t}\}$ and K denotes the maximum of r^{-2} and $\sup |Ric|$ on $\bigcup_{[0, r^2]} B_{8r}(x_0, t)$.

Proof. Since the flow is smooth, for any $x_0 \in M$, there must exist an $r > 0$ by the continuity of inj . That is, $\text{inj} \geq \sqrt{t}$ on $\bigcup_{[0, r^2]} B_{8r}(x_0, t)$. By the definition of K , we have $|Ric| \leq K$ on $\bigcup_{[0, r^2]} B_{8r}(x_0, t)$. Consider $y \in B_{4r}(x_0, 0)$ and apply Theorem 1.2 with $\delta = \eta = 1$, $T = \frac{1}{K} \leq r^2$ and $h = t$ on the domain $\bigcup_{[0, r^2]} B_{4r}(y, t)$, one obtains $|Rm|(y, t) \leq Ct^{-1}$ for some $C = C(n)$ and $t \in (0, K^{-1}]$. Since y is an arbitrary point in $B_{4r}(x_0, 0)$, $|Rm|(x, t) \leq Ct^{-1}$ on $\bigcup_{(0, K^{-1}]} B_{4r}(x_0, t)$. For $t \in [K^{-1}, r^2]$, one may apply Theorem 1.2 on $\bigcup_{[t^*, t^*+K^{-1}]} B_{4r}(y, t)$ and see that $|Rm|(y, t^*) \leq CK$. Since t^* is arbitrary, the second statement of the theorem is proved. \square

6. An estimate of ∇Ric without using injectivity radius

For every Riemannian manifold, the traced second Bianchi identity $\nabla_j R_{ij} = \frac{1}{2} \partial_i R$ holds. In view of this, we say that a manifold satisfies *strong Bianchi inequality* if the pointwise norm estimate $|\nabla \text{Ric}| \leq \beta |\nabla R|$ holds for some $\beta > 0$. For a solution of the Ricci flow, we consider a weaker condition as follows.

Definition 6.1. Let U be an open set of a manifold M . A solution of the Ricci flow $(U, g(t))_{t \in (0, T]}$ with $|\text{Ric}| \leq K$ is said to satisfy the weak Bianchi inequality if

$$|\nabla \text{Ric}| \leq \alpha K t^{-\frac{1}{2}} + \beta |\nabla R|$$

on $U \times (0, T]$ for some constants $\alpha, \beta > 0$.

This inequality means that the trace-free part of ∇Ric is bounded by either the traced part or a constant which is allowed to depend on $t^{-\frac{1}{2}}$. This is not a strong restriction in the sense that it holds on a large class of static manifolds. More details about this can be found in the next section.

In [30], W.-X. Shi proved that if the curvature operator is bounded along the Ricci flow, then all the derivatives of it are bounded uniformly except for the initial time. If the boundedness condition of the full curvature operator is replaced by the one of Ricci curvature, then it seems that Shi-type estimate does not hold. However, if we impose the condition that weak Bianchi inequality holds, then we can derive a Shi-type estimate for Ricci curvature. Note that the weak Bianchi inequality is quite looser than the strong one, because it allows $|\nabla \text{Ric}| \neq 0$ whenever $|\nabla R| = 0$ at some point.

Theorem 6.2 (Global estimate). *There exists a constant $C > 0$, depending only on α, β and n such that for every n -dimensional closed solution $(M^n, g(t))_{t \in [0, T]}$*

of the Ricci flow, if the Ricci curvature and its derivatives satisfy that $|\text{Ric}| \leq K$ and $|\nabla \text{Ric}| \leq \alpha K t^{-\frac{1}{2}} + \beta |\nabla R|$ for all $t \in [0, \frac{1}{K}] \subset [0, T)$, where K is a positive constant, then

$$|\nabla \text{Ric}|^2 \leq CK^2 t^{-1}$$

for all $t \in (0, \frac{1}{K}]$.

Remark 6.3. When $t = 0$, we define $\frac{1}{t}$ to be ∞ . Hence the aforementioned inequalities, which are concerned, hold trivially.

