

A metric approach to a class of doubly nonlinear evolution equations and applications

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Abstract. This paper deals with the analysis of a class of doubly nonlinear evolution equations in the framework of a general metric space. We propose for such equations a suitable metric formulation (which in fact extends the notion of *Curve of Maximal Slope* for gradient flows in metric spaces, see [5]), and prove the existence of solutions for the related Cauchy problem by means of an approximation scheme by time discretization. Then, we apply our results to obtain the existence of solutions to abstract doubly nonlinear equations in reflexive Banach spaces. The metric approach is also exploited to analyze a class of evolution equations in L^1 spaces.

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1. Introduction

Let B be a separable Banach space, T a positive number, and let us consider two proper functionals $\Psi : B \rightarrow (-\infty, +\infty]$ and $\mathcal{E} : [0, T] \times B \rightarrow (-\infty, +\infty]$, such that

$$\begin{aligned} \Psi \text{ is convex and lower semicontinuous, } \quad \Psi(v) \geq \Psi(0) = 0 \quad \forall v \in B, \\ \mathcal{E}(t, \cdot) : B \rightarrow (-\infty, +\infty] \text{ is lower semicontinuous} \quad \text{for a.e. } t \in (0, T). \end{aligned}$$

Hereafter, we shall denote by $\|\cdot\|$ the norm on B and by $\|\cdot\|_*$ the norm on the dual space B' . We consider the abstract doubly nonlinear evolution equation

$$\partial\Psi(u'(t)) + \partial\mathcal{E}(t, u(t)) \ni 0 \quad \text{in } B' \quad \text{a.e. in } (0, T), \quad (\text{DNE})$$

where $\partial\Psi$ denotes the subdifferential in the sense of convex analysis of Ψ , while we provisionally denote by $\partial\mathcal{E}$ a suitable version of the subdifferential of \mathcal{E} with respect to the second variable (in fact, we take $\partial\mathcal{E}$ to be the convex subdifferential

of \mathcal{E} with respect to the variable u if the functional $u \mapsto \mathcal{E}(t, u)$ is convex). Clearly, in the quadratic case $\Psi(u) := \frac{1}{2}\|u\|_B^2$ for all $u \in B$, (DNE) reduces to a gradient flow equation.

This differential inclusion in fact arises in several applicative contexts, ranging, among others, from thermomechanics (where it may be understood as a generalized balance relation, see *e.g.* [25, 43]), to the modeling of rate-independent evolutions. Without going into details, we point out that, within the realm of these applications, the functional Ψ may be interpreted as a dissipation potential, while \mathcal{E} is an energy functional. Indeed, there is nowadays a quite wide literature on the analysis of (DNE), which we briefly review, distinguishing the case in which the functional Ψ has a superlinear growth at infinity from the linear-growth case.

The most general well-posedness results (earlier ones were obtained in [6, 13, 48]), for the Cauchy problem associated with (DNE) in the superlinear case for Ψ date back to the papers [15, 16], along with applications to a broad class of PDE models, for phase transition phenomena, which can be recast in the general form (DNE). In the setting of a Hilbert space in [15], and of a reflexive Banach space in [16], the existence of solutions to (DNE) is proved via approximation by time discretization, and passage to the limit by compactness and monotonicity techniques. In [15, 16], the functional \mathcal{E} takes the form $\mathcal{E}(t, u) := \Phi(u) - \langle \ell(t), u \rangle$ for all $(t, u) \in (0, T) \times B$, Φ being a convex functional, so that the convex subdifferential in (DNE) is given by $\partial\mathcal{E} = \partial\Phi - \ell$. In fact, this crucial convexity assumption allows to exploit maximal monotone operator techniques. We recall that, in the same setting, long-time behavior results for (DNE) have recently been obtained in [46, 47].

In the linear-growth case, equation (DNE) arises in connection with *rate-independent* problems. Indeed, in such situations the dissipation functional Ψ is positively homogeneous of degree 1, whence $\partial\Psi(\lambda v) = \partial\Psi(v)$ for all $\lambda \geq 0$ and $v \in B$. Therefore, a solution to (DNE) remains a solution if the time variable is rescaled, thus modeling phenomena insensitive to changes in the time scale. Rate-independent models indeed occur, for instance, in elastoplasticity [19, 20, 24, 29–32], in damage [39], in the quasistatic evolution of fractures [21, 28], in shape memory alloys [38, 40, 41], and in several other contexts, see the survey [33] and the references therein. Existence, approximation, uniqueness, and regularity of solutions to the Cauchy problem for (DNE) in the rate-independent case have been proved in [35, 42], again in the setting of a reflexive Banach space and of a smooth, convex energy functional \mathcal{E} . However, the aforementioned applications to continuum mechanics problems lead to possibly non smooth and (highly) non convex energy functionals, as well as to ambient spaces which are neither reflexive, nor dual of separable spaces (for example, L^1 spaces for shape memory alloys), or even lack a linear structure (like in the applications to fractures). In fact, the non convexity of \mathcal{E} may be a counterpart of the latter feature, as shown in Section 3.3 later on by the example of a non convex functional defined on a Banach manifold. These considerations have indeed motivated the development of an abstract, energetic formulation of rate-independent problems in [42], which can be in fact given in a purely topological framework, see [28]. We may mention that, in the same spirit, global variational principles for doubly nonlinear evolution equations (both

in the superlinear and in the rate-independent case), have been recently proposed in [34, 49, 51].

However, the analysis of the doubly nonlinear equation (DNE) in the case of a non convex, non smooth energy functional and of a more general ambient space still remains open. In the fully general case, one may indeed face the problem of giving meaning to the pointwise formulation (DNE) itself. For example, if the space B does not enjoy the Radon-Nikodým property (like in the case of L^1 spaces), absolutely continuous curves with values in B need not be a.e. differentiable with respect to the variable t , so that the pointwise time derivative appearing in (DNE) may not be defined. Furthermore, in the absence of a linear structure on the ambient space, the notion of (Gâteaux)-derivative/subdifferential of a functional does not make sense anymore. These drawbacks can be overcome by resorting to suitable *surrogates of derivative notions*, which have been introduced in the realm of *Analysis in Metric Spaces*. In particular, we refer to the notions proposed within the theory of *Curves of Maximal Slope* for gradient flows in metric spaces, which was initiated by E. De Giorgi in the seminal paper [18] and has been subsequently developed in [3, 4, 27] and in the recent monograph [5].

The goal of this paper is to analyze (DNE) in the framework of a *general metric space*. Indeed, we shall provide a suitable *purely metric* formulation of (DNE), in fact adapting the notion of *Curve of Maximal Slope* to the doubly nonlinear case. Then, we shall prove an existence and approximation result for the related Cauchy problem in the case of a superlinear dissipation functional.

In the forthcoming papers [36,37], we shall instead develop the analysis of rate-independent problems in a metric framework. More precisely, we shall study rate-independent metric evolutions as the vanishing viscosity limit of doubly nonlinear metric evolutions driven by a superlinear dissipation. Let us point out that this asymptotic analysis has been recently addressed in the paper [22], for general rate-independent problems in a finite-dimensional framework, as well as in [20], in the more specific case of quasistatic evolutions in plasticity with softening.

The metric formulation

For simplicity, we introduce the metric formulation of equation (DNE) when the functional \mathcal{E} is independent of the t variable, postponing the general discussion to Section 2.4. In order to give some insight into the metric approach, we first develop some heuristic calculations in a smooth case and with an ambient Banach space.

Hence, we suppose that $\Psi \in C^1(B)$, that its Fenchel-Moreau conjugate Ψ^* is in $C^1(B')$ too, and that $\mathcal{E} \in C^1(B)$ (nevertheless, we do not require \mathcal{E} to be convex). Under these smoothness assumptions,

$$\begin{aligned} \partial\Psi(u) &= \{D\Psi(u)\}, & \partial\mathcal{E}(u) &= \{D\mathcal{E}(u)\} & \text{for all } u \in B, \\ \partial\Psi^*(v) &= \{D\Psi^*(v)\} & & & \text{for all } v \in B'. \end{aligned}$$

Thus, the doubly nonlinear equation (DNE) turns out to be

$$D\Psi(u'(t)) + D\mathcal{E}(u(t)) = 0 \quad \text{for a.e. } t \in (0, T). \quad (1.1)$$

By a convex analysis argument, (1.1) is equivalent to

$$\Psi(u'(t)) + \Psi^*(-D\mathcal{E}(u(t))) \leq \langle -D\mathcal{E}(u(t)), u'(t) \rangle \quad \text{for a.e. } t \in (0, T), \quad (1.2)$$

(where $\langle \cdot, \cdot \rangle$ denotes the duality pairing between B' and B). Let us point out that (1.2) in fact holds as an equality, as the converse inequality is true thanks to the definition of Ψ^* ; however, in view of the metric formulation we are going to introduce later on, we prefer to state (1.2) in this form. Now, taking into account the chain rule formula

$$\langle D\mathcal{E}(u(t)), u'(t) \rangle = \frac{d}{dt}\mathcal{E}(u(t)) \quad \text{for a.e. } t \in (0, T), \quad (1.3)$$

we can equivalently rephrase (1.1) as

$$\frac{d}{dt}\mathcal{E}(u(t)) \leq -\Psi(u'(t)) - \Psi^*(-D\mathcal{E}(u(t))) \quad \text{for a.e. } t \in (0, T), \quad (1.4)$$

which again in fact holds as an equality. To fix ideas, let us choose

$$\begin{aligned} \Psi(u) &:= \frac{1}{p} \|u\|^p \quad \forall u \in B, \quad \text{so that} \\ \Psi^*(v) &:= \frac{1}{q} \|v\|_*^q \quad \forall v \in B', \quad 1 < p < \infty, \quad \frac{1}{p} + \frac{1}{q} = 1. \end{aligned}$$

Then, (1.4) becomes

$$\frac{d}{dt}\mathcal{E}(u(t)) \leq -\frac{1}{p} \|u'(t)\|^p - \frac{1}{q} \| -D\mathcal{E}(u(t)) \|_*^q \quad \text{for a.e. } t \in (0, T).$$

Let us point out that the above formulation highlights the role of the *norms of the derivatives* $u'(t)$ and $-D\mathcal{E}(t, u(t))$, rather than of the derivatives themselves. That is why, (1.4) appears to be a suitable formulation for going over to a purely metric framework, where one may (only) dispose of notions surrogating the norm of the pointwise derivative of a curve, and the norm of the Gâteaux derivative of a functional.

We now briefly recall such notions (referring to [3, 4], [5, Chapter 1], and to the next sections for further details), in the context of a (separable) metric space (X, d) . In this framework, it is possible to define the notion of *absolute continuity* of a curve with values in X , and to prove that, if $u : (0, T) \rightarrow X$ is absolutely continuous, the limit

$$|u'(t)| := \lim_{h \rightarrow 0} \frac{d(u(t), u(t+h))}{h} \quad \text{exists for a.e. } t \in (0, T), \quad (1.5)$$

defining the *metric derivative* of the curve u . It can be readily checked that, if X is a Banach space B and if the absolutely continuous curve $u : (0, T) \rightarrow B$ is a.e. differentiable on $(0, T)$, then

$$|u'(t)| = \|u'(t)\| \quad \text{for a.e. } t \in (0, T). \quad (1.6)$$

Nonetheless, as we are going to see in Section 7, the notion of metric derivative is significant even in spaces like L^1 , in which the link (1.6) between the metric and the pointwise derivatives is no longer available for general absolutely continuous curves.

In the same way, given a functional $\mathcal{E} : X \rightarrow (-\infty, +\infty]$ and a point $u \in \text{dom}(\mathcal{E})$, following [18] we define the (*local*) *slope* of \mathcal{E} at u as

$$|\partial\mathcal{E}|(u) := \limsup_{v \rightarrow u} \frac{(\mathcal{E}(u) - \mathcal{E}(v))^+}{d(u, v)}. \tag{1.7}$$

Again, it can be shown that, in the Banach space case,

$$\begin{aligned} &\text{if } \mathcal{E} : B \rightarrow (-\infty, +\infty] \text{ is (Fréchet) differentiable at } u \in \text{dom}(\mathcal{E}), \\ &\text{then } |\partial\mathcal{E}|(u) = \|\mathcal{D}\mathcal{E}(u)\|_*. \end{aligned} \tag{1.8}$$

More in general, if \mathcal{E} is convex, then $|\partial\mathcal{E}|$ is related to the (convex) subdifferential $\partial\mathcal{E}$ of \mathcal{E} by

$$|\partial\mathcal{E}|(u) = \min \{ \|\xi\|_* : \xi \in \partial\mathcal{E}(u) \} \quad \forall u \in \text{dom}(\partial\mathcal{E}). \tag{1.9}$$

The chain rule formula (1.3) translates in the metric setting as

$$\begin{aligned} &\frac{d}{dt}\mathcal{E}(u(t)) \geq -|u'(t)| \cdot |\partial\mathcal{E}|(u(t)) \quad \text{for a.e. } t \in (0, T) \\ &\text{for any absolutely continuous curve } u : (0, T) \rightarrow X. \end{aligned} \tag{1.10}$$

We remark that, in the case of a smooth functional $\mathcal{E} : B \rightarrow (-\infty, +\infty]$, the above chain rule inequality results from (1.3), (1.8), and the Cauchy-Schwarz inequality; we have the same interpretation in the case of a convex functional as well, due to (1.9) and the well-known chain rule for the subdifferential in the sense of convex analysis. We refer to Section 2.4 for a detailed discussion of the chain rule (1.10) in the case of a time-dependent functional.

We are now in the position of stating the metric analog of (1.4), of course replacing the derivatives of the curve and of the functional with the metric derivative (1.5) and the local slope (1.7). Since we are now dealing with *scalar notions*, the role of the dissipation Ψ shall be played by a function

$$\begin{aligned} &\psi : [0, +\infty) \rightarrow [0, +\infty), \quad \text{convex and lower semicontinuous,} \\ &\text{with } \psi(0) = 0 \text{ and } \lim_{x \rightarrow +\infty} \frac{\psi(x)}{x} = +\infty. \end{aligned} \tag{1.11}$$

Hence, supposing that the functional $\mathcal{E} : X \rightarrow (-\infty, +\infty]$ complies with the chain rule (1.10), we say that an absolutely continuous curve

$$\begin{aligned} &u : (0, T) \rightarrow X \text{ satisfies the } \textit{metric formulation} \text{ of (DNE) if} \\ &\text{the map } t \in (0, T) \mapsto \mathcal{E}(u(t)) \text{ is absolutely continuous and} \\ &\frac{d}{dt}\mathcal{E}(u(t)) \leq -\psi(|u'(t)|) - \psi^*(|\partial\mathcal{E}|(u(t))) \quad \text{for a.e. } t \in (0, T). \end{aligned} \tag{1.12}$$

It can be easily checked that, when $\psi(x) = \frac{1}{2}x^2$ for all $x \in [0, +\infty)$, the above formulation coincides with the metric formulation of gradient flows, see [4, 5, 18].

The main result of this paper (Theorem 3.5 later on) states the existence of absolutely continuous curves complying with the above metric formulation, supplemented by an initial condition. The proof is performed by passing to the limit in an approximation scheme based on time discretization (see Section 3.1). The *variational* scheme yielding the approximate solutions is indeed the metric analog of the implicit Euler scheme used for doubly nonlinear evolution equations in Banach spaces (see [15, 16, 42]). As a matter of fact, such a scheme has been proposed in [4, 17] as a possible way to approximate gradient flows in metric spaces, in the framework of the theory of *Minimizing Movements*. Exploiting some technical tools of this theory, we have been able to show that the approximate solutions converge to a curve solving the Cauchy problem for (1.12). Without going into many details, let us point out that the whole procedure works out under some lower semicontinuity and coercivity assumptions on \mathcal{E} (which substantially enable to carry out the approximation scheme and to obtain compactness of the approximate solutions), joint with the lower semicontinuity of the map $u \mapsto |\partial\mathcal{E}|(u)$ and the chain rule (1.10).