We recall the following evolution equations that will be used in the proof:

$$\frac{\partial}{\partial t} R = \Delta R + 2|\text{Ric}|^2, \quad \frac{\partial}{\partial t} R^2 = 2R(\Delta R + 2|\text{Ric}|^2) = \Delta R^2 - 2|\nabla R|^2 + 4R \cdot |\text{Ric}|^2$$

and

$$\begin{aligned} \frac{\partial}{\partial t} |\nabla R|^2 &= 2 \left\langle \nabla R, \nabla (\Delta R + 2|\text{Ric}|^2) \right\rangle - 2 \text{Ric}(\nabla R, \nabla R) \\ &\leq \Delta |\nabla R|^2 - 2 \left| \nabla^2 R \right|^2 + 4|\text{Ric}| \cdot |\nabla R|^2 + 8|\text{Ric}| \cdot |\nabla \text{Ric}| \cdot |\nabla R|. \end{aligned}$$

Proof. Since $\frac{\partial}{\partial t} R = \Delta R + 2|\text{Ric}|^2$, by $|\text{Ric}| \leq K$, we have

$$\frac{\partial}{\partial t} R^2 \leq \Delta R^2 - 2|\nabla R|^2 + CK^3,$$

where C is an indefinite constant varying line by line. Moreover, using $|\nabla \text{Ric}| \leq \alpha K t^{-\frac{1}{2}} + \beta |\nabla R|$, we can derive

$$\frac{\partial}{\partial t} |\nabla R|^2 \leq \Delta |\nabla R|^2 - 2 \left| \nabla^2 R \right|^2 + CK |\nabla R|^2 + CK^3 t^{-1}.$$

Let $F = t|\nabla R|^2 + AR^2$ for some constant A . We can show that $\frac{\partial}{\partial t} F \leq \Delta F + CK^3$ whenever A is larger than some constant depending only on β . Comparing with the o.d.e. $\frac{d}{dt}\phi(t) = CK^3$, one can prove that $F \leq C(K^2 + K^3 t)$ by maximum principle. Hence $|\nabla R|^2 \leq CK^2 t^{-1}$. By using the weak Bianchi inequality again, we have $|\nabla \text{Ric}|^2 \leq CK^2 t^{-1}$. \square

To show the local version, we have to do more efforts. To abbreviate the notation, we define the parabolic region emanated from $B_r(x_0, 0)$ as

$$\mathcal{P}(r; x_0, t_0) := \Omega \times (0, t_0], \text{ where } \Omega \subset M$$

is the topological region defined by $B_r(x_0, 0)$.

Theorem 6.4 (Local estimate). *There exist positive constants θ_0 and C depending only on α, β, n and Λ such that for every solution $(M^n, g(t))_{t \in [0, \theta_0/K]}$ of the Ricci flow, if $|Rm| \leq \Lambda$ on $B_r(x_0, 0)$, $|\text{Ric}| \leq K$ and $|\nabla \text{Ric}| \leq \alpha K \left(\frac{1}{r^2} + \frac{1}{t} + K \right)^{\frac{1}{2}} + \beta |\nabla R|$ on $\overline{\mathcal{P}(r; x_0, t_0)}$ for some $r \leq \sqrt{\theta_0/K}$ and $t_0 \leq \theta_0/K$, then*

$$|\nabla \text{Ric}|^2 \leq C K^2 \left(\frac{1}{r^2} + \frac{1}{t} + K \right)$$

on $\mathcal{P}(\frac{r}{\sqrt{2}}; x_0, t_0)$.

Proof. Recall that along the Ricci flow

$$\frac{\partial}{\partial t} R^2 = \Delta R^2 - 2|\nabla R|^2 + 4R \cdot |\text{Ric}|^2$$

and

$$\frac{\partial}{\partial t} |\nabla R|^2 \leq \Delta |\nabla R|^2 - 2 \left| \nabla^2 R \right|^2 + 4|\text{Ric}| \cdot |\nabla R|^2 + 8|\text{Ric}| \cdot |\nabla \text{Ric}| \cdot |\nabla R|.$$

Denoting $u = \frac{1}{r^2} + \frac{1}{t} + K$, by the assumptions and Yang's inequality, we have

$$\frac{\partial}{\partial t} |\nabla R|^2 \leq \Delta |\nabla R|^2 - 2 \left| \nabla^2 R \right|^2 + C_1 K |\nabla R|^2 + C_1 K^3 u,$$

for some constant $C_1 > 0$.