Applications: the reflexive case

The main applications of our metric approach are to (a class of) doubly nonlinear evolution equations of the form

$$\partial\Psi(u(t), u'(t)) + \partial\mathcal{E}(t, u(t)) \ni 0 \quad \text{in } B' \quad \text{for a.e. } t \in (0, T), \quad (1.13)$$

in the setting of

a separable reflexive Banach space B ,

the functional Ψ having a superlinear growth with respect to the second variable. Existence results for a class of equations of the type (1.13) (which are often called *quasivariational* due to the dependence of the dissipation functional on the state variable u), have been recently obtained in the papers [7, 8] for a superlinear dissipation, while the quasivariational rate-independent case has been analyzed in [35]. In fact, in this paper we are able to deal with dissipation functionals in (1.13) of the form

$$\Psi(u, v) := \psi(\|v\|_u) \quad \forall u, v \in B,$$

where ψ is as in (1.11) and

$\{\|\cdot\|_u\}_{u \in B}$ is a family of norms on B , inducing the *Finsler distance*

$$d(v, w) := \inf \left\{ \int_0^1 \|u'(t)\|_{u(t)} dt : u : [0, 1] \rightarrow B, \quad u(0) = v, \quad u(1) = w \right\} \quad \forall v, w \in B. \quad (1.14)$$

In the setting of the *metric space* (B, d) , it is possible to prove that relation (1.6) between the metric and the pointwise derivative of an absolutely continuous curve still holds in a suitable form (see Section 6). Likewise, relations (1.8)–(1.9) between the slope and the (sub-)differential of \mathcal{E} carry over to this Finsler setting if \mathcal{E} is, for instance, a λ -convex or a C^1 perturbation of a convex functional. As a result, every absolutely continuous curve fulfilling the metric formulation (1.12) is in fact a solution of the pointwise differential inclusion (1.13). Thus, our main metric result, Theorem 3.5, yields the existence of absolutely continuous curves solving the Cauchy problem related to (1.13), *cf.* Theorem 8.3 later on. A typical parabolic evolution equation which can be rephrased in the abstract form (1.13), with $B = L^p(\Omega)$, is the following generalized Allen-Cahn equation

$$\alpha(u, u_t) |u_t|^{p-2} u_t - \Delta u + u^3 - u = h \quad \text{a.e. in } \Omega \times (0, T), \tag{1.15}$$

u_t denoting the partial time derivative of u . Here, $p \geq 1$, Ω is a bounded domain in \mathbb{R}^d , $d \geq 1$, $\alpha : \mathbb{R}^2 \rightarrow (0, +\infty)$ a continuous function, bounded from below and from above, Δ is the Laplace operator, and $h : \Omega \times (0, T) \rightarrow \mathbb{R}$ some source term. In fact, (1.15) is the prototype of the parabolic doubly nonlinear equations we shall address in Section 8.2. More precisely, we shall deduce from Theorem 8.3 the existence of solutions to a suitable initial-boundary value problem for (a generalization of) (1.15).

Applications: the L^1 case

We shall also apply our metric approach to the analysis of (doubly nonlinear) metric evolutions in the metric space $L^1(\Omega)$, with the distance induced by the $L^1(\Omega)$ -norm. As already mentioned, absolutely continuous curves on a time interval $(0, T)$ with values in $L^1(\Omega)$ are not, in general, a.e. differentiable on $(0, T)$, so that the metric formulation (1.12) does not lead to a pointwise formulation any more. Hence, in Section 7 we shall focus on purely metric evolutions only, in the case of the dissipation functional

$$\psi(x) := \frac{1}{2} x^2 \quad \forall x \geq 0. \tag{1.16}$$

In fact, in Section 7.2 we shall analyze the evolution driven in $L^1(\Omega)$, by the quadratic ψ (1.16) and by an energy functional of Ginzburg-Landau type, and prove an existence result (Theorem 7.5). However, in Section 7.1 we shall preliminarily compare the metric and the pointwise formulations on some simpler examples. For instance, we shall consider, in the case $\Omega = (0, 1)$, the quadratic energy functional $\mathcal{E} : L^1(0, 1) \rightarrow [0, +\infty]$

$$\mathcal{E}(u) := \begin{cases} \frac{1}{2} \int_0^1 u^2(x) \, dx & \text{if } u \in L^2(0, 1), \\ +\infty & \text{otherwise} \end{cases} \quad \forall u \in L^1(0, 1). \tag{1.17}$$

It can be checked that the local slope of \mathcal{E} in the metric space $L^1(0, 1)$ is

$$|\partial\mathcal{E}|(u) = \begin{cases} \|u\|_{L^\infty(0,1)} & \text{if } u \in L^\infty(0, 1), \\ +\infty & \text{otherwise} \end{cases} \quad \forall u \in L^2(0, 1).$$

Hence, an absolutely continuous curve $u : (0, T) \rightarrow L^1(0, 1)$ fulfills the metric formulation (1.12) in $L^1(0, 1)$, with the choices (1.16)–(1.17), if

$$\begin{aligned} \text{the map } t \in (0, T) \mapsto \frac{1}{2} \int_0^1 u^2(x, t) \, dx \text{ is absolutely continuous and} \\ \frac{d}{dt} \left(\int_0^1 u^2(x, t) \, dx \right) \leq -|u'(t)|^2 - \|u(t)\|_{L^\infty(0,1)}^2 \quad \text{for a.e. } t \in (0, T). \end{aligned} \quad (1.18)$$

On the other hand, the evolution equation corresponding to (1.18) is (DNE), driven by the dissipation potential

$$\Psi(u) := \frac{1}{2} \|u\|_1^2 \quad \forall u \in L^1(\Omega) \quad (1.19)$$

and by the energy functional \mathcal{E} (1.17), namely

$$\|u_t(t)\|_1 \text{Sign}(u_t(x, t)) + u(x, t) \ni 0 \quad \text{for a.e. } (x, t) \in (0, 1) \times (0, T), \quad (1.20)$$

where we denote by Sign the multivalued operator

$$\text{Sign}(r) := \begin{cases} 1 & \text{if } r > 0, \\ [-1, 1] & \text{if } r = 0, \\ -1 & \text{if } r < 0 \end{cases}.$$

As a matter of fact, in Section 7.1, we shall calculate an explicit solution of (the Cauchy problem for) (1.20) and show that it also fulfills the metric formulation (1.18).

Plan of the paper

In Section 2 we fix the metric setup in which we are going to develop our theory, and accordingly give the preliminary definitions of *metric derivative*, *slope*, and *chain rule condition*. In fact, we extend these notions to the framework of a *non-symmetric* distance Δ on the space X , and we also allow Δ to take value $+\infty$. Further, besides the topology induced by Δ , we are also going to deal with another topology σ on X , possibly weaker, which mimics the role of the weak topology in the Banach space case. Section 3 is devoted to the construction of the approximation scheme for (the Cauchy problem related to) (1.12), and to the statement of our existence and approximation Theorem 3.5. Subsequently, we illustrate such

result on the simple example of a time-independent functional defined on an infinite dimensional Banach manifold. The proof of Theorem 3.5 is carried out in several steps in Section 4. Starting from Section 5, we develop the main applications of our results to the Banach space setting. Indeed, Sections 5 and 6 are devoted to preliminaries, the former in the setting of a separable Banach space, and the latter of a separable *reflexive* Banach space, endowed with a Finsler (asymmetric) distance induced by a family of sublinear functionals (in fact, a generalization of the setup (1.14)). Throughout these sections, we investigate the link between slopes and subdifferentials, and prove (a version of) formula (1.9) for a broad class of functionals, encompassing λ -convex functionals and C^1 -perturbations of convex functionals. We show that these functionals also comply with the chain rule (1.10) in the general Banach space case. Moreover, we provide some technical results enabling to switch from the metric formulation (1.12) back to the pointwise formulation (1.13) in the Finsler, reflexive case. Building on the material developed in Section 5, in Section 7 we investigate metric evolutions in L^1 spaces and also provide some examples with explicit computations of the *metric solution*. Finally, on the basis of Section 6, in Section 8 we develop the aforementioned applications first in the setting of a general *reflexive* Banach space, with a Finsler asymmetric distance, secondly in the space $L^p(\Omega)$, $1 < p < \infty$.

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Part I: the metric theory

2. The metric setup

2.1. Asymmetric distances and metric derivatives

General assumptions

In a

$$\text{Hausdorff topological space } (X, \sigma), \quad (2.1)$$

we are given a *reference point* $x_o \in X$ and

a possibly non symmetric (asymmetric) distance $\Delta : X \times X \rightarrow [0, +\infty]$, fulfilling

$$\begin{aligned} \Delta(u, v) = 0 &\Leftrightarrow u = v \quad \forall u, v \in X, \\ \Delta(u, v) &\leq \Delta(u, w) + \Delta(w, v) \quad \forall u, v, w \in X, \end{aligned} \quad (2.2)$$

We set

$$\delta(u, v) := \min [\Delta(u, v), \Delta(v, u)], \quad X_u := \{v \in X : \Delta(u, v) < +\infty\}, \quad X_0 := X_{x_o}. \quad (2.3)$$

Observe that we could always assume that Δ is finite, by restricting our discussion to the space X_0 ; nevertheless, sometimes it could be useful to allow a more flexible choice of the reference point x_o .

Remark 2.1. A typical non-symmetric distance Δ allowed to take the value $+\infty$ is defined on the space $X = L^1(\Omega)$, Ω being a measurable subset of R^d , by

$$\Delta(u, v) = \begin{cases} \|u - v\|_{L^1} & \text{if } u \geq v \text{ a.e. in } \Omega, \\ +\infty & \text{else} \end{cases} \quad \forall u, v \in L^1(\Omega).$$

Indeed, this example is relevant within applications to damage problems, see [39].

Metric Δ -derivatives

It is easy to extend the notion of *metric derivative* (see [3]) of an absolutely continuous curve in X to a possibly nonsymmetric setting.

First, for $1 \leq p \leq +\infty$ we define

$$\begin{aligned} &\text{AC}^p(a, b; X) \\ &:= \left\{ v : (a, b) \rightarrow X : \exists m \in L^p(a, b) \text{ s.t. } \Delta(v(s), v(t)) \leq \int_s^t m(r) dr \right\}, \end{aligned} \quad (2.4)$$

denoting by $\text{AC}(a, b; X)$ the space $\text{AC}^1(a, b; X)$. Note that, if one disposes of a distance d on the ambient space X fulfilling

$$\exists \kappa_1, \kappa_2 > 0 : \quad \kappa_1 d(u, v) \leq \delta(u, v) \leq \kappa_2 d(u, v) \quad \forall u, v \in X.$$

then $AC^p(a, b; X)$ is included in the usual space of absolutely continuous curves in the metric space (X, d) (see [3]).

The following result is the natural extension of [5, Theorem 1.1.2].

Proposition 2.2. *For any $v \in AC^p(a, b; X)$, $1 \leq p \leq +\infty$, the limits*

$$|v'|^+(t) := \liminf_{h \downarrow 0} \frac{\Delta(v(t), v(t+h))}{h} = \liminf_{h \downarrow 0} \frac{\Delta(v(t-h), v(t))}{h} \quad (2.5)$$

exist and are equal for a.e. $t \in (a, b)$; the function $|v'|$ is in $L^p(a, b)$ and fulfills

$$\Delta(v(s), v(t)) \leq \int_s^t |v'|^+(r) dr \quad \forall a < s \leq t < b. \quad (2.6)$$

Furthermore,

$$|v'|^+(t) \leq m(t) \quad \text{for a.e. } t \in (a, b) \quad (2.7)$$

for any function $m \in L^p(a, b)$ fulfilling

$$\Delta(v(s), v(t)) \leq \int_s^t m(r) dr \quad \forall a < s \leq t < b. \quad (2.8)$$

Proof. Let us fix $v \in AC^p(a, b; X)$ and let $m \in L^p(a, b)$ fulfill (2.8). Let us introduce for any $s \in (a, b)$ the function $l_s : (a, b) \rightarrow [0, +\infty)$ by

$$l_s(t) := \Delta(v(s), v(t)) \quad \forall t \in (a, b).$$

By the definition (2.4) of $AC^p(a, b; X)$, we get the following inequality

$$(l_s(t_2) - l_s(t_1))^+ \leq \Delta(v(t_1), v(t_2)) \leq \int_{t_1}^{t_2} m(r) dr \quad \forall a < t_1 \leq t_2 < b, \quad (2.9)$$

whence we deduce that the map $t \mapsto g_s(t) := l_s(t) - \int_a^t m(r) dr$ is non increasing on (a, b) , in particular a.e. differentiable. Moreover, from (2.9) we get

$$(l'_s(t))^+ \leq \ell(t) := \liminf_{h \downarrow 0} \frac{\Delta(v(t), v(t+h))}{h} \quad \text{for a.e. } t \in (a, b). \quad (2.10)$$

Note that ℓ is a measurable positive function on (a, b) , fulfilling

$$0 \leq \ell(t) \leq \liminf_{h \downarrow 0} \frac{1}{h} \int_t^{t+h} m(r) dr = m(t) \quad \text{for a.e. } t \in (a, b). \quad (2.11)$$

Thus, $\ell \in L^p(a, b)$; moreover, since $l_s(t) = \int_a^t m(r) dr + g_s(t)$ and g is non increasing, the singular part of the distributional derivative of l_s is a non positive measure and therefore (2.10) yields

$$\Delta(v(s), v(t)) = l_s(t) \leq \int_s^t (l'_s(r))^+ dr \leq \int_s^t \ell(r) dr \quad \forall a < s \leq t < b. \quad (2.12)$$

Further, let us consider the measurable function $\tilde{\ell} : (a, b) \rightarrow [0, +\infty)$ defined by

$$\tilde{\ell}(t) := \limsup_{h \downarrow 0} \frac{\Delta(v(t), v(t+h))}{h} \quad \forall t \in (a, b).$$

Arguing as in (2.10), we deduce from (2.8) that

$$\tilde{\ell}(t) \leq \tilde{m}(t) \quad \text{for a.e. } t \in (a, b) \quad (2.13)$$

for any $\tilde{m} \in L^p(a, b)$ for which inequality (2.8) holds. Thus, due to (2.12) we find

$$\tilde{\ell}(t) \leq \ell(t), \quad \text{hence} \quad \exists |v'| (t) := \lim_{h \downarrow 0} \frac{\Delta(v(t), v(t+h))}{h} \quad \text{for a.e. } t \in (a, b),$$

and $|v'| (t) \in L^p(a, b)$ by (2.11). Moreover, (2.12) yields (2.6). We have thus proved the first part of the statement. The second one follows from (2.13).

Finally, the existence of the second limit of (2.5) follows from the same argument, applied to the reversed curve $\hat{v}(t) := v(a+b-t)$ and to the reversed distance $\hat{\Delta}(u, v) := \Delta(v, u)$. In particular

$$\begin{aligned} \Delta(v(s), v(t)) &= \hat{\Delta}(\hat{v}(a+b-t), \hat{v}(a+b-s)) \leq \int_{a+b-t}^{a+b-s} |\hat{v}'|(r) \, dr \\ &= \int_s^t |\hat{v}'|(a+b-r) \, dr. \end{aligned} \quad (2.14)$$

By the minimality property (2.7) (applied to v and \hat{v}) we get

$$|v'| (t) = |\hat{v}'|(a+b-t) \quad \text{for a.e. } t \in (a, b), \quad (2.15)$$

which yields the identity between the two limits in (2.5). \square

2.2. Δ -slopes

In the setup specified by (2.1)-(2.2), let $\mathcal{E} : X \rightarrow (-\infty, +\infty]$ be a functional with proper domain $E = \text{dom}(\mathcal{E}) = \{u \in X : \mathcal{E}(u) < +\infty\}$. Hereafter, we shall suppose that

$$\mathcal{E} \text{ is } \sigma\text{-sequentially lower semicontinuous.} \quad (2.16)$$

We now introduce the notion of local and relaxed slope in the framework of the asymmetric distance Δ : the following definition mimics in an obvious way the usual definitions of slope given in the setting of a symmetric distance, for which we refer to [3, 5].