Let $S = (BK^2 + R^2) \cdot |\nabla R|^2$, where $B > \max\{n^2 + 4nC_1^{-1}, 32n^2\}$ is a constant. We derive

$$\begin{aligned} \frac{\partial}{\partial t} S &= \frac{\partial}{\partial t} R^2 \cdot |\nabla R|^2 + (BK^2 + R^2) \frac{\partial}{\partial t} |\nabla R|^2 \\ &\leq (\Delta R^2 - 2|\nabla R|^2 + 4R \cdot |\text{Ric}|^2) \cdot |\nabla R|^2 \\ &\quad + (BK^2 + R^2) (\Delta |\nabla R|^2 - 2|\nabla^2 R|^2 + C_1 K |\nabla R|^2 + C_1 K^3 u) \\ &\leq \Delta S - 2\nabla R^2 \cdot \nabla |\nabla R|^2 - 2|\nabla R|^4 - 2(B + n^2) K^2 \left| \nabla^2 R \right|^2 \\ &\quad + (C_1 B + C_1 n^2 + 4n) K^3 |\nabla R|^2 + C_1 (B + n^2) K^5 u \\ &\leq \Delta S - 2\nabla R^2 \cdot \nabla |\nabla R|^2 - 2|\nabla R|^4 - 2BK^2 \left| \nabla^2 R \right|^2 \\ &\quad + 2C_1 BK^3 |\nabla R|^2 + 2C_1 BK^5 u. \end{aligned}$$

We want to control the bad terms $2\nabla R^2 \cdot \nabla |\nabla R|^2$, whose sign is unknown, and $2C_1 BK^3 |\nabla R|^2$, which may not be bounded. Indeed, using the following two inequalities, they can be absorbed by the other terms:

$$\left| 2\nabla R^2 \cdot \nabla |\nabla R|^2 \right| \leq 8nK |\nabla R|^2 \cdot \left| \nabla^2 R \right| \leq \frac{1}{2} |\nabla R|^4 + 32n^2 K^2 \left| \nabla^2 R \right|^2$$

and

$$2C_1BK^3|\nabla R|^2 \leq \frac{1}{2}|\nabla R|^4 + 2C_1^2B^2K^6 \leq \frac{1}{2}|\nabla R|^4 + \frac{2}{3}C_1^2B^2K^5u.$$

Since $B > 32n^2$, substituting these two inequalities into the evolution equation of S , we get

$$\frac{\partial}{\partial t}S \leq \Delta S - |\nabla R|^4 + C_2B^2K^5u \leq \Delta S - \frac{S^2}{4B^2K^4} + C_2B^2K^5u,$$

for some constant C_2 . Consider $F = bSK^{-4}$ with some constant $b := \min\{\frac{1}{4B^2}, \frac{1}{C_2B^2}\}$ depending only on n , one can derive

$$\frac{\partial}{\partial t}F \leq \Delta F - F^2 + u^2.$$

To proceed the proof by using maximum principle, we need a space-time cut-off function. However, the standard way to construct such a function requires the bound of $|\nabla \text{Ric}|$, which is exactly what we want to derive here. (Because the evolution equation of $|\nabla^2\varphi|$, which can be seen in the proof of Lemma B afterwards, involves ∇Ric .) This problem occurs also in the proof of Shi's estimate. To tackle this, Hamilton [19, Section 13] used a continuity argument and eventually showed that there exists a short time θ_0K^{-1} such that Shi's estimate holds. The first step is to take a cut-off function φ on the initial manifold M satisfying $\{x \in M|\varphi > 0\} = B_r(x_0, 0)$, $\varphi = r$ in $B_{\frac{r}{\sqrt{2}}}(x_0, 0)$, $0 \leq \varphi \leq r < Ar$, $|\nabla\varphi| \leq A$ and $|\nabla^2\varphi| \leq \frac{A}{r}$ for some constant $A > 1$ depending only on n and the initial curvature bound Λ . Extend φ to be a space-time function by letting φ be independent of time. Since the Ricci flow is smooth, by continuity, $|\nabla\varphi|^2 \leq 2A^2$ and $\varphi|\nabla^2\varphi| \leq 2A^2$ holds on $\mathcal{P}(r; x_0, \theta_1/K)$ up to some time $\theta_1/K > 0$. Moreover, we can construct a barrier function H which behaves well up to $t = \theta_1/K$.