Definition 2.3. The Δ -local slope of the functional \mathcal{E} at a point $u \in \text{dom}(\mathcal{E})$ is

$$|\partial \mathcal{E}|(u) := \limsup_{\Delta(u, v) \rightarrow 0} \frac{(\mathcal{E}(u) - \mathcal{E}(v))^+}{\Delta(u, v)}. \quad (2.17)$$

The Δ -relaxed slope $|\partial^- \mathcal{E}|$ of \mathcal{E} at a point $u \in \text{dom}(\mathcal{E}) \cap X_0$ is defined by

$$|\partial^- \mathcal{E}|(u) := \inf \left\{ \liminf_{n \uparrow \infty} |\partial \mathcal{E}|(u_n) : u_n \xrightarrow{\sigma} u, \sup\{\Delta(x_o, u_n), \mathcal{E}(u_n)\} < +\infty \right\}. \tag{2.18}$$

Note that if $D \cap X_u = \{u\}$ then $|\partial \mathcal{E}|(u) = 0$; $|\partial^- \mathcal{E}|$ is (a version of) the (sequential) lower semicontinuous envelope of $|\partial \mathcal{E}|$ with respect to the topology σ , along sequences in X_0 of bounded energy and bounded distance with respect to x_o .

2.3. Time dependent families of energy functionals

In this paper we deal with families of time-dependent functionals $\mathcal{E}_t: X \rightarrow (-\infty, +\infty]$, $t \in [0, T]$. In order to avoid further technical difficulties, we will only consider a quite “regular” dependence with respect to time: we thus assume that the proper domain of \mathcal{E}_t is fixed, *i.e.*

$$D := \text{dom}(\mathcal{E}_t) \quad \forall t \in [0, T], \quad \text{and we set} \quad D_0 := D \cap X_0. \tag{2.19a}$$

We also suppose that the functionals are uniformly bounded from below, letting

$$-C_0 := \inf_{t \in [0, T], v \in D} \mathcal{E}_t(v) > -\infty, \tag{2.19b}$$

and that

$$\forall v \in D \text{ the function } t \mapsto \mathcal{E}_t(v) \text{ is differentiable in } [0, T], \text{ with derivative } \partial_t \mathcal{E}_t(v) \tag{2.19c}$$

which satisfies

$$|\partial_t \mathcal{E}_t(v)| \leq C_1(\mathcal{E}_t(v) + \Delta(x_o, v) + 2C_0) \quad \forall t \in [0, T], v \in D_0 \tag{2.19d}$$

for a suitable constant $C_1 \geq 0$.

Remark 2.4. Let us point out that (2.19d) (which has been proposed in [33, §3]), and the Gronwall Lemma yield the following estimate

$$\mathcal{E}_t(v) \leq (\mathcal{E}_s(v) + 2C_0 C_1 |t - s| + C_1 \Delta(x_o, v) |t - s|) \exp(C_1 |t - s|) \tag{2.20}$$

$$\forall t, s \in [0, T], v \in D_0.$$

We will often impose some lower semicontinuity-compactness conditions on sequences with equibounded energy \mathcal{E}_t ; thanks to the previous remark, the particular choice of the time t is not relevant, so that we can state our assumptions for a fixed arbitrary time. We thus introduce the auxiliary quantity

$$\mathcal{F}(v) := 2C_0 + \Delta(x_o, v) + \mathcal{E}_0(v) \tag{2.21}$$

and note that we have, for a suitable constant $C > 0$,

$$\begin{aligned} & \frac{1}{C} \sup_{t \in [0, T]} \left(2C_0 + \Delta(x_o, v) + \mathcal{E}_t(v) \right) \\ & \leq \mathcal{F}(v) \leq C \inf_{t \in [0, T]} \left(2C_0 + \Delta(x_o, v) + \mathcal{E}_t(v) \right) \quad \forall v \in D_0. \end{aligned} \tag{2.22}$$

Therefore, the t -energy $\mathcal{E}_t(u_n)$ of a Δ -bounded sequence $\{u_n\} \subset D_0$ remains bounded if and only if $\sup_n \mathcal{F}(u_n) < +\infty$: in this case $\sup_{n \in \mathbb{N}, s \in [0, T]} \mathcal{E}_s(u_n) < +\infty$.

2.4. The purely metric formulation of the Cauchy Problem (DNE)

Chain rule and curves of maximal slope

It is not difficult to check that if $v : [0, T] \rightarrow D$ is a curve and $\bar{t} \in (0, T)$ is a point such that there exists the metric Δ -derivative $|v'|(\bar{t})$, the map $t \mapsto \mathcal{E}_t(v(t))$ is continuously differentiable at \bar{t} , and $|\partial \mathcal{E}_{\bar{t}}|(v(\bar{t})) < +\infty$, then

$$\left. \frac{d}{dt} \mathcal{E}_t(v(t)) \right|_{t=\bar{t}} \geq \partial_t \mathcal{E}_{\bar{t}}(v(\bar{t})) - |v'|(\bar{t}) \cdot |\partial \mathcal{E}_{\bar{t}}|(v(\bar{t})). \tag{2.23}$$

In this paper we are interested in finding curves of *maximal slope*, i.e. attaining equality in (2.23):

$$\left. \frac{d}{dt} \mathcal{E}_t(v(t)) \right|_{t=\bar{t}} = \partial_t \mathcal{E}_{\bar{t}}(v(\bar{t})) - |v'|(\bar{t}) \cdot |\partial \mathcal{E}_{\bar{t}}|(v(\bar{t})). \tag{2.24}$$

In a linear Euclidean framework, this would be equivalent to imposing that the velocity vector and the gradient of the functional \mathcal{E}_t have opposite directions at each time. Of course, we should complement this condition with a relation between their moduli of the type

$$|\partial \mathcal{E}_{\bar{t}}|(v(\bar{t})) = h(|v'|(\bar{t})), \tag{2.25}$$

$h : [0, +\infty) \rightarrow [0, +\infty)$ being a continuous, surjective, and increasing map. By introducing its convex primitive function and its Legendre-Fenchel-Moreau transform

$$\psi(x) := \int_0^x h(r) \, dr, \quad \psi^*(y) = \sup_{x \geq 0} xy - \psi(x),$$

and recalling that for arbitrary couples of non negative real numbers $x, y \geq 0$

$$xy \leq \psi(x) + \psi^*(y), \quad y = h(x) = \psi'(x) \Leftrightarrow xy = \psi(x) + \psi^*(y), \tag{2.26}$$

we thus end up with the differential characterization

$$\frac{d}{dt} \mathcal{E}_t(v(t)) = \partial_t \mathcal{E}_t(v(t)) - \psi(|v'|(\bar{t})) - \psi^*(|\partial \mathcal{E}_t|(v(t))), \quad t \in (0, T). \tag{2.27}$$

We may further consider a relaxed version of (2.27): first of all, we would like to replace the slope $|\partial\mathcal{E}_t|$ with its lower semicontinuous envelope $|\partial^-\mathcal{E}_t|$ (2.18), which enjoys better convergence properties. This is meaningful only if $|\partial^-\mathcal{E}_t|$ is strong enough to control the time derivative of the energies \mathcal{E}_t along absolutely continuous curves. We fix this property in the following definition:

Definition 2.5 (Chain rule for the relaxed slope). Let $\mathcal{E}_t, t \in [0, T]$, be a family of functionals fulfilling (2.19a,b,c,d). We say that $|\partial^-\mathcal{E}_t|$ satisfies the *chain rule condition* if for any curve $v \in AC(0, T; X_0)$ with

$$\int_0^T |v'(t) \cdot |\partial^-\mathcal{E}_t|(v(t))| dt < +\infty, \quad \sup_{t \in (0, T)} \mathcal{E}_t(v(t)) < +\infty, \quad (2.28)$$

the map $t \mapsto \mathcal{E}_t(v(t))$ is absolutely continuous, and

$$\frac{d}{dt} \mathcal{E}_t(v(t)) \geq \partial_t \mathcal{E}_t(v(t)) - |v'(t) \cdot |\partial^-\mathcal{E}_t|(v(t))| \quad \text{for a.e. } t \in (0, T). \quad (2.29)$$

We may also drop the continuity assumption on h , by considering monotone surjective graphs instead of maps: in this case, we simply replace the relation $h = \psi'$ with the subdifferential condition $h = \partial\psi$ and (2.25) by

$$|\partial\mathcal{E}_t|(v(t)) \in h(|v'(t)|).$$

We can therefore consider an arbitrary real function

$$\begin{aligned} \psi : [0, +\infty) &\rightarrow [0, +\infty], \quad \text{convex and lower semicontinuous,} \\ \text{with } \psi(0) = 0, \quad \text{superlinear growth } \lim_{x \uparrow +\infty} \frac{\psi(x)}{x} &= +\infty, \quad (2.30) \\ \text{and non empty } \text{int}(\text{dom}(\psi)) &= (0, a), \quad a \in (0, +\infty]. \end{aligned}$$

Collecting all the above remarks, we can now state our metric formulation of (the Cauchy Problem related to) (DNE).

Problem 2.6 (Metric formulation of (DNE)). Suppose that the chain rule condition stated in Definition 2.5 holds true. Given $u_0 \in D_0$, find a curve $u \in AC(0, T; X_0)$ such that

$$u(0) = u_0, \text{ the map } t \mapsto \mathcal{E}_t(u(t)) \text{ is absolutely continuous on } (0, T), \text{ and} \quad (2.31)$$

$$\frac{d}{dt} \mathcal{E}_t(u(t)) \leq \partial_t \mathcal{E}_t(u(t)) - \psi(|u'(t)|) - \psi^*(|\partial^-\mathcal{E}_t|(u(t))) \text{ for a.e. } t \in (0, T). \quad (2.32)$$

For instance, the choice $\psi(x) := x^p/p, x \in [0, +\infty), p \geq 1$, with conjugate $\psi^*(x) = x^{p'}/p', 1/p + 1/p' = 1$, of course fits in this framework. In this case, (2.32) reduces to

$$\frac{d}{dt} \mathcal{E}_t(u(t)) \leq \partial_t \mathcal{E}_t(u(t)) - \frac{|u'|^p(t)}{p} - \frac{|\partial^-\mathcal{E}_t|^{p'}(u(t))}{p'}.$$

Finally, let us point out for later convenience that, by an elementary convex analysis argument, if the chain rule of Definition 2.5 is satisfied, then any absolutely continuous curve fulfilling (2.32) indeed fulfills for a.e. $t \in (0, T)$

$$\begin{aligned} \frac{d}{dt} \mathcal{E}_t(u(t)) - \partial_t \mathcal{E}_t(u(t)) &= -|u'(t)| \partial^- \mathcal{E}_t(u(t)) \\ &= -\psi(|u'(t)|) - \psi^*(|\partial^- \mathcal{E}_t(u(t))|), \end{aligned} \quad (2.33)$$

namely the inequality in (2.32) is equivalent to an equality.

Remark 2.7 (Link with the metric theory of gradient flows.) Let us point out that our metric approach to (DNE) is tightly linked to the general theory developed in [5] (see also the references therein) for gradient flow equations in metric spaces. More precisely, following the terminology of [5, Chapter 1], the chain rule property of Definition 2.5 is (with slight changes) equivalent to requiring $|\partial^- \mathcal{E}|$ to be an *upper gradient*, whereas the metric analog of our definition of solution is the notion of *curve of maximal slope*.

2.5. Topological assumptions

Let us collect here all the topological assumptions relating the asymmetric distance Δ and the functionals ψ and \mathcal{E}_t , $t \in [0, T]$, to the topology σ of X .

Sequential semicontinuity. If $\{u_n\}, \{v_n\}, u, v \in X_0$ satisfy

$$\sup_n (\mathcal{F}(u_n) + \mathcal{F}(v_n)) < +\infty \text{ and } (u_n, v_n) \xrightarrow{\sigma} (u, v),$$

then

$$\liminf_{n \uparrow \infty} \Delta(u_n, v_n) \geq \Delta(u, v), \quad \liminf_{n \uparrow \infty} \mathcal{E}_t(u_n) \geq \mathcal{E}_t(u) \quad \forall t \in [0, T], \quad (2.34)$$

$$\limsup_{n \uparrow \infty} \partial_t \mathcal{E}_t(u_n) \leq \partial_t \mathcal{E}_t(u) \quad \forall t \in [0, T]. \quad (2.35)$$

Strengthened sequential semicontinuity. Further, in the case in which $\partial \psi$ is not single valued (this means that ψ is not differentiable in the interior of its domain, or that (cf. (2.30)) $a < \infty$, $\psi(a) < +\infty$ and $\psi'_-(a) < +\infty$), we also assume that for every sequence $t_n \in [0, T]$, $u_n \in D_0$ such that

$$\sup_n (\mathcal{F}(u_n) + |\partial \mathcal{E}_{t_n}|(u_n)) < +\infty, \quad \Delta(u, u_n) \rightarrow 0, \quad t_n \downarrow t,$$

we have

$$\limsup_{n \uparrow \infty} \frac{\mathcal{E}_{t_n}(u_n) - \mathcal{E}_t(u_n)}{t_n - t} \leq \partial_t \mathcal{E}_t(u). \quad (2.36)$$

Note that (2.36) surely holds if the following slightly stronger version of (2.35) is satisfied

$$\sup_n \mathcal{F}(u_n) < +\infty, \quad \Delta(u, u_n) \rightarrow 0, \quad t_n \downarrow t \Rightarrow \limsup_{n \uparrow \infty} \partial_t \mathcal{E}_{t_n}(u_n) \leq \partial_t \mathcal{E}_t(u). \quad (2.37)$$

Sequential compactness. If a sequence $\{u_n\} \subset X_0$ satisfies $\sup_{n \in \mathbb{N}} \mathcal{F}(u_n) < +\infty$, then

$$\exists u \in X \text{ and a subsequence } \{u_{n_k}\} \sigma\text{-converging to } u. \quad (2.38)$$

A few remarks on the above assumptions are in order.

Remark 2.8 (Topology comparison). Due to (2.34) and (2.38), we have

$$\sup_n \mathcal{F}(u_n) < +\infty, \quad \delta(u_n, u) \rightarrow 0 \quad \Rightarrow \quad u_n \xrightarrow{\sigma} u. \quad (2.39)$$

In fact, any σ -sequential limit point v of u_n (whose existence follows from the compactness assumption) satisfies, by (2.34), $\delta(u, v) \leq \liminf_{n \uparrow +\infty} \delta(u, u_n) = \lim_{n \uparrow +\infty} \delta(u, u_n) = 0$. Thus, v coincides with u .

Remark 2.9 (Δ -completeness of the sublevels of \mathcal{E}). It is not difficult to check that the sublevels of \mathcal{E} satisfies the following completeness property with respect to the asymmetric distance Δ : any sequence $u_n \in X_0$ satisfies

$$\lim_{n \rightarrow \infty} \sup_{m > 0} \Delta(u_n, u_{n+m}) = 0, \quad \sup_n \mathcal{E}(u_n) < +\infty \Rightarrow \exists ! u : u_n \xrightarrow{\sigma} u, \quad \lim_{n \rightarrow \infty} \Delta(u_n, u) = 0. \quad (2.40)$$

3. The main result

We shall construct a solution $u \in AC(0, T; X)$ to Problem 2.6 by passing to the limit in a suitable approximation scheme by time discretization.