Lemma A. *Let $H = \frac{cA^2}{\varphi^2} + \frac{d}{t} + K$ for some constants $c = 14 + 4n$ and $d = 2(1 + \theta_1)$. Then $\frac{\partial}{\partial t}H > \Delta H - H^2 + u^2$ on $\mathcal{P}(r; x_0, \theta_1/K)$.*

By using the maximum principle, one can show that $H - F$ cannot vanish on $\mathcal{P}(p, r, \theta_1/K)$. Hence $H - F > 0$ on $\mathcal{P}(p, r, \theta_2/K)$ for some $\theta_2 > \theta_1$. Combining with the following lemma, we can show that θ_1 has a uniform lower bound, i.e., θ_1 must be larger than or equal to the uniform constant θ_0 described in the following lemma. We may assume $\theta_1 < 1$ (otherwise the uniform lower bound θ_0 can be simply taken to be 1).

Lemma B. *There exists a constant θ_0 which depends only on α, β, n and Λ such that if $|\text{Ric}| \leq K$ and $F \leq H$ on $\mathcal{P}(r; x_0, \theta/K)$ for some $\theta \leq \theta_0$ and $r \leq \sqrt{\theta/K}$, then $|\nabla\varphi|^2 \leq 2A^2$ and $\varphi|\nabla^2\varphi| \leq 2A^2$ on $\mathcal{P}(r; x_0, \theta/K)$.*

Indeed, suppose on the contrary that $\theta_1 < \theta_0$, then this lemma tells us that the estimates of derivatives of φ hold for time beyond θ_1 . This contradicts the definition of θ_1 .

Therefore, $F < H$ on $\mathcal{P}(r; x_0, \theta_0/K)$. We conclude that

$$\begin{aligned} |\nabla R|^2 &= \frac{FK^4}{b(BK^2 + R^2)} \leq \frac{K^4}{bBK^2} \left(\frac{(14+4n)A^2}{\varphi^2} + \frac{2(1+\theta_1)}{t} + K \right) \\ &\leq CK^2 \left(\frac{1}{\varphi^2} + \frac{1}{t} + K \right) \end{aligned}$$

and

$$\begin{aligned} |\nabla \text{Ric}|^2 &\leq \alpha^2 K^2 u + \beta^2 |\nabla R|^2 \leq \alpha^2 K^2 u + CK^2 \left(\frac{1}{\varphi^2} + \frac{1}{t} + K \right) \\ &\leq CK^2 \left(\frac{1}{r^2} + \frac{1}{t} + K \right) \end{aligned}$$

for some C depending only on α, β, n and Λ . \square

Now we prove Lemma A and Lemma B.

Proof of Lemma A. We show that $-\frac{\partial}{\partial t} H + \Delta H + u^2 < H^2$ by the following calculations. Using $|\nabla \varphi|^2 \leq 2A^2$, $\varphi |\nabla^2 \varphi| \leq 2A^2$ and $t \leq \theta_1/K$.

$$\begin{aligned} -\frac{\partial}{\partial t} H + \Delta H + u^2 &= \frac{d}{t^2} + cA^2 \Delta \left(\frac{1}{\varphi^2} \right) + \left(\frac{1}{r^2} + \frac{1}{t} + K \right)^2 \\ &\leq \frac{d}{t^2} + \frac{cA^2}{\varphi^4} (6|\nabla \varphi|^2 - 2\varphi \Delta \varphi) + \left(\frac{1}{r^2} + \frac{1}{t} + \frac{\theta_1}{t} \right)^2 \\ &\leq \frac{d}{t^2} + \frac{cA^2}{\varphi^4} (12A^2 + 4nA^2) + 2 \left(\frac{1}{r^2} \right)^2 + 2 \left(\frac{1+\theta_1}{t} \right)^2 \\ &\leq \frac{(12+4n)cA^4}{\varphi^4} + 2 \left(\frac{A^2}{\varphi^2} \right)^2 + \frac{2(1+\theta_1)^2 + d}{t^2} \\ &= \frac{((12+4n)c+2)A^4}{\varphi^4} + \frac{2(1+\theta_1)^2 + d}{t^2}. \end{aligned}$$

Choose $c = 14 + 4n$ and $d = 2(1 + \theta_1)$, then we have

$$\begin{aligned} -\frac{\partial}{\partial t} H + \Delta H + u^2 &\leq \frac{((12+4n)c+2)A^4}{\varphi^4} + \frac{2(1+\theta_1)^2 + d}{t^2} \\ &\leq \left(\frac{cA^2}{\varphi^2} \right)^2 + \left(\frac{d}{t} \right)^2 \leq H^2. \end{aligned} \quad \square$$

Proof of Lemma B. By definition, $\nabla\varphi = g^{ij}\varphi_j e_i = \varphi^i e_i$. Thus

$$\frac{\partial}{\partial t}|\nabla\varphi|^2 = \frac{\partial}{\partial t}\left(g^{ij}\varphi_i\varphi_j\right) = 2R_{pq}g^{ip}g^{jq}\varphi_i\varphi_j \leq 2K|\nabla\varphi|^2$$

whenever $|\text{Ric}| \leq K$. Therefore, $|\nabla\varphi|^2 \leq A^2 e^{2Kt} \leq 2A^2$ when $t \leq \frac{\theta}{K}$ and $\theta \leq \log\sqrt{2}$.

By using Uhlenbeck's orthonormal frame $\{E_a\}$ (cf. [17, page 155]), which satisfies $\frac{\partial}{\partial t}E_a^i = g^{ij}R_{jk}E_a^k$, one can derive

$$\begin{aligned}\frac{\partial}{\partial t}\nabla_a\nabla_b\varphi &= \frac{\partial}{\partial t}E_aE_b\varphi - \frac{\partial}{\partial t}(\Gamma_{ab}^cE_c\varphi) \\ &= R_{bc}\nabla_a\nabla_c\varphi + R_{da}\nabla_d\nabla_b\varphi - (\nabla_aR_{cb} + \nabla_bR_{ac} - \nabla_cR_{ab})E_c\varphi.\end{aligned}$$

Hence

$$\frac{\partial}{\partial t}\varphi|\nabla^2\varphi| = \varphi\frac{\partial}{\partial t}|\nabla^2\varphi| \leq C\varphi\left(|\text{Ric}||\nabla^2\varphi| + |\nabla\text{Ric}||\nabla\varphi|\right).$$

By the assumption $F = b(BK^2 + R^2)K^{-4}|\nabla R|^2 \leq H = \frac{cA^2}{\varphi^2} + \frac{d}{t} + K$ and the weak Bianchi inequality, we have

$$|\nabla R|^2 \leq \frac{K^4}{b(BK^2 + R^2)}\left(\frac{cA^2}{\varphi^2} + \frac{d}{t} + K\right) \leq \frac{K^2}{bB}\left(\frac{cA^2}{\varphi^2} + \frac{d + \theta_1}{t}\right)$$

and

$$\begin{aligned}|\nabla\text{Ric}| &\leq \alpha K\sqrt{\frac{1}{r^2} + \frac{1}{t} + K} + \beta\frac{K}{\sqrt{bB}}\sqrt{\frac{cA^2}{\varphi^2} + \frac{d + \theta_1}{t}} \\ &\leq CK\left(\sqrt{\frac{cA^2}{\varphi^2} + \frac{d + \theta_1}{t}}\right),\end{aligned}$$

where C depends on α, β and n . Recall that $\varphi \leq r$, $A > 1$, $c = 14 + 4n$ and $d = 2(1 + \theta_1) < 4$. Hence

$$\begin{aligned}\frac{\partial}{\partial t}\varphi|\nabla^2\varphi| &\leq CK\varphi|\nabla^2\varphi| + CK|\nabla\varphi|\sqrt{cA^2 + \frac{(d + \theta_1)\varphi^2}{t}} \\ &\leq CK\left(\varphi|\nabla^2\varphi| + A + \frac{r}{\sqrt{t}}\right),\end{aligned}$$

where C depends on α, β and n . By comparing with the ordinary differential equation $\frac{d}{dt}\phi = CK\left(\phi + A + \frac{r}{\sqrt{t}}\right)$, as Hamilton did in [19, pages 45-46], one can show that

$$\varphi|\nabla^2\varphi| \leq e^{CKt}\left(A^2 + CK(At + 2r\sqrt{t})\right).$$

Therefore, when $r \leq \sqrt{\frac{\theta}{K}}$ and $t \leq \frac{\theta}{K}$ for some $\theta = \theta(\alpha, \beta, n, A)$, we have $\varphi |\nabla^2 \varphi| \leq 2A^2$. \square

7. Further discussion on Bianchi inequalities

In this section, we discuss the validity of Bianchi inequalities on a fixed Riemannian manifold. For general Riemannian manifolds, the derivative of Ricci tensor can be decomposed as follows.