In the sequel, we adopt the convention of denoting by the symbols C and C' all the accessory positive constants occurring in the estimates.

3.1. Approximation

We fix a time step $\tau > 0$, to which there corresponds a partition

$$\mathcal{P}_\tau := \{t_0 = 0 < t_1 < \dots < t_n < \dots < t_{N-1} < T \leq t_N\}, \quad t_n := n\tau, \quad N \in \mathbb{N}, \quad (3.1)$$

of the interval $(0, T)$. We consider the following recursive minimization scheme

Problem 3.1 (Variational approximation scheme). Given $U_\tau^0 := u_0$, find $U_\tau^1, \dots, U_\tau^N \in X$ fulfilling

$$U_\tau^n \in J_\tau(t_n, U_\tau^{n-1}) := \operatorname{Argmin}_{u \in X} \left\{ \tau \psi \left(\frac{\Delta(U_\tau^{n-1}, u)}{\tau} \right) + \mathcal{E}_{t_n}(u) \right\}, \quad (3.2)$$

for $n = 1, \dots, N$.

Lemma 3.2. *Under the lower semicontinuity-compactness assumptions (2.19a)–(2.19b) and (2.34)–(2.38) on \mathcal{E} , and the growth-convexity conditions (2.30) on ψ , for all $\tau > 0$ and $u_0 \in \mathbf{D}$ Problem 3.1 admits at least one solution $\{U_\tau^n\}_{n=1}^N$. Further, if $u_0 \in D_0$ then $U_\tau^n \in D_0$ for all $n = 1, \dots, N$.*

The proof is a standard application of the well-known *direct method* in the Calculus of Variations.

Approximate solutions

Let \overline{U}_τ and \underline{U}_τ be, respectively, the left-continuous and right-continuous piecewise constant interpolants of the values $\{U_\tau^n\}_{n=1}^N$ fulfilling $\overline{U}_\tau(t_n) = \underline{U}_\tau(t_n) = U_\tau^n$ for all $n = 1, \dots, N$, i.e.,

$$\overline{U}_\tau(t) = U_\tau^n \quad \forall t \in (t_{n-1}, t_n], \quad \underline{U}_\tau(t) = U_\tau^{n-1} \quad \forall t \in [t_{n-1}, t_n), \quad n = 1, \dots, N. \quad (3.3)$$

Furthermore, let $\bar{t}_\tau, \underline{t}_\tau : [0, T] \rightarrow [0, T]$ be defined by

$$\bar{t}_\tau(0) = \underline{t}_\tau(0) := 0, \quad \bar{t}_\tau(t) := t_k \quad \text{for } t \in (t_{k-1}, t_k], \quad \underline{t}_\tau(t) := t_{k-1} \quad \text{for } t \in [t_{k-1}, t_k). \quad (3.4)$$

Of course, for every $t \in [0, T]$ we have $\bar{t}_\tau(t) \downarrow t$ and $\underline{t}_\tau(t) \uparrow t$ as $\tau \downarrow 0$.

We introduce another family of interpolants, due to E. De Giorgi, between the discrete values U_τ^n .

Definition 3.3 (De Giorgi variational interpolants). We denote by \tilde{U}_τ any interpolant of the discrete values $\{U_\tau^n\}_{n=0}^N$ obtained by solving the problem

$$\begin{cases} \tilde{U}_\tau(0) = u_0, & \text{and, for } t = t_{n-1} + r \in (t_{n-1}, t_n], \\ \tilde{U}_\tau(t) \in J_r(t, U_\tau^{n-1}) := \operatorname{Argmin}_{u \in X} \left\{ r\psi\left(\frac{\Delta(U_\tau^{n-1}, u)}{r}\right) + \mathcal{E}_t(u) \right\}, \end{cases} \quad (3.5)$$

such that the map $t \mapsto \tilde{U}_\tau(t)$ is Lebesgue measurable in $(0, T)$.

Remark 3.4 (Measurability of \tilde{U}_τ). Since the map $s \mapsto J_s(t_{n-1}, U_\tau^{n-1})$ is σ -compactly valued and upper semicontinuous, the existence of a measurable selection $\tilde{U}_\tau(t_{n-1} + r) \in J_r(t_{n-1} + r, U_\tau^{n-1})$, $r \in (t_{n-1}, t_n]$, is ensured by [14, Corollary III.3, Theorem III.6].

Note that when $t = t_n$, the minimization scheme in (3.5) coincides with the one in (3.2), so that we can always assume that

$$\tilde{U}_\tau(t_n) = \underline{U}_\tau(t_n) = \overline{U}_\tau(t_n) = U_\tau^n, \quad \text{for every } n = 1, \dots, N. \quad (3.6)$$

3.2. Statement of the main result

Theorem 3.5 (Main existence and approximation result). *In the metric framework discussed in Sections 2.1 and 2.2, let us suppose that ψ complies with (2.30) and that the family of functionals \mathcal{E}_t , $t \in [0, T]$, satisfies (2.19a)–(2.19d), the topological assumptions (2.34)–(2.38) of Section 2.5, and the chain rule condition of Definition 2.5.*

Then, for any $u_0 \in D_0$ and any sequence $\tau_n \downarrow 0$ as $n \uparrow \infty$, there exists a subsequence (still labeled τ_n) and a curve $u \in AC(0, T; X_0)$ such that

$$\overline{U}_{\tau_n}(t) \xrightarrow{\sigma} u(t), \quad \underline{U}_{\tau_n}(t) \xrightarrow{\sigma} u(t), \quad \tilde{U}_{\tau_n}(t) \xrightarrow{\sigma} u(t) \quad \forall t \in [0, T], \quad (3.7)$$

where

$$u \text{ is a solution to Problem 2.6, thus satisfying also (2.33),} \quad (3.8)$$

and the energy identity

$$\begin{aligned} \int_s^t \psi(|u'(r)|) dr + \int_s^t \psi^*(|\partial^- \mathcal{E}_r|(u(r))) dr + \mathcal{E}_t(u(t)) \\ = \mathcal{E}_s(u(s)) + \int_s^t \partial_t \mathcal{E}_r(u(r)) dr \end{aligned} \quad (3.9)$$

for every $s, t \in [0, T]$. In addition, the following convergences hold as $n \uparrow \infty$

$$\int_0^t \psi \left(\frac{\Delta(\underline{U}_{\tau_n}(r), \overline{U}_{\tau_n}(r))}{\tau_n} \right) dr \longrightarrow \int_0^t \psi(|u'(r)|) dr \quad \forall t \in [0, T], \quad (3.10)$$

$$\int_0^t \psi^*(|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n}(r))) dr \longrightarrow \int_0^t \psi^*(|\partial^- \mathcal{E}_r|(u(r))) dr \quad \forall t \in [0, T], \quad (3.11)$$

$$\mathcal{E}_{\tilde{U}_{\tau_n}(t)}(\overline{U}_{\tau_n}(t)) \rightarrow \mathcal{E}_t(u(t)), \quad \mathcal{E}_t(\tilde{U}_{\tau_n}(t)) \rightarrow \mathcal{E}_t(u(t)) \quad \forall t \in [0, T], \quad (3.12)$$

and for a.e. $t \in (0, T)$

$$\begin{cases} \liminf_{n \uparrow \infty} |\partial \mathcal{E}_t|(\tilde{U}_{\tau_n}(t)) = |\partial^- \mathcal{E}_t|(u(t)) & \text{if } |u'(t)| \neq 0, \\ \liminf_{n \uparrow \infty} \psi^*(|\partial \mathcal{E}_t|(\tilde{U}_{\tau_n}(t))) = \psi^*(|\partial^- \mathcal{E}_t|(u(t))) = 0 & \text{if } |u'(t)| = 0 \end{cases} \quad (3.13)$$

Finally, let

$$\mathcal{J} := \{t \in (0, T) : |u'(t)| \neq 0\}. \quad (3.14)$$

Then,

i) if ψ^* as well has superlinear growth, i.e. $\lim_{x \uparrow +\infty} \frac{\psi^*(x)}{x} = +\infty$, we have the further convergence

$$|\partial \mathcal{E}_t|(\tilde{U}_{\tau_n}) \rightarrow |\partial^- \mathcal{E}_t|(u) \quad \text{in } L^1(\mathcal{J}) \text{ as } n \uparrow \infty; \quad (3.15)$$

ii) in the general case, there exists a non increasing sequence $\{O_n\}_n$ of Borel subsets of $(0, T)$ such that $\cap_n O_n = \emptyset$ and, denoting by I_n the indicator function of the set $(0, T) \setminus O_n$, there holds

$$I_n \cdot |\partial \mathcal{E}_t|(\tilde{U}_{\tau_n}) \rightarrow |\partial^- \mathcal{E}_t|(u) \quad \text{in } L^1(\mathcal{I}) \text{ as } n \uparrow \infty. \quad (3.16)$$

3.3. An example on an infinite Banach manifold

We consider two Hilbert spaces V and H , such that V is densely and compactly embedded in H (we identify $H \equiv H' \subset V'$), and we denote by (\cdot, \cdot) and $\|\cdot\|$ the scalar product and the norm in H and by $\|\cdot\|_V$ the norm in V . We define the metric space (X, Δ) via

$$X = \{u \in H : \|u\| = 1\}, \quad \Delta(u_1, u_2) := \|u_1 - u_2\| \quad \forall u_1, u_2 \in X,$$

and take as σ the topology induced by the distance Δ . We consider a functional $\widehat{\mathcal{E}} \in C^1(V)$ fulfilling

$$\widehat{\mathcal{E}} \text{ is convex and } \exists \Lambda_1, \Lambda_2 > 0 \text{ s.t. } \widehat{\mathcal{E}}(v) \geq \Lambda_1 \|v\|_V^2 - \Lambda_2 \quad \forall v \in V, \quad (3.17)$$

and we define $\mathcal{E} : X \rightarrow (-\infty, +\infty]$ by

$$\mathcal{E}(u) := \begin{cases} \widehat{\mathcal{E}}(u) & \text{for } u \in V \cap X, \\ +\infty & \text{otherwise} \end{cases} \quad \forall u \in X. \quad (3.18)$$

The following results shed light on the local slope of \mathcal{E} and on its chain rule properties.

Lemma 3.6. *Under the above assumptions, we have for all $u \in \text{dom}(\mathcal{E})$*

$$\begin{aligned} |\partial \mathcal{E}|(u) < +\infty &\Leftrightarrow D\widehat{\mathcal{E}}(u) \in H, \quad \text{and in this case} \\ |\partial^- \mathcal{E}|(u) = |\partial \mathcal{E}|(u) &= \|D\widehat{\mathcal{E}}(u) - (D\widehat{\mathcal{E}}(u), u)u\|. \end{aligned} \quad (3.19)$$

Proof. We fix $u \in \text{dom}(\mathcal{E})$ and note that for all $w \in V \setminus \{0\}$ such that $(w, u) = 0$ there exists a curve $\gamma : [-\rho, \rho] \rightarrow X$ with $\gamma \in C^1([-\rho, \rho]; V)$ and $\gamma'(0) = w$. Then,

$$\frac{\mathcal{E}(u) - \mathcal{E}(\gamma(r))}{\Delta(u, \gamma(r))} \rightarrow \frac{D\widehat{\mathcal{E}}(u)[w]}{\|w\|} \quad \text{as } r \rightarrow 0.$$

Being w arbitrary, we infer that

$$\begin{aligned} |\partial \mathcal{E}|(u) &\geq \sup_{v \in V \setminus \{0\}, (v, u) = 0} \frac{D\widehat{\mathcal{E}}(u)[v]}{\|v\|} \geq \sup_{v \in V \setminus \{0\}} \frac{D\widehat{\mathcal{E}}(u)[v] - (D\widehat{\mathcal{E}}(u), u)(v, u)}{\|v\|} \\ &= \|D\widehat{\mathcal{E}}(u) - (D\widehat{\mathcal{E}}(u), u)u\|, \end{aligned} \quad (3.20)$$

where the second inequality follows by writing every $v \in V \setminus \{0\}$ as $v = (v, u)u + w$, and noting that $(w, u) = (v, u) - (v, u)(u, u) = 0$. On the other hand, for $u \in \text{dom}(\mathcal{E})$ and $v \in X$ one has $(\mathcal{E}(u) - \mathcal{E}(v))^+ > 0$ if and only if $v \in X \cap V$. Hence, if $D\widehat{\mathcal{E}}(u) \in H$ we estimate

$$\begin{aligned} \frac{(\mathcal{E}(u) - \mathcal{E}(v))^+}{\|v - u\|} &\leq \frac{\left(D\widehat{\mathcal{E}}(u)[v - u]\right)^+}{\|v - u\|} \\ &\leq \frac{\left(D\widehat{\mathcal{E}}(u)[v - u] - (D\widehat{\mathcal{E}}(u), u)(u, v - u)\right)^+}{\|v - u\|} \\ &\quad + \frac{\left((D\widehat{\mathcal{E}}(u), u)(u, v - u)\right)^+}{\|v - u\|} \\ &\leq \|D\widehat{\mathcal{E}}(u) - (D\widehat{\mathcal{E}}(u), u)u\| \\ &\quad + (D\widehat{\mathcal{E}}(u), u)^+ \frac{1 - (u, v)}{\sqrt{2(1 - (u, v))}}, \end{aligned} \tag{3.21}$$

the first inequality due to the convexity of $\widehat{\mathcal{E}}$ and the last one to the identity $\|v - u\|^2 = 2(1 - (u, v))$, since $\|u\| = \|v\| = 1$. We take the lim sup of (3.21) as $\|v - u\| \rightarrow 0$ and conclude the converse inequality of (3.20). Hence, the formula for $|\partial\mathcal{E}|$ ensues. Using this, it is easy to check that the map $u \mapsto |\partial\mathcal{E}|(u)$ is lower semicontinuous, whence (3.19). \square

Lemma 3.7. *Under the above assumptions, the functional \mathcal{E} defined by (3.18) complies with the chain rule of Definition 2.5.*

Proof. Let us point out that any curve $u \in AC(0, T; X)$ is a.e. differentiable with values in H , so that

$$|u'| (t) = \|u'(t)\| \quad \text{for a.e. } t \in (0, T). \tag{3.22}$$

Now, if u fulfills (2.28), necessarily $u(t) \in V$ (whence $\mathcal{E}(u(t)) = \widehat{\mathcal{E}}(u(t))$) for all $t \in [0, T]$. Besides, the fact that $|\partial\mathcal{E}|(u(t)) < +\infty$ for a.e. $t \in (0, T)$ yields by Lemma 3.6 that $D\widehat{\mathcal{E}}(u(t)) \in H$ for a.e. $t \in (0, T)$. Since $\widehat{\mathcal{E}}$ is smooth on H , it satisfies the chain rule

$$\frac{d}{dt}\mathcal{E}(u(t)) = \frac{d}{dt}\widehat{\mathcal{E}}(u(t)) = (u'(t), D\widehat{\mathcal{E}}(u(t))) \quad \text{for a.e. } t \in (0, T). \tag{3.23}$$

The constraint $\|u(t)\| = 1$ for all $t \in [0, T]$ implies that

$$(u'(t), u(t)) = 0 \quad \text{for a.e. } t \in (0, T). \tag{3.24}$$

Hence, recalling (3.19) and (3.22), we deduce that

$$\frac{d}{dt} \widehat{\mathcal{E}}(u(t)) = \left(u'(t), D\widehat{\mathcal{E}}(u(t)) - (D\widehat{\mathcal{E}}(u(t)), u(t))u(t) \right) \geq -\|u'(t)\| |\partial\mathcal{E}|(u(t))$$

for a.e. $t \in (0, T)$,

namely the chain rule inequality (2.29). \square

Hence, the metric formulation (2.31)–(2.32) associated with the energy functional \mathcal{E} (3.18) and with the quadratic dissipation $\psi(r) := \frac{1}{2}r^2$ for all $r \geq 0$ reads

$$\begin{aligned} &\text{find } u \in \text{AC}(0, T; X) \text{ s.t. the map } t \in (0, T) \mapsto \mathcal{E}(u(t)) \\ &\quad \text{is absolutely continuous, and} \\ &\frac{d}{dt} \mathcal{E}(u(t)) \leq -\frac{1}{2} \|u'(t)\|^2 - \frac{1}{2} \|D\widehat{\mathcal{E}}(u(t)) - (D\widehat{\mathcal{E}}(u(t)), u(t))u(t)\|^2 \end{aligned} \quad (3.25)$$

for a.e. $t \in (0, T)$.