Theorem 7.1 (Cf. [16, page 288] for $n = 3$). *Let $E_{ijk} = a(g_{ij}\partial_k R + g_{ik}\partial_j R) + b g_{jk}\partial_i R$ with $a = \frac{n-2}{2n^2+2n-4}$ and $b = \frac{1}{2} - a(n+1)$. Then the decomposition $\nabla_i R_{jk} = E_{ijk} + F_{ijk}$ satisfies that $g^{ij}F_{ijk} = g^{jk}F_{ijk} = g^{ki}F_{ijk} = 0$ and $\langle E_{ijk}, F_{ijk} \rangle = 0$. In particular, we have*

$$|\nabla_i R_{jk}|^2 = |E_{ijk}|^2 + |F_{ijk}|^2 \quad \text{and} \quad |E_{ijk}|^2 = (a+b)|\nabla R|^2.$$

Remark 7.2. When $n = 3$, $a = \frac{1}{20}$, $b = \frac{3}{10}$ and $|E_{ijk}|^2 = \frac{7}{20}|\nabla R|^2$; when $n = 4$, $a = \frac{1}{18}$, $b = \frac{2}{9}$ and $|E_{ijk}|^2 = \frac{5}{18}|\nabla R|^2$.

From this proposition, we know that a manifold satisfies the weak Bianchi inequality if the trace-free part of ∇Ric can be bounded by the non-free part and a constant, i.e. $|F_{ijk}|^2 \leq |E_{ijk}|^2 + C$. Note that when $n \rightarrow \infty$, $a+b \rightarrow 0$ and thus $|\nabla \text{Ric}| \approx |F_{ijk}|$.

Proof. Using $g^{ij}F_{ijk} = g^{jk}F_{ijk} = 0$ and the traced second Bianchi identity $\nabla_i R_k^i = \frac{1}{2}\partial_k R$, one can derive $(n+1)a + b = \frac{1}{2}$ and $2a + nb = 1$. Thus $a = \frac{n-2}{2n^2+2n-4}$.

Furthermore, an easy computation shows that $|E_{ijk}|^2 = (2(n+1)a^2 + 4ab + nb^2)|\nabla R|^2$ and $\langle E_{ijk}, \nabla_i R_{jk} \rangle = (a+b)|\nabla R|^2$. Observing that $2(n+1)a^2 + 4ab + nb^2 = a+b$, one obtains $\langle E_{ijk}, F_{ijk} \rangle = \langle E_{ijk}, \nabla_i R_{jk} - E_{ijk} \rangle = 0$. \square

On the other hand, we can compute explicitly on manifolds with rotationally symmetric metrics.

Theorem 7.3. *Let (M, g) , $g = dr^2 + \varphi^2(r)g_{\mathbb{S}^{n-1}}$, be a rotationally symmetric n -dimensional manifold and $n \geq 3$. Here r is the arc-length parameter. Denote the radial and spherical sectional curvatures as K_0 and K_1 , respectively. Suppose that $\frac{\partial}{\partial r}K_0 \cdot \frac{\partial}{\partial r}K_1 \geq -\frac{C^2}{(n-1)^2-1}$ for some constant C . Then*

$$|\nabla \text{Ric}|^2 \leq \left(\frac{1}{4} + \frac{1}{4(n-1)^2} \right) |\nabla R|^2 + (n-2)C^2$$

on U . In particular, (M, g) satisfies the strong Bianchi inequality $|\nabla \text{Ric}| \leq \frac{n}{2(n-1)}|\nabla R|$ whenever $\frac{\partial}{\partial r}K_0 \cdot \frac{\partial}{\partial r}K_1$ is nonnegative (e.g., a paraboloid or an infinite horn).

Remark 7.4. In this theorem, we do not assume that $|\text{Ric}|$ is bounded by some constant.

Proof. It is well-known that for rotationally symmetric manifolds we have

$$\text{Ric} = (n-1)K_0 dr^2 + (K_0 + (n-2)K_1)\varphi^2 g_{\mathbb{S}^{n-1}}$$

and

$$R = (n-1)K_0 + (n-1)(K_0 + (n-2)K_1).$$

Hence

$$\begin{aligned} |\nabla R|^2 &= 4(n-1)^2 \left(\frac{\partial}{\partial r} K_0 \right)^2 + 4(n-1)^2(n-2) \left(\frac{\partial}{\partial r} K_0 \right) \left(\frac{\partial}{\partial r} K_1 \right) \\ &\quad + (n-1)^2(n-2)^2 \left(\frac{\partial}{\partial r} K_1 \right)^2 \end{aligned}$$

and

$$\begin{aligned} |\nabla \text{Ric}|^2 &= (\nabla_1 R_{11})^2 + (\nabla_1 R_{jj})^2 \\ &= (n-1)^2 \left(\frac{\partial}{\partial r} K_0 \right)^2 + \left(\frac{\partial}{\partial r} K_0 + (n-2) \frac{\partial}{\partial r} K_1 \right)^2 \\ &\leq \frac{(n-1)^2 + 1}{4(n-1)^2} |\nabla R|^2 + (n-2) \left(1 - (n-1)^2 \right) \left(\frac{\partial}{\partial r} K_0 \right) \left(\frac{\partial}{\partial r} K_1 \right) \\ &\quad + \frac{(n-2)^2}{4} \left(3 - (n-1)^2 \right) \left(\frac{\partial}{\partial r} K_1 \right)^2 \\ &\leq \frac{(n-1)^2 + 1}{4(n-1)^2} |\nabla R|^2 + (n-2)C^2. \end{aligned} \quad \square$$

It is interesting to know whether such Bianchi inequalities hold for generic solutions of the Ricci flow. A related result which appeared earlier in a collaborated work of A. Deruelle and the author [4, Theorem 2.10] shows that the validity of such inequalities may help us to resolve some long standing open problems about expanding gradient Ricci solitons.

References

- [1] M. T. ANDERSON, *Convergence and rigidity of manifolds under Ricci curvature bounds*, Invent. Math. **102** (1990), 429–445.
- [2] H.-D. CAO and X. CUI, *Curvature estimates for four-dimensional gradient steady Ricci solitons*, ArXiv:1411.3631.
- [3] B. CHOW, S.-C. CHU, D. GLICKENSTEIN, C. GUENTHER, J. ISENBERG, T. IVEY, D. KNOPH, P. LU, F. LUO and L. NI, “The Ricci Flow: Techniques and Applications. Part I: Geometric Aspects”, Vol. 135, Math. Surv. Mono., Amer. Math. Soc., 2007.