In view of (3.17), \mathcal{E} complies with the assumptions of our main Theorem 3.5, providing existence and approximation of a solution $u \in \text{AC}(0, T; X)$ to the Cauchy problem for (3.25) for any initial datum $u_0 \in V \cap X$. It follows from the related energy identity (3.9) that u has the further regularity $u \in H^1(0, T; H) \cap L^\infty(0, T; V)$. In fact, using the chain rule (3.23), (3.24), the energy identity (3.9) and the Cauchy-Schwarz inequality we deduce that u solves the gradient flow equation

$$\begin{cases} u'(t) = - \left(D\widehat{\mathcal{E}}(u(t)) - (D\widehat{\mathcal{E}}(u(t)), u(t))u(t) \right) & \text{for a.e. } t \in (0, T), \\ \|u(t)\| = 1 & \forall t \in [0, T] \end{cases}.$$

4. Proof of the main result

4.1. Estimates for the (ψ) -Moreau-Yosida approximation

In this section we collect some general properties of the *time-incremental* problem (3.2). Namely, given $r > 0$, $t \in (0, T)$, and $u \in X$, we study the minimization problem

$$\inf_{v \in X} \left\{ r\psi \left(\frac{\Delta(u, v)}{r} \right) + \mathcal{E}_{t+r}(v) \right\}. \quad (4.1)$$

Note that, in the case Δ is a distance on X , $\psi(x) := x^2/2$, and the functional \mathcal{E} does not depend on t , (4.1) actually reduces to

$$\inf_{v \in X} \left\{ \frac{d^2(v, u)}{r} + \mathcal{E}(v) \right\}, \quad (4.2)$$

which is related to the Moreau-Yosida approximation of \mathcal{E} . The properties of the minimization problem (4.2) have been thoroughly studied in [5] (see also [45]). In fact, Lemmas 4.4 and 4.5 below are an extension to our framework of analogous results contained in [5, Chapter 3]. Besides the time dependence of the energy functionals, one of the main difficulties here is given by the general choice of the function ψ : indeed, we neither assume that ψ is strictly convex, nor that it is everywhere differentiable or even everywhere finite on $[0, +\infty)$.

Definition 4.1 (ψ -Moreau-Yosida approximation). For $r > 0$, we consider

$$E_{t,r}(u; v) := r\psi\left(\frac{\Delta(u, v)}{r}\right) + \mathcal{E}_{t+r}(v),$$

and define the ψ -Moreau-Yosida approximation $\mathcal{E}_{t,r}$ of the functionals \mathcal{E} by

$$\mathcal{E}_{t,r}(u) := \inf_{v \in X} E_{t,r}(u; v). \tag{4.3}$$

We also denote by $J_r(t, u)$ the set where the infimum in (4.3) is attained, *i.e.*

$$J_{t,r}(u) := \operatorname{Argmin}_{v \in X} E_{t,r}(u; v). \tag{4.4}$$

Remark 4.2 (Simplifying assumptions). By adding a positive constant to \mathcal{E}_t , we can always assume that $C_0 = -1$ in (2.19b), *i.e.*

$$\inf_{t \in [0, T], v \in D} \mathcal{E}_t(v) \geq 1; \tag{4.5}$$

we can therefore set

$$\mathcal{F}(v) := \Delta(x_o, v) + \mathcal{E}_0(v) \tag{4.6}$$

with

$$\frac{1}{A} \sup_{t \in [0, T]} \left(\Delta(x_o, v) + \mathcal{E}_t(v) \right) \leq \mathcal{F}(v) \leq A \inf_{t \in [0, T]} \left(\Delta(x_o, v) + \mathcal{E}_t(v) \right) \quad \forall v \in D, \tag{4.7}$$

$$|\partial_t \mathcal{E}_t(v)| \leq A \mathcal{F}(v) \quad \forall v \in D, \tag{4.8}$$

$$\mathcal{E}_t(v) \leq (\mathcal{E}_s(v) + C_1 \Delta(x_o, v) |t - s|) \exp(C_1 |t - s|) \quad \forall t, s \in [0, T], v \in D, \tag{4.9}$$

for a suitable constant $A > 0$ (all inequalities being trivial if $v \in D \setminus D_0$).

Remark 4.3 (Elementary properties of ψ). Being 0 a minimum point for ψ , it is immediate to check that ψ is non decreasing on $\operatorname{dom}(\psi)$. We denote by ψ'_- and ψ'_+ respectively the (non decreasing) left and right derivatives of ψ on $D(\psi)$ (we set $\psi'_+(a) = +\infty$), which satisfy

$$\psi'_-(x) \leq \psi'_+(x), \quad \partial \psi(x) = [\psi'_-(x), \psi'_+(x)] \quad \forall x \in \operatorname{dom}(\psi). \tag{4.10}$$

Since ψ has a superlinear growth, the conjugate function ψ^* is finite at each $y \in [0, +\infty)$, non decreasing, and satisfies $\psi^*(0) = 0$.

The following result collects some properties of $\mathcal{E}_{t,r}^{\mathcal{E}}$.

Lemma 4.4. *Under the same assumptions as in Theorem 3.5 and Remark 4.2, there exists a constant $C > 0$ such that for every $t \in [0, T]$, $u \in D_0$ there holds*

$$\mathcal{F}(u_r) \leq C\mathcal{F}(u) \quad \forall 0 < r \leq \min(1, T - t), \quad u_r \in \mathcal{J}_{t,r}(u), \quad (4.11)$$

and

$$\begin{aligned} \mathcal{E}_{t,r_2}^{\mathcal{E}}(u) - C\mathcal{F}(u)r_2 \leq \mathcal{E}_{t,r_1}^{\mathcal{E}}(u) - C\mathcal{F}(u)r_1 \leq \mathcal{E}_t(u) \\ \text{for every } 0 < r_1 < r_2 \leq \min(1, T - t); \end{aligned} \quad (4.12)$$

in particular, the map $r \mapsto \mathcal{E}_{t,r}^{\mathcal{E}}(u)$ is a linear perturbation of a non increasing function and has bounded variation. Moreover,

$$\lim_{r \downarrow 0} \sup_{u_r \in \mathcal{J}_{t,r}(u)} \Delta(u, u_r) = 0, \quad \lim_{r \downarrow 0} \mathcal{E}_{t,r}^{\mathcal{E}}(u) = \mathcal{E}_t(u), \quad (4.13)$$

and

$$|\partial \mathcal{E}_{t+r}^{\mathcal{E}}(u_r)| \leq \psi'_+ \left(\frac{\Delta(u, u_r)}{r} \right) \quad \text{if } u_r \in \mathcal{J}_{t,r}(u) \text{ and } 0 \leq \frac{\Delta(u, u_r)}{r} < a. \quad (4.14)$$

Proof.

Step 1: proof of (4.11). First of all, let us point out that the minimality of u_r and (4.7) yield

$$r\psi \left(\frac{\Delta(u, u_r)}{r} \right) \leq \mathcal{E}_{t+r}(u) \leq A\mathcal{F}(u) \quad \forall u_r \in \mathcal{J}_{t,r}(u). \quad (4.15)$$

Let us now fix $\rho > 0$ so that $\psi^*(\rho) < 1/2$ and therefore, being $r \leq 1$,

$$r\psi \left(\frac{\Delta(u, u_r)}{r} \right) \geq \rho\Delta(u, u_r) - r\psi^*(\rho) \geq \rho\Delta(u, u_r) - 1/2;$$

by the minimality of u_r we thus get for $C := 2A(1 + \rho^{-1})$

$$\begin{aligned} \mathcal{F}(u_r) &\leq C \left(\rho\Delta(u, u_r) - 1/2 + \mathcal{E}_{t+r}(u_r) \right) \leq C \left(r\psi \left(\frac{\Delta(u, u_r)}{r} \right) + \mathcal{E}_{t+r}(u_r) \right) \\ &\leq C\mathcal{E}_{t+r}(u) \leq C A\mathcal{F}(u), \end{aligned}$$

the latter two passages following from (4.15).

Step 2: proof of (4.12). We first observe that, for every $0 < r_1 < r_2$

$$\begin{aligned} \mathbf{E}_{t,r_2}(u; v) - \mathbf{E}_{t,r_1}(u; v) &\leq r_2\psi \left(\frac{\Delta(u, v)}{r_2} \right) - r_1\psi \left(\frac{\Delta(u, v)}{r_1} \right) \\ &\quad + \int_{r_1}^{r_2} \partial_r \mathcal{E}_{t+\theta}(v) \, d\theta \end{aligned} \quad (4.16)$$

$$\leq A(r_2 - r_1)\mathcal{F}(v) \quad \forall v \in D, \quad (4.17)$$

the last passage due to (4.8) and the fact that the map $r \mapsto r\psi(x/r)$ is non increasing. Choosing $v = u_{r_1}$ and recalling that $\mathcal{E}_{t,r_2}^\circ(u) \leq \mathbf{E}_{t,r_2}(u; u_{r_1})$ we get by (4.11)

$$\mathcal{E}_{t,r_2}(u) - \mathcal{E}_{t,r_1}(u) \leq A(r_2 - r_1)\mathcal{F}(u_{r_1}) \leq CA(r_2 - r_1)\mathcal{F}(u).$$

Step 3: proof of (4.13). From (4.15) and the definition of ψ^* we get

$$M\Delta(u, u_r) \leq A\mathcal{F}(u) + r\psi^*(M) \quad \forall M > 0, \forall r \leq T - t, \forall u_r \in J_{t,r}(u).$$

Taking the supremum with respect to u_r and the lim sup as $r \downarrow 0$ we get

$$M \limsup_{r \downarrow 0} \sup_{u_r \in J_{t,r}(u)} \Delta(u, u_r) \leq A\mathcal{F}(u) \quad \forall M > 0,$$

yielding the first limit in (4.13).

To check the second one, we note that, by (4.12), (4.13), (2.20), and the lower semicontinuity of the functional $u \mapsto \mathcal{E}_t(u)$,

$$\mathcal{E}_t(u) \geq \limsup_{r \downarrow 0} \mathcal{E}_{t,r}^\circ(u) \geq \liminf_{r \downarrow 0} \mathcal{E}_{t+r}(u_r) \geq \mathcal{E}_t(u).$$

Step 4: proof of (4.14). We may assume $a < +\infty$, the case $a = +\infty$ being easier to handle. Hence, we fix $r > 0$, $u_r \in J_r(t, u)$ such that $\Delta(u, u_r) < a$, and for simplicity we set $\mathcal{E}(u) := \mathcal{E}_{t+r}(u)$. We also suppose that $|\partial\mathcal{E}|(u_r) > 0$: otherwise, the inequality would be trivial. Note that,

$$|\partial\mathcal{E}|(u_r) = \limsup_{\Delta(u_r, v) \rightarrow 0} \frac{(\mathcal{E}(u_r) - \mathcal{E}(v))^+}{\Delta(u_r, v)} = \limsup_{\Delta(u_r, v) \rightarrow 0, \Delta(u, v) > \Delta(u, u_r)} \frac{(\mathcal{E}(u_r) - \mathcal{E}(v))^+}{\Delta(u_r, v)}.$$

Indeed, since $|\partial\mathcal{E}|(u_r) > 0$, there exists a sequence $\{v_k\}$ with $\Delta(u_r, v_k) \rightarrow 0$ as $k \uparrow \infty$ and $\bar{k} \in \mathbb{N}$ such that

$$|\partial\mathcal{E}|(u_r) = \lim_{k \uparrow +\infty} \frac{(\mathcal{E}(u_r) - \mathcal{E}(v_k))^+}{\Delta(u_r, v_k)}, \quad \text{with } \mathcal{E}(v_k) < \mathcal{E}(u_r), \quad \frac{\Delta(u, v_k)}{r} < a, \quad (4.18)$$

for $k \geq \bar{k}$, the latter inequality following from the fact that $\Delta(u, u_r) < a$ and $\Delta(u_r, v_k) \rightarrow 0$. Hence, $\Delta(u, v_k) > \Delta(u, u_r)$ for all $k \geq \bar{k}$: otherwise, if $\Delta(u, v_k) \leq \Delta(u, u_r)$, the minimization (4.1) would lead to

$$\mathcal{E}(u_r) + r\psi\left(\frac{\Delta(u, u_r)}{r}\right) \leq \mathcal{E}(v_k) + r\psi\left(\frac{\Delta(u, v_k)}{r}\right) \leq \mathcal{E}(v_k) + r\psi\left(\frac{\Delta(u, u_r)}{r}\right),$$

(the second passage by the monotonicity of ψ), contrary to (4.18). Furthermore, for every $k \geq \bar{k}$

$$\begin{aligned} \frac{\mathcal{E}(u_r) - \mathcal{E}(v_k)}{\Delta(u_r, v_k)} &\leq r \frac{\psi\left(\frac{\Delta(u, v_k)}{r}\right) - \psi\left(\frac{\Delta(u, u_r)}{r}\right)}{\Delta(u_r, v_k)} \\ &\leq \frac{\psi\left(\frac{\Delta(u, v_k)}{r}\right) - \psi\left(\frac{\Delta(u, u_r)}{r}\right)}{\frac{\Delta(u, v_k)}{r} - \frac{\Delta(u, u_r)}{r}}, \end{aligned}$$

the first inequality following from (4.1), and the second one by the triangle inequality. Therefore, noting that $0 < \Delta(u, v_k) - \Delta(u, u_r) \leq \Delta(u_r, v_k) \rightarrow 0$, we have

$$\begin{aligned} |\partial \mathcal{E}|(u_r) &= \limsup_{\Delta(u_r, v_k) \rightarrow 0} \frac{(\mathcal{E}(u_r) - \mathcal{E}(v_k))^+}{\Delta(u_r, v_k)} \\ &\leq \liminf_{\Delta(u_r, v_k) \rightarrow 0} \frac{\psi\left(\frac{\Delta(u, v_k)}{r}\right) - \psi\left(\frac{\Delta(u, u_r)}{r}\right)}{\frac{\Delta(u, v_k)}{r} - \frac{\Delta(u, u_r)}{r}} \\ &\leq \limsup_{h \downarrow 0} \frac{\psi\left(\frac{\Delta(u, u_r)}{r} + h\right) - \psi\left(\frac{\Delta(u, u_r)}{r}\right)}{h} = \psi'_+\left(\frac{\Delta(u, u_r)}{r}\right). \quad \square \end{aligned}$$

Before proving the following lemma, which will play a crucial role later on, we recall for the reader's convenience the well-known duality formula relating ψ and ψ^*

$$\psi^*(y) = yx - \psi(x) \quad \forall y \in [\psi'_-(x), \psi'_+(x)]. \quad (4.19)$$

Moreover, in the case in which $D(\psi) = [0, a]$, with $a < +\infty$, and $\ell := \psi'_-(a) < +\infty$, there holds

$$\begin{aligned} \psi^*(y) &\leq \psi^*(\ell) = \ell a - \psi(a) & \forall y \leq \ell, \\ \psi^*(y) &= ya - \psi(a) = \psi^*(\ell) + (y - \ell)a & \forall y > \ell. \end{aligned} \quad (4.20)$$

Indeed, the first inequality follows from the monotonicity of ψ^* ; on the other hand, recalling that $\partial \psi(a) = [\ell, +\infty)$ and that $\partial \psi^* = (\partial \psi)^{-1}$, we conclude that $\partial \psi^*(y) = \{a\}$ for $y > \ell$, whence the second of (4.20).

Lemma 4.5. *Under the same assumptions as in Theorem 3.5, for every $t \in [0, T)$, $u \in D_0$, and for a.e. $r > 0$*

$$\begin{aligned} &\text{the map } r \mapsto \mathcal{E}_{t,r}(u) \text{ is differentiable,} \\ &\psi'_-\left(\frac{\Delta(u, u_r)}{r}\right) < +\infty \text{ at each point } u_r \in J_{t,r}(u), \end{aligned} \quad (4.21)$$

and

$$\frac{d}{dr} \mathcal{E}_{t,r}(u) \leq \partial_t \mathcal{E}_{t+r}(u_r) - \psi^* \left(\psi'_- \left(\frac{\Delta(u, u_r)}{r} \right) \right), \quad (4.22)$$

$$\frac{d}{dr} \mathcal{E}_{t,r}(u) \leq \partial_t \mathcal{E}_{t+r}(u_r) - \psi^* (|\partial \mathcal{E}_{t+r}|(u_r)), \quad (4.23)$$

where we adopt the convention of writing $\psi'_-(0) = 0$. In particular, we have

$$\begin{aligned} r_0 \psi \left(\frac{\Delta(u, u_{r_0})}{r_0} \right) + \int_0^{r_0} \psi^* (|\partial \mathcal{E}_{t+r}|(u_r)) \, dr + \mathcal{E}_{t+r_0}(u_{r_0}) \\ \leq \mathcal{E}_t(u) + \int_0^{r_0} \partial_t \mathcal{E}_{t+r}(u_r) \, dr, \end{aligned} \quad (4.24)$$

for every $0 < r_0 \leq T - t$ and $u_{r_0} \in J_{t,r_0}(u)$.

Proof. Preliminarily, let us point out that (4.16) yields for any $r_1, r_2 > 0$

$$\begin{aligned} \mathcal{E}_{t,r_2}(u) - \mathcal{E}_{t,r_1}(u) &\leq r_2 \psi \left(\frac{\Delta(u, u_{r_1})}{r_2} \right) - r_1 \psi \left(\frac{\Delta(u, u_{r_1})}{r_1} \right) \\ &+ \left(\mathcal{E}_{t+r_2}(u_{r_1}) - \mathcal{E}_{t+r_1}(u_{r_1}) \right). \end{aligned} \quad (4.25)$$

Step 1: proof of (4.22). Since by (4.12) the map $r \mapsto \mathcal{E}_{t,r}(u)$ is a linear perturbation of a monotone map, it is also almost everywhere differentiable on $(0, +\infty)$; let r be a point of differentiability and let us choose $r_1 := r$ and $r_2 := r + h$, $h > 0$, (so that $\Delta(u, u_r)/(r + h) \in D(\psi)$ as well) in (4.25); we also set

$$G(h) := \mathcal{E}_{t,r+h}(u) - \mathcal{E}_{t+r+h}(u_r) \text{ so that } \frac{d}{ds} \mathcal{E}_{t,s}(u) \Big|_{s=r} = \frac{d}{dh} G(h) \Big|_{h=0} - \partial_t \mathcal{E}_{t+r}(u_r).$$

When $\Delta(u, u_r) > 0$ (4.25) yields, with easy calculations,

$$\begin{aligned} \frac{G(h) - G(0)}{h} &\leq \frac{1}{h} \left((r+h) \psi \left(\frac{\Delta(u, u_r)}{r+h} \right) - r \psi \left(\frac{\Delta(u, u_r)}{r} \right) \right) \\ &\leq \psi \left(\frac{\Delta(u, u_r)}{r+h} \right) - \frac{\Delta(u, u_r)}{r+h} \left(\frac{\psi \left(\frac{\Delta(u, u_r)}{r+h} \right) - \psi \left(\frac{\Delta(u, u_r)}{r} \right)}{\frac{\Delta(u, u_r)}{r+h} - \frac{\Delta(u, u_r)}{r}} \right). \end{aligned} \quad (4.26)$$

Letting $h \downarrow 0$, also taking into account that ψ is continuous on $\text{int}(\text{dom}(\psi))$ we have

$$\frac{\psi \left(\frac{\Delta(u, u_r)}{r+h} \right) - \psi \left(\frac{\Delta(u, u_r)}{r} \right)}{\frac{\Delta(u, u_r)}{r+h} - \frac{\Delta(u, u_r)}{r}} \uparrow \psi'_- \left(\frac{\Delta(u, u_r)}{r} \right) \text{ as } h \downarrow 0.$$

Therefore, we infer that

$$G'(0) \leq \psi \left(\frac{\Delta(u, u_r)}{r} \right) - \frac{\Delta(u, u_r)}{r} \psi'_- \left(\frac{\Delta(u, u_r)}{r} \right) = -\psi^* \left(\psi'_- \left(\frac{\Delta(u, u_r)}{r} \right) \right)$$

and the same relation holds even when $\Delta(u, u_r) = 0$, by the convention $\psi'_-(0) = 0$.

Step 2: proof of (4.23). If $\Delta(u, u_r) = 0$, then we may note that $\psi^*(\psi'_+(\Delta(u, u_r)/r)) = \psi^*(\psi'_+(0)) = -\psi(0) = 0$, so that (4.23) follows from (4.14), the monotonicity of ψ^* , and (4.22).

The same argument shows that (4.23) is an immediate consequence of (4.14) and (4.22) when $\partial\psi$ is single valued, since in that case $\psi'_- = \psi'_+$.

In order to prove (4.23) in the general case, we can assume without loss of generality that $|\partial\mathcal{E}_{t+r}|(u_r) > 0$, and that

$$|\partial\mathcal{E}_{t+r}|(u_r) \geq \psi'_- \left(\frac{\Delta(u, u_r)}{r} \right).$$

If not, we would trivially conclude (4.23) from (4.22). On the other hand, by (4.14)

$$|\partial\mathcal{E}_{t+r}|(u_r) \leq \psi'_+ \left(\frac{\Delta(u, u_r)}{r} \right), \quad \text{thus} \quad |\partial\mathcal{E}_{t+r}|(u_r) \in \partial\psi \left(\frac{\Delta(u, u_r)}{r} \right). \quad (4.27)$$

Let us denote by x the number $\frac{\Delta(u, u_r)}{r}$: arguing as in the proof of Lemma 4.4, we can select a sequence $\{v_k\}$ fulfilling

$$\begin{aligned} \Delta(u_r, v_k) &\rightarrow 0 \text{ as } k \uparrow \infty, \quad \Delta(u, u_r) < \Delta(u, v_k), \\ |\partial\mathcal{E}_{t+r}|(u_r) &= \lim_{k \uparrow \infty} \frac{\mathcal{E}_{t+r}(u_r) - \mathcal{E}_{t+r}(v_k)}{\Delta(u_r, v_k)}. \end{aligned} \quad (4.28)$$

We also set

$$r_k := \frac{\Delta(u, v_k)}{x} > \frac{\Delta(u, u_r)}{x} = r,$$

noting that

$$\begin{aligned} r_k \downarrow r \text{ as } k \uparrow \infty, \text{ and} \\ \limsup_{k \uparrow \infty} \frac{\mathcal{E}_{t+r}(u_r) - \mathcal{E}_{t+r}(v_k)}{\Delta(u_r, v_k)} \leq \limsup_{\Delta(u_r, v_k) \rightarrow 0} \frac{\mathcal{E}_{t+r}(u_r) - \mathcal{E}_{t+r}(v_k)}{x(r_k - r)} \end{aligned} \quad (4.29)$$

by the triangle inequality. Therefore,

$$\begin{aligned} \frac{d}{ds} \mathcal{E}_{t,s}(u) \Big|_{s=r} &= \lim_{k \uparrow \infty} \frac{\mathcal{E}_{t,r_k}^e(u) - \mathcal{E}_{t,r}^e(u)}{r_k - r} \\ &\leq \liminf_{k \uparrow \infty} \frac{1}{r_k - r} \left(\mathcal{E}_{t+r_k}(v_k) + r_k \psi \left(\frac{\Delta(u, v_k)}{r_k} \right) - \mathcal{E}_{t+r}(u_r) - r \psi \left(\frac{\Delta(u, u_r)}{r} \right) \right) \\ &= \liminf_{k \uparrow \infty} \frac{1}{r_k - r} \left(\psi(x)(r_k - r) + (\mathcal{E}_{t+r_k}(v_k) - \mathcal{E}_{t+r}(v_k)) + (\mathcal{E}_{t+r}(v_k) - \mathcal{E}_{t+r}(u_r)) \right) \\ &\leq \psi(x) + \limsup_{k \uparrow \infty} \frac{\mathcal{E}_{t+r_k}(v_k) - \mathcal{E}_{t+r}(v_k)}{r_k - r} - \lim_{k \uparrow \infty} \frac{\mathcal{E}_{t+r}(u_r) - \mathcal{E}_{t+r}(v_k)}{r_k - r} \\ &\leq \partial_t \mathcal{E}_{t+r}(u_r) + \psi(x) - x |\partial \mathcal{E}_{t+r}|(u_r) = \partial_t \mathcal{E}_{t+r}(u_r) - \psi^*(|\partial \mathcal{E}_{t+r}|(u_r)), \quad (4.30) \end{aligned}$$

where the fifth passage follows from (2.36), (4.28), and (4.29), whereas the last identity is due to (4.19) and (4.27).

We argue analogously in the case in which $\text{int}(\text{dom}(\psi)) = (0, a)$, with $a < +\infty$, and $\Delta(u, u_r)/r = a$. Indeed, we repeat (4.28)-(4.30), the only difference being that the final identity in (4.30) follows now from (4.20).

Step 3: proof of (4.24). We note that for every $r_0 > 0$ and every (measurable) selection $u_r \in J_r(t, u)$, $r \in (0, r_0]$,

$$\begin{aligned} \psi \left(\frac{\Delta(u, u_{r_0})}{r_0} \right) + \mathcal{E}_{t+r_0}(u_{r_0}) - \mathcal{E}_t(u) &= \mathcal{E}_{t,r_0}^e(u) - \lim_{r \downarrow 0} \mathcal{E}_{t,r}^e(u) \leq \int_0^{r_0} \frac{d}{dr} \mathcal{E}_{t,r}(u) \, dr \\ &\leq \int_0^{r_0} \left(\partial_t \mathcal{E}_{t+r}(u_r) - \psi^*(|\partial \mathcal{E}_{t+r}|(u_r)) \right) \, dr, \end{aligned}$$

where we have used (4.13) in the first passage, the monotonicity (up to a linear perturbation) of $r \mapsto \mathcal{E}_{t,r}^e(u)$ in the second passage and, finally, (4.23). \square

4.2. Estimates for the approximate solutions

A priori estimates

Preliminarily, we recall the following well-known *Discrete Gronwall Lemma*:

Lemma 4.6. *Let B, b , and κ be positive constants with $1 - b \geq \frac{1}{\kappa} > 0$ and let $\{a_n\} \subset [0, +\infty)$ be a sequence satisfying*

$$a_n \leq B + b \sum_{k=1}^n a_k \quad \forall n \in \mathbb{N}.$$

Then, $\{a_n\}$ can be bounded by

$$a_n \leq \kappa B e^{\kappa b n} \quad \forall n \in \mathbb{N}. \quad (4.31)$$

Proposition 4.7 (A priori estimates). *Under the assumptions of Theorem 3.5, for $\tau > 0$ let $\{U_\tau^n\}_{n=1}^N$ be a family of solutions to (3.2), and let \bar{U}_τ , \underline{U}_τ , and \tilde{U}_τ be the interpolants defined by (3.3) and (3.5). Then, the discrete energy inequality*

$$\begin{aligned} \int_{\mathbf{s}_\tau}^{t_\tau} \psi \left(\frac{\Delta(\underline{U}_\tau(r), \bar{U}_\tau(r))}{\tau} \right) dr + \int_{\mathbf{s}_\tau}^{t_\tau} \psi^* (|\partial \mathcal{E}_r|(\tilde{U}_\tau(r))) dr + \mathcal{E}_{t_\tau}(\bar{U}_\tau(t_\tau)) \\ \leq \mathcal{E}_{\mathbf{s}_\tau}(\bar{U}_\tau(\mathbf{s}_\tau)) + \int_{\mathbf{s}_\tau}^{t_\tau} \partial_t \mathcal{E}_r(\tilde{U}_\tau(r)) dr \end{aligned} \quad (4.32)$$

holds for every pair of nodes $\mathbf{s}_\tau < t_\tau \in \mathcal{P}_\tau$. Moreover, there exists a positive constant C such that the following estimates hold for every $\tau > 0$:

$$\int_0^T \psi \left(\frac{\Delta(\underline{U}_\tau(r), \bar{U}_\tau(r))}{\tau} \right) dr \leq C, \quad \int_0^T \psi^* (|\partial \mathcal{E}_r|(\tilde{U}_\tau(r))) dr \leq C, \quad (4.33)$$

$$\mathcal{F}(\bar{U}_\tau(t)) \leq C, \quad \mathcal{F}(\tilde{U}_\tau(t)) \leq C \quad \forall t \in (0, T), \quad (4.34)$$

$$\sup_{t \in (0, T)} \Delta(\underline{U}_\tau(t), \tilde{U}_\tau(t)) = o(1), \quad \sup_{t \in (0, T)} \Delta(\underline{U}_\tau(t), \bar{U}_\tau(t)) = o(1) \text{ as } \tau \downarrow 0. \quad (4.35)$$

Proof. Let t_{j-1}, t_j be two consecutive nodes of the partition \mathcal{P}_τ (cf. (3.1)), and let $t \in (t_{j-1}, t_j]$: referring to the definition (4.3) of the Moreau-Yosida approximation $\mathcal{E}_{t,r}^j$, let us apply inequality (4.24) with the choices $t = t_{j-1}$, $u = U_\tau^{j-1}$, $r_0 = t - t_{j-1}$, $u_{r_0} = \tilde{U}_\tau(t)$, $u_r = \tilde{U}_\tau(r)$ for $r \in (t_{j-1}, t)$. Thus, after changing variable in the two integrals we obtain

$$\begin{aligned} (t - t_{j-1}) \psi \left(\frac{\Delta(U_\tau^{j-1}, \tilde{U}_\tau(t))}{t - t_{j-1}} \right) + \int_{t_{j-1}}^t \psi^* (|\partial \mathcal{E}_r|(\tilde{U}_\tau(r))) dr + \mathcal{E}_t(\tilde{U}_\tau(t)) \\ \leq \mathcal{E}_{t_{j-1}}(U_\tau^{j-1}) + \int_{t_{j-1}}^t \partial_t \mathcal{E}_r(\tilde{U}_\tau(r)) dr \quad \forall t \in (t_{j-1}, t_j]. \end{aligned} \quad (4.36)$$

Writing (4.36) for $t = t_j$, we obtain

$$\begin{aligned} \int_{t_{j-1}}^{t_j} \psi \left(\frac{\Delta(\underline{U}_\tau(r), \bar{U}_\tau(r))}{\tau} \right) dr + \int_{t_{j-1}}^{t_j} \psi^* (|\partial \mathcal{E}_r|(\tilde{U}_\tau(r))) dr + \mathcal{E}_{t_j}(U_\tau^j) \\ \leq \mathcal{E}_{t_{j-1}}(U_\tau^{j-1}) + \int_{t_{j-1}}^{t_j} \partial_t \mathcal{E}_r(\tilde{U}_\tau(r)) dr. \end{aligned} \quad (4.37)$$

Hence, (4.32) follows by adding up the contributions (4.37) on the subintervals of the partition. It follows from the superlinear growth of ψ that there exists a positive

constant C such that

$$\begin{aligned} \int_{t_{j-1}}^{t_j} \psi \left(\frac{\Delta(\underline{U}_\tau(r), \overline{U}_\tau(r))}{\tau} \right) dr &\geq \Delta(U_\tau^{j-1}, U_\tau^j) - C\tau \\ &\geq \Delta(x_o, U_\tau^j) - \Delta(x_o, U_\tau^{j-1}) - C\tau, \end{aligned} \tag{4.38}$$

the last passage following from the triangle inequality. Combining (4.37) and (4.38), recalling that ψ^* is positive (cf. Remark 4.3), summing over the index j , and using (4.7), we obtain

$$\begin{aligned} \frac{1}{A} \mathcal{F}(U_\tau^j) &\leq \Delta(x_o, U_\tau^j) + \mathcal{E}_{t_j}(U_\tau^j) \\ &\leq CT + \Delta(x_o, u_0) + \mathcal{E}_0(u_0) + \int_0^{t_j} \partial_t \mathcal{E}_r(\tilde{U}_\tau(r)) dr \\ &\leq CT + \Delta(x_o, u_0) + \mathcal{E}_0(u_0) + A \int_0^{t_j} \mathcal{F}(\tilde{U}_\tau(r)) dr \\ &\leq CT + \Delta(x_o, u_0) + \mathcal{E}_0(u_0) + AC \int_0^{t_j} \mathcal{F}(\underline{U}_\tau(r)) dr, \end{aligned} \tag{4.39}$$

the third inequality following from (4.8) and the fourth one from (4.11). Therefore, we deduce that

$$\mathcal{F}(U_\tau^j) \leq c_0 + C \sum_{k=1}^j \tau \mathcal{F}(U_\tau^k) \quad \forall j = 1, \dots, N,$$

where the constant c_0 only depends on the initial and the problem data. Then, the discrete Gronwall Lemma 4.6 yields the first estimate in (4.34), and the second one readily follows thanks to (4.11). Recalling (4.8), we also infer that

$$\int_0^{t_j} |\partial_t \mathcal{E}_r(\tilde{U}_\tau(r))| dr \leq C \quad \text{for all } \tau > 0. \tag{4.40}$$

Therefore, summing up over the index j and arguing by comparison in (4.37) we conclude the estimates of (4.33).