- [4] C.-W. CHEN and A. DERUELLE, *Structure at infinity of expanding gradient Ricci soliton*, Asian J. Math. **19** (2015), 933–950.
- [5] J. CHEEGER, M. GROMOV, and M. TAYLOR, *Finite propagation speed, kernel estimates for functions of the Laplace operator, and the geometry of complete Riemannian manifolds*, J. Differential Geom. **17** (1982), 15–53.
- [6] S. Y. CHENG, P. LI and S.-T. YAU, *On the upper estimate of the heat kernel of complete Riemannian manifold*, Amer. J. Math. **103** (1981), 1021–1063.
- [7] B. CHOW, P. LU and B. YANG, *Lower lower bounds for the scalar curvatures of noncompact gradient Ricci solitons*, C. R. Math. Acad. Sci. Paris **349** (2011), 1265–1267.
- [8] C. B. CROKE, *Some isoperimetric inequalities and eigenvalue estimates*, Ann. Sci. École Norm. Sup. (4) **13** (1980), 419–435.
- [9] A. DERUELLE, *Stability of non compact steady and expanding gradient Ricci solitons*, Calc. Var. Partial Differential Equations **54** (2015), 2367–2405.
- [10] X. DAI, G. WEI and R. YE, *Smoothing Riemannian metrics with Ricci curvature bounds*, Manuscripta Math. **90** (1996), 49–61.
- [11] Y. DENG and X. ZHU, *Complete non-compact gradient Ricci solitons with nonnegative Ricci curvature*, Math. Z. **279** (2015), 211–226.
- [12] J. ENDERS, R. MÜLLER and P. M. TOPPING, *On type I singularities in Ricci flow*, Comm. Anal. Geom. **19** (2011), 905–922.
- [13] L. Z. GAO, *Convergence of Riemannian manifolds; Ricci and $L^{n/2}$ -curvature pinching*, J. Differential Geom. **32** (1990), 349–381.
- [14] D. GILBARG and D. S. TRUDINGER, “Elliptic Partial Differential Equations of Second Order”, 2nd, Vol. 224, Grundlehren der mathematischen Wissenschaften, Springer-Verlag, 1983.
- [15] R. E. GREENE and H. WU, *Lipschitz convergence of Riemannian manifolds*, Pacific J. Math. **131** (1988), 119–141.
- [16] R. S. HAMILTON, *Three manifolds with positive Ricci curvature*, J. Differential Geom. **17** (1982), 255–306.
- [17] R. S. HAMILTON, *Four-manifolds with positive curvature operator*, J. Differential Geom. **24** (1986), 153–179.
- [18] R. S. HAMILTON, *A compactness property for solutions of the Ricci flow*, Amer. J. Math. **117** (1995), 545–572.
- [19] R. S. HAMILTON, *The formation of singularities in the Ricci flow*, Surv. Differ. Geom. **2** (1995), 7–136.
- [20] S. HUANG and L.-F. TAM, *Kähler-Ricci flow with unbounded curvature*, Amer. J. Math. **140** (2018), 189–220.
- [21] B. KOTSCHWAR, O. MUNTEANU and J. WANG, *A local curvature estimate for the Ricci flow*, J. Func. Anal. **271** (2016), 2604–2630.
- [22] P. LI, “Geometric Analysis”, Cambridge Stud. Adv. Math., Vol. 134, Cambridge University Press, 2012.
- [23] N. Q. LE and N. ŠEŠUM, *Remarks on curvature behavior at the first singular time of the Ricci flow*, Pacific J. Math. **255** (2012), 155–175.
- [24] L. MA and L. CHENG, *On the conditions to control curvature tensors of Ricci flow*, Ann. Global Anal. Geom. **37** (2010), 403–411.
- [25] O. MUNTEANU and M.-T. WANG, *The curvature of gradient Ricci solitons*, Math. Res. Lett. **18** (2011), 1051–1069.
- [26] O. MUNTEANU and J. WANG, *Geometry of shrinking Ricci solitons*, Compos. Math. **151** (2015), 2273–2300.
- [27] O. MUNTEANU and J. WANG, *Conical structure for shrinking Ricci solitons*, J. Eur. Math. Soc. (JEMS) **19** (2017), 3377–3390.
- [28] G. PERELMAN, *The entropy formula for the Ricci flow and its geometric applications*, arXiv:math/0211159v1s, 2002.

- [29] P. PETERSEN, “Riemannian Geometry”, Graduate Texts in Mathematics, Vol. 171, Springer-Verlag, 1998.
- [30] W.-X. SHI, *Deforming the metric on complete Riemannian manifolds*, J. Differential Geom. **30** (1989), 223–301.
- [31] M. SIMON, *Ricci flow of almost non-negatively curved three manifolds*, J. Reine Angew. Math. **630** (2009), 177–217.
- [32] N. ŠEŠUM, *Curvature tensor under the Ricci flow*, Amer. J. Math. **127** (2005), 1315–1324.
- [33] B. WANG, *On the conditions to extend Ricci flow*, Int. Math. Res. Not. IMRN **8** (2008), 1–30.
- [34] B. WANG, *On the conditions to extend Ricci flow (II)*, Int. Math. Res. Not. IMRN **14** (2012), 3192–3223.
- [35] G. XU, *Short-time existence of the Ricci flow on noncompact Riemannian manifolds*, Trans. Amer. Math. Soc. **365** (2013), 5605–5654.
- [36] D. YANG, *L^p pinching and compactness theorems for compact Riemannian manifolds*, In: “Séminaire de Théorie Spectrale et Géométrie”, Chambéry-Grenoble, 1987-1988, 81–89. See also the rewritten version: Forum Math., **4** (1992), 323–333.
- [37] R. YE, *Curvature estimates for the Ricci flow I*, Calc. Var. Partial Differential Equations **31** (2008), 417–437.
- [38] Z. ZHANG, *Scalar curvature behavior for finite time singularity of Kähler-Ricci flow*, Michigan Math. J. **59** (2010), 419–433.

Department of Applied Mathematics
National Sun Yat-sen University
Kaohsiung, Taiwan
BabbageTW@gmail.com
chencw@math.nsysu.edu.tw