Finally, in order to check the first limit in (4.35) (in fact, the second one in (4.35) can be proved in the same way), we start by noting that, from (4.36), the positivity of ψ^* and the previous estimates

$$(t - t_{j-1}) \psi \left(\frac{\Delta(U_\tau^{j-1}, \tilde{U}_\tau(t))}{t - t_{j-1}} \right) \leq C \quad \forall t \in (t_{j-1}, t_j], \quad j = 1, \dots, N.$$

Combining this with the superlinear growth of ψ we obtain that for any $M \geq 0$ there exists $S \geq 0$ fulfilling

$$\Delta(\underline{U}_\tau(t), \tilde{U}_\tau(t)) \leq \frac{C}{M} + (t - t_{j-1}) \frac{S}{M} \leq \frac{C}{M} + \tau \frac{S}{M} \quad \forall t \in (t_{j-1}, t_j], \quad \forall j = 1, \dots, N.$$

Thus, we easily deduce that for any $\varepsilon > 0$ there exist $\tau_0 > 0$ such that for $0 < \tau < \tau_0$

$$\Delta(\underline{U}_\tau(t), \tilde{U}_\tau(t)) \leq \varepsilon \quad \forall t \in (0, T),$$

whence the desired conclusion. \square

4.3. Passage to the limit and proof of existence

The proof of the ensuing Proposition 4.9 is an adaptation of the argument developed for [5, Corollary 3.3.4], and is based on the following version of the Ascoli-Arzelà compactness theorem, proved in [5, Proposition 3.3.1], which for convenience we recall here, in a slightly simplified form.

Proposition 4.8. *Under assumptions (2.1)–(2.2) on the space X , let \mathcal{K} be a σ -sequentially compact subset of X with the following property: for all $\{u_n\}, \{v_n\}, u, v \in \mathcal{K}$,*

$$(u_n, v_n) \xrightarrow{\sigma} (u, v) \Rightarrow \liminf_{n \uparrow \infty} \Delta(u_n, v_n) \geq \Delta(u, v). \quad (4.41)$$

Let $\{u_n\}$ be a sequence of curves $u_n : [0, T] \rightarrow X$ fulfilling

$$u_n(t) \in \mathcal{K} \quad \forall n \in \mathbb{N}, \quad \forall t \in [0, T], \quad (4.42)$$

$$\limsup_{n \uparrow \infty} \Delta(u_n(s), u_n(t)) \leq \omega(s, t) \quad \forall s, t \in [0, T], \quad s < t, \quad (4.43)$$

where $\omega : [0, T] \times [0, T] \rightarrow [0, +\infty)$ is a function such that

$$\lim_{s \uparrow r, t \uparrow r, s < t} \omega(s, t) = 0 \quad \forall r \in [0, T].$$

Then, there exist an increasing subsequence $k \mapsto n_k$ and a σ -continuous curve $u : [0, T] \rightarrow X$ such that

$$u_{n_k}(t) \xrightarrow{\sigma} u(t) \quad \forall t \in [0, T],$$

and the limit curve u satisfies

$$\lim_{r \uparrow s} \Delta(u(r), u(s)) = \lim_{t \downarrow s} \Delta(u(s), u(t)) = 0 \quad \forall s \in (0, T). \quad (4.44)$$

Proposition 4.9 (Compactness of the approximate solutions). *Under the assumptions of Theorem 3.5, given any vanishing sequence $\tau_n \downarrow 0$ of time steps, there exist a subsequence (still labeled τ_n), a limit curve $u \in \text{AC}(0, T; X_0)$, and a function $L \in L^1(0, T)$ such that the following convergences hold as $n \uparrow \infty$*

$$\overline{U}_{\tau_n}(t) \xrightarrow{\sigma} u(t), \quad \underline{U}_{\tau_n}(t) \xrightarrow{\sigma} u(t), \quad \tilde{U}_{\tau_n}(t) \xrightarrow{\sigma} u(t) \quad \forall t \in [0, T], \quad (4.45)$$

$$\liminf_{n \uparrow \infty} \mathcal{E}_t(\tilde{U}_{\tau_n}(t)) \geq \mathcal{E}_t(u(t)), \quad \liminf_{n \uparrow \infty} \mathcal{E}_{\tilde{t}_{\tau_n}(t)}(\overline{U}_{\tau_n}(t)) \geq \mathcal{E}_t(u(t)) \quad \forall t \in [0, T], \quad (4.46)$$

$$\frac{\Delta(\underline{U}_{\tau_n}, \overline{U}_{\tau_n})}{\tau_n} \rightharpoonup L \quad \text{in } L^1(0, T), \quad L(t) \geq |u'(t)| \quad \text{for a.e. } t \in (0, T), \quad (4.47)$$

$$\liminf_{n \uparrow \infty} |\partial \mathcal{E}_t|(\tilde{U}_{\tau_n}(t)) \geq |\partial^- \mathcal{E}_t|(u(t)) \quad \forall t \in [0, T]. \quad (4.48)$$

Proof. It is easy to see that estimate (4.33) and the superlinear growth of ψ entail that the family

$$\left\{ \frac{\Delta(\underline{U}_\tau(r), \overline{U}_\tau(r))}{\tau} \right\}_\tau \text{ is bounded and uniformly integrable in } L^1(0, T).$$

Therefore, the Dunford-Pettis criterion ensures that it is weakly relatively compact in $L^1(0, T)$, whence the first of (4.47).

Exploiting (4.34) and assumption (2.38) on the sublevels of \mathcal{F} , we can apply Proposition 4.8 to the sequence $\{\overline{U}_{\tau_n}\}$, of course with \mathcal{K} as a suitable sublevel of \mathcal{F} (note that (4.41) is then a consequence of (2.34)). Moreover, in order to check (4.43), let us note that, by the triangle inequality,

$$\Delta(\overline{U}_{\tau_n}(s), \overline{U}_{\tau_n}(t)) \leq \int_{\tilde{t}_{\tau_n}(s)}^{\tilde{t}_{\tau_n}(t)} \frac{\Delta(\underline{U}_{\tau_n}(r), \overline{U}_{\tau_n}(r))}{\tau_n} dr \quad \forall 0 \leq s \leq t \leq T.$$

Therefore, passing to the limit as $n \uparrow \infty$ and recalling (2.34), (3.4) and (4.47), we infer

$$\Delta(u(s), u(t)) \leq \limsup_{n \uparrow \infty} \Delta(\overline{U}_{\tau_n}(s), \overline{U}_{\tau_n}(t)) \leq \int_s^t L(r) dr \quad \forall 0 \leq s \leq t \leq T, \quad (4.49)$$

whence (4.43).

Thus, thanks to Proposition 4.8 we find a limit curve $u \in C^0([0, T]; X)$ and a subsequence along which

$$\overline{U}_{\tau_n}(t) \xrightarrow{\sigma} u(t) \quad \forall t \in [0, T].$$

Convergences (4.45) for \underline{U}_{τ_n} and \tilde{U}_{τ_n} then follow from (4.35) and (2.39); further, $u \in AC(0, T; X_0)$ by (4.49). The second inequality in (4.47) also follows from (4.49) and Proposition 2.2.

As far as (4.46) is concerned, the first lim inf inequality ensues from (4.45), estimate (4.34) and the lower semicontinuity assumption (2.34); in the same way, from (2.35) we deduce that

$$\limsup_{n \uparrow \infty} \partial_t \mathcal{E}_t(\tilde{U}_{\tau_n}(t)) \leq \partial_t \mathcal{E}_t(u(t)) \quad \forall t \in [0, T]. \quad (4.50)$$

Finally, in order to prove the second of (4.46), we combine the estimate

$$\begin{aligned} \left| \mathcal{E}_{\tilde{t}_{\tau_n}(t)}(\overline{U}_{\tau_n}(t)) - \mathcal{E}_t(\overline{U}_{\tau_n}(t)) \right| &\leq \int_t^{\tilde{t}_{\tau_n}(t)} \partial_t \mathcal{E}_r(\overline{U}_{\tau_n}(t)) dr \\ &\leq A \int_t^{\tilde{t}_{\tau_n}(t)} \mathcal{F}(\overline{U}_{\tau_n}(t)) dr \\ &\leq C(\tilde{t}_{\tau_n}(t) - t) \quad \forall t \in [0, T] \end{aligned}$$

with the lower semicontinuity inequality (again due to (2.34))

$$\liminf_{n \uparrow \infty} \mathcal{E}_t(\bar{U}_{\tau_n}(t)) \geq \mathcal{E}_t(u(t)) \quad \forall t \in [0, T].$$

In the end, (4.48) follows from (4.45) and the definition (2.18) of $|\partial^- \mathcal{E}|$. \square

We may now complete the proof of Theorem 3.5.

Proof of Theorem 3.5. By (4.45), $u(0) = u_0$. Let us fix $t \in (0, T]$ and consider inequality (4.32) for the nodes $\bar{\mathbf{t}}_{\tau_n}(t)$ and $\mathbf{s} = 0$:

$$\begin{aligned} \int_0^{\bar{\mathbf{t}}_{\tau_n}(t)} \psi \left(\frac{\Delta(\underline{U}_{\tau_n}(r), \bar{U}_{\tau_n}(r))}{\tau_n} \right) dr &+ \int_0^{\bar{\mathbf{t}}_{\tau_n}(t)} \psi^*(|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n}(r))) dr \\ &+ \mathcal{E}_{\bar{\mathbf{t}}_{\tau_n}(t)}(\bar{U}_{\tau_n}(t)) && (4.51) \\ &\leq \mathcal{E}_0(u_0) + \int_0^{\bar{\mathbf{t}}_{\tau_n}(t)} \partial_t \mathcal{E}_r(\tilde{U}_{\tau_n}(r)) dr. \end{aligned}$$

We have

$$\begin{aligned} \liminf_{n \uparrow \infty} \left(\int_0^{\bar{\mathbf{t}}_{\tau_n}(t)} \psi \left(\frac{\Delta(\underline{U}_{\tau_n}(r), \bar{U}_{\tau_n}(r))}{\tau_n} \right) dr \right) &\geq \int_0^t \psi(L(r)) dr \\ &\geq \int_0^t \psi(|u'(r)|) dr, \end{aligned} \quad (4.52)$$

the first inequality due to the first of (4.47) and the convexity of ψ , while the second inequality follows from the second of (4.47) and the monotonicity of ψ . Now, for later convenience let us set $A(t) := \liminf_{n \uparrow \infty} |\partial \mathcal{E}_r|(\tilde{U}_{\tau_n}(t))$ for a.e. $t \in (0, T)$. By Fatou's lemma and the monotonicity of ψ^* we have

$$\begin{aligned} \liminf_{n \uparrow \infty} \left(\int_0^{\bar{\mathbf{t}}_{\tau_n}(t)} \psi^*(|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n}(r))) dr \right) &\geq \int_0^{\bar{\mathbf{t}}_{\tau_n}(t)} \liminf_{n \uparrow \infty} \psi^*(|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n}(r))) dr \\ &\geq \int_0^t \psi^*(A(r)) dr \\ &\geq \int_0^t \psi^*(|\partial^- \mathcal{E}_r|(u(r))) dr. \end{aligned} \quad (4.53)$$

Furthermore, (4.52), (4.53), and the a priori estimates (4.33) also entail

$$\begin{aligned} \int_0^T |u'(r)| |\partial^- \mathcal{E}_r|(u(r)) dr &\leq \int_0^T \psi(|u'(r)|) dr \\ &+ \int_0^T \psi^*(|\partial^- \mathcal{E}_r|(u(r))) dr \leq C. \end{aligned} \quad (4.54)$$

In the same way, we find that

$$\mathcal{E}_t(u(t)) + \int_0^T |\partial_t \mathcal{E}_t(u(t))| \, dt \leq C \quad \forall t \in [0, T]. \tag{4.55}$$

Now, combining (4.45), (4.46), (4.50), (4.52)–(4.53), and exploiting the Fatou lemma, we manage to pass to the limit in (4.51) and obtain

$$\begin{aligned} \int_0^t \psi(|u'(r)|) \, dr + \int_0^t \psi^*(|\partial^- \mathcal{E}_r(u(r))|) \, dr + \mathcal{E}_t(u(t)) \\ \leq \mathcal{E}_0(u_0) + \int_0^t \partial_t \mathcal{E}_r(u(r)) \, dr. \end{aligned} \tag{4.56}$$

On the other hand, note that, thanks to (4.54) and (4.55), we may apply the chain rule of Definition 2.5 to the limit curve $u \in \text{AC}(0, T; X_0)$. Upon integration, we get

$$\begin{aligned} \mathcal{E}_0(u_0) - \mathcal{E}_t(u(t)) + \int_0^t \partial_t \mathcal{E}_r(u(r)) \, dr &\leq \int_0^t |u'(r)| |\partial^- \mathcal{E}_r(u(r))| \, dr \\ &\leq \int_0^t \psi(|u'(r)|) \, dr + \int_0^t \psi^*(|\partial^- \mathcal{E}_r(u(r))|) \, dr. \end{aligned}$$

Thus, (4.56) yields

$$\int_0^t \left(\psi(|u'(r)|) + \psi^*(|\partial^- \mathcal{E}_r(u(r))|) + \frac{d}{dr} \mathcal{E}_r(u(r)) - \partial_t \mathcal{E}_r(u(r)) \right) \, dr = 0.$$

Since the integrand is non negative by inequality (2.29) and $t \in (0, T)$ is arbitrary, we deduce

$$\begin{aligned} \psi(|u'(t)|) + \psi^*(|\partial^- \mathcal{E}_t(u(t))|) + \frac{d}{dt} \mathcal{E}_t(u(t)) - \partial_t \mathcal{E}_t(u(t)) = 0 \\ \text{for a.e. } t \in (0, T) \end{aligned} \tag{4.57}$$

i.e., (3.8), whence (2.33) as well. The above relation yields the energy identity (3.9) upon integration.

Finally, taking the \limsup as $n \uparrow \infty$ of (4.51) and again using the identity just proved, we deduce

$$\begin{aligned} \limsup_{n \uparrow \infty} \left(\int_0^{\bar{t}_{\tau_n}(t)} \psi \left(\frac{\Delta(\underline{U}_{\tau_n}(r), \bar{U}_{\tau_n}(r))}{\tau_n} \right) \, dr + \int_0^{\bar{t}_{\tau_n}(t)} \psi^*(|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n}(r))) \, dr \right. \\ \left. + \mathcal{E}_{\bar{t}_{\tau_n}(t)}(\bar{U}_{\tau_n}(t)) \right) \\ \leq \mathcal{E}_0(u_0) + \int_0^t \partial_t \mathcal{E}_r(u(r)) \, dr \\ = \int_0^t \psi(|u'(r)|) \, dr + \int_0^t \psi^*(|\partial^- \mathcal{E}_r(u(r))|) \, dr + \mathcal{E}_t(u(t)). \end{aligned}$$

So, taking into account (4.46), (4.52), and (4.53) and arguing by comparison, we deduce convergences (3.10)–(3.11) and the first of (3.12). We also conclude the second of (3.12) by taking the \limsup as $n \uparrow \infty$ of the following inequality

$$\begin{aligned} \int_0^{\bar{t}_{\tau_n}(t)} \psi \left(\frac{\Delta(\underline{U}_{\tau_n}(r), \bar{U}_{\tau_n}(r))}{\tau_n} \right) dr + \int_0^t \psi^* (|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n}(r))) dr + \mathcal{E}_t(\tilde{U}_{\tau_n}(t)) \\ \leq \mathcal{E}_0(u_0) + \int_0^{\bar{t}_{\tau_n}(t)} \partial_t \mathcal{E}_r(\tilde{U}_{\tau_n}(r)) dr \end{aligned}$$

(which is obtained by summing up (4.32) and (4.36)), and arguing as in the above lines.

In order to prove (3.13), we note that, combining (4.53) with (3.11) leads to

$$\begin{aligned} \lim_{n \uparrow \infty} \int_0^t \psi^* (|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n}(r))) dr &= \int_0^t \liminf_{n \uparrow \infty} \psi^* (|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n}(r))) dr \\ &= \int_0^t \psi^* (A(r)) dr \\ &= \int_0^t \psi^* (|\partial^- \mathcal{E}_r|(u(r))) dr \quad \forall t \in [0, T], \end{aligned} \tag{4.58}$$

whence

$$\liminf_{n \uparrow \infty} \psi^* (|\partial \mathcal{E}_t|(\tilde{U}_{\tau_n}(t))) = \psi^*(A(t)) = \psi^*(|\partial^- \mathcal{E}_t|(u(t))) \quad \text{for a.e. } t \in (0, T).$$

Recalling (2.33), we conclude that for a.e. $t \in (0, T)$

$$\begin{aligned} |u'(t)| \cdot A(t) &\leq \psi(|u'(t)|) + \psi^*(A(t)) \\ &= |u'(t)| \cdot |\partial^- \mathcal{E}_t|(u(t)) \leq |u'(t)| \cdot A(t) \end{aligned} \tag{4.59}$$

so that all the above inequalities hold as equalities and, if $|u'(t)| \neq 0$, we conclude $A(t) = |\partial^- \mathcal{E}_t|(u(t))$, while $|u'(t)| = 0$ leads to the second of (3.13).

Finally, suppose first that ψ^* has superlinear growth at infinity: it follows from the a priori estimate (4.33) that the sequence $\{|\partial \mathcal{E}_t|(\tilde{U}_{\tau_n})\}$ is uniformly integrable in $L^1(0, T)$. Hence, the fundamental compactness theorem of Young measures theory (see [10, Theorem 1] and also [12]) ensures that $\{|\partial \mathcal{E}_t|(\tilde{U}_{\tau_n})\}$ admits a subsequence (which we do not relabel) and a limit Young measure $\nu = \{\nu_t\}_{t \in (0, T)}$ (ν_t being a probability measure on \mathbb{R} for a.e. $t \in (0, T)$) such that

ν_t is concentrated on the set $\mathcal{L}(t)$

$$\text{of the limit points of } \{|\partial \mathcal{E}_t|(\tilde{U}_{\tau_n})(t)\} \text{ for a.e. } t \in (0, T), \tag{4.60}$$

$$|\partial \mathcal{E}_t|(\tilde{U}_{\tau_n}) \rightharpoonup \Sigma(t) := \int_{\mathbb{R}} \xi d\nu_t(\xi) \quad \text{in } L^1((0, T)), \tag{4.61}$$

$$\liminf_{n \uparrow \infty} \int_0^T \psi^* (|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n})(r)) dr \geq \int_0^T \left(\int_{\mathbb{R}} \psi^*(\xi) d\nu_r(\xi) \right) dr. \tag{4.62}$$

Now, the definition of $|\partial^- \mathcal{E}|$ gives for a.e. $t \in (0, T)$

$$|\partial^- \mathcal{E}_t|(u(t)) \leq \xi, \quad \text{whence} \quad \psi^*(|\partial^- \mathcal{E}_t|(u(t))) \leq \psi^*(\xi) \quad \forall \xi \in \mathcal{L}(t). \quad (4.63)$$

Combining the above inequality, (4.58), (4.60), and (4.62), we deduce that

$$\int_0^T \left(\int_{\mathbb{R}} \psi^*(\xi) \, d\nu_r(\xi) \right) dr = \int_0^T \psi^*(|\partial^- \mathcal{E}_r|(u(r))) \, dr,$$

whence, again by (4.63),

$$\psi^*(\xi) = \psi^*(|\partial^- \mathcal{E}_t|(u(t))) \quad \text{for a.e. } \xi \in \mathcal{L}(t) \quad \text{for a.e. } t \in (0, T). \quad (4.64)$$

Taking into account the above identity, (2.33) and the first of (4.63) we thus conclude the following chain of inequalities

$$\begin{aligned} |u'(t)| \xi &\leq \psi(|u'(t)|) + \psi^*(\xi) = \psi(|u'(t)|) + \psi^*(|\partial^- \mathcal{E}_t|(u(t))) \\ &= |u'(t)| |\partial^- \mathcal{E}_t|(u(t)) \leq |u'(t)| \xi \quad \forall \xi \in \mathcal{L}(t) \quad \text{for a.e. } t \in (0, T). \end{aligned} \quad (4.65)$$

Then, recalling the definition (3.14) of the set \mathcal{I} , we conclude that

$$\xi = |\partial^- \mathcal{E}_t|(u(t)) \quad \forall \xi \in \mathcal{L}(t) \quad \text{for a.e. } t \in \mathcal{I}. \quad (4.66)$$

Therefore, the limit Young measure ν is such that for a.e. $t \in \mathcal{I}$ its disintegration ν_t coincides with the Dirac mass $\delta_{|\partial^- \mathcal{E}_t|(u(t))}$. Since the sequence $\{|\partial \mathcal{E}_t|(\tilde{U}_{\tau_n})\}$ is uniformly integrable, we conclude (3.15).

Without the superlinear growth assumption on ψ^* , using a version of the *Biting Lemma* (see e.g. [50, Theorem 13]) we deduce that there is a sequence of Borel subsets $O_n \subset (0, T)$, decreasing to \emptyset , such that, denoting by I_n the indicator function of the set $(0, T) \setminus O_n$ the sequence $\omega_n := I_n |\partial \mathcal{E}_t|(\tilde{U}_{\tau_n})$ is uniformly integrable in $L^1(0, T)$. Thus, we apply [10, Theorem 1] to the sequence $\{\omega_n\}$, find an associated limit Young measure $\mu = \{\mu_t\}_{t \in (0, T)}$, and conclude relations (4.60)–(4.62) for a (not relabeled) subsequence $\{\omega_n\}$. Since the sequence $O_n \downarrow \emptyset$, we may check that for a.e. $t \in (0, T)$ the set of the limit points of $\{\omega_n(t)\}$ coincides with the set of the limit points of $\{|\partial \mathcal{E}_t|(\tilde{U}_{\tau_n})(t)\}$, hence relations (4.63) hold as well. On the other hand,

$$\begin{aligned} \liminf_{n \uparrow \infty} \int_0^T \psi^*(\omega_n(r)) \, dr &\leq \liminf_{n \uparrow \infty} \int_0^T \psi^*(|\partial \mathcal{E}_r|(\tilde{U}_{\tau_n})(r)) \, dr \\ &= \int_0^T \psi^*(|\partial^- \mathcal{E}_r|(u(r))) \, dr \end{aligned}$$

so that we similarly conclude (4.64) for the Young measure μ . Arguing exactly in the same way as above, we infer (3.16).

Hence, the proof is done. □

Part II: applications in Banach spaces

5. Preliminaries in Banach spaces

In this part, we focus our attention on the case in which the ambient space X (cf. (2.1)) is a *separable Banach space*: to stress this assumption, we shall indicate it with the letter B . We shall denote by $\|\cdot\|$ the norm of B , by $\|\cdot\|_*$ the norm on the dual space B' and by $\langle \cdot, \cdot \rangle$ the duality pairing between B' and B .

For simplicity, in the sequel we shall work with non symmetric distances Δ on B taking values in $[0, +\infty)$. Furthermore, to fix ideas we shall suppose that

σ is the *strong topology* of B .

5.1. Sublinear functionals

Let us recall that a *sublinear functional* is a *convex and positively homogeneous* map $\eta : B \rightarrow [0, +\infty)$, thus satisfying the following conditions:

$$\eta(\lambda v) = \lambda \eta(v) \quad \forall \lambda \geq 0 \quad \forall v \in B \quad (5.1a)$$

$$\eta(v + w) \leq \eta(v) + \eta(w) \quad \forall v, w \in B. \quad (5.1b)$$

It is easy to check that $\eta(0) = 0$ and it is well known that, among all the positively homogeneous maps satisfying (5.1a), condition (5.1b) is equivalent to the convexity of η . We also assume that there exists a positive constant K such that

$$K^{-1} \|v\| \leq \eta(v) \leq K \|v\| \quad \forall v \in B. \quad (5.1c)$$

The choice

$$\Delta(u, v) := \eta(v - u) \quad \forall u, v \in B \quad (5.2)$$

induces an asymmetric distance on B which satisfies the properties of Section 2.1 and is metrically equivalent to the distance induced by the norm of B . Therefore, given a proper functional $\mathcal{E} : B \rightarrow (-\infty, +\infty]$ and a point $u \in \text{dom}(\mathcal{E})$, we shall use the notation

$$|\partial \mathcal{E}|(u) = \limsup_{v \rightarrow u} \frac{(\mathcal{E}(u) - \mathcal{E}(v))^+}{\Delta(u, v)}, \quad (5.3)$$

and accordingly consider the relaxed slope $|\partial^- \mathcal{E}|$ (2.18).

Duality

For any $u \in B$ we also introduce the *dual functional* $\eta_* := B' \rightarrow [0, +\infty)$ defined by

$$\eta_*(\sigma) := \sup_{v \in B \setminus \{0\}} \frac{\langle \sigma, v \rangle}{\eta(v)} = \sup \left\{ \langle \sigma, v \rangle : \eta(v) = 1 \right\} \quad \forall \sigma \in B' \quad \forall u \in B. \quad (5.4)$$

Note that if η is a norm, then the related functional η_* coincides with the corresponding dual norm of B' . Further, (5.1c) implies, respectively,

$$K^{-1} \|y\|_* \leq \eta_*(y) \leq K \|y\|_* \quad \forall y \in B'. \tag{5.5}$$

Let $\psi : [0, +\infty) \rightarrow [0, +\infty)$ be a positive, convex, and lower semicontinuous function. We define the functional $\Psi : B \rightarrow [0, +\infty)$ by

$$\Psi(v) := \psi(\eta(v)) \quad \forall v \in B, \tag{5.6}$$

and denote by $\partial\Psi$ its subdifferential and by Ψ^* its Fenchel-Moreau conjugate

$$\Psi^*(\sigma) := \sup_{v \in B} (\langle \sigma, v \rangle - \Psi(v)).$$

In the sequel, we shall need the following duality result.

Lemma 5.1. *The conjugate of Ψ is given by*

$$\Psi^*(\sigma) := \psi^*(\eta_*(\sigma)) \quad \forall \sigma \in B'. \tag{5.7}$$

Moreover, we have the following characterization of the subdifferential $\partial\Psi$: for all $v \in B$

$$\sigma \in \partial\Psi(v) \iff \left(\eta_*(\sigma) \in \partial\psi(\eta(v)) \text{ and } \eta_*(\sigma) \cdot \eta(v) = \langle \sigma, v \rangle \right). \tag{5.8}$$

Proof. It follows from the definition of η_* that $\langle \sigma, v \rangle \leq \eta(v) \eta_*(\sigma)$ for all $v \in B$ and $\sigma \in B'$. Hence, by the definition of Ψ^* we have

$$\Psi^*(\sigma) \leq \sup_{v \in B} \left(\eta(v) \cdot \eta_*(\sigma) - \psi(\eta(v)) \right) = \sup_{r \geq 0} \left(r \eta_*(\sigma) - \psi(r) \right) = \psi^*(\eta_*(\sigma)).$$

On the other hand, for any $\sigma \in B'$ we can find a sequence $\{v_n\}$ fulfilling $\eta(v_n) = 1$, and $\eta_*(\sigma) = \lim_{n \uparrow \infty} \langle \sigma, v_n \rangle$. Then, for any $r \geq 0$

$$\begin{aligned} r\eta_*(\sigma) - \psi(r) &= \lim_{n \uparrow \infty} (\langle \sigma, r v_n \rangle - \psi(r \eta(v_n))) = \lim_{n \uparrow \infty} (\langle \sigma, r v_n \rangle - \psi(\eta(r v_n))) \\ &\leq \sup_{v \in B} \left(\langle \sigma, v \rangle - \psi(\eta(v)) \right) = \Psi^*(\sigma), \end{aligned}$$

and (5.7) ensues.

Thanks to (5.7), it is straightforward to check that

$$\left(\Psi(v) + \Psi^*(\sigma) = \langle \sigma, v \rangle \right) \Leftrightarrow \left(\psi(\eta(v)) + \psi^*(\eta_*(\sigma)) = \eta(v) \cdot \eta_*(\sigma) = \langle \sigma, v \rangle \right).$$

On the other hand, the standard convex analysis characterization of the subdifferential in terms of the Legendre-Fenchel-Moreau transform yields

$$\begin{aligned} \sigma \in \partial\Psi(v) &\Leftrightarrow \Psi(v) + \Psi^*(\sigma) = \langle \sigma, v \rangle, \\ \eta_*(\sigma) \in \partial\psi(\eta(v)) &\Leftrightarrow \psi(\eta(v)) + \psi^*(\eta_*(\sigma)) = \eta(v) \cdot \eta_*(\sigma). \end{aligned}$$

Combining the above relations, we readily deduce (5.8). □

5.2. Subdifferential and slopes for admissible functionals

Definition 5.2 (Fréchet subdifferential). Let $\mathcal{E} : B \rightarrow (-\infty, +\infty]$ be a proper functional; the *Fréchet subdifferential* $\partial\mathcal{E}(u) \subset B'$ of \mathcal{E} at a point $u \in \text{dom}(\mathcal{E})$ is defined by

$$\xi \in \partial\mathcal{E}(u) \Leftrightarrow \liminf_{w \rightarrow u} \frac{\mathcal{E}(w) - \mathcal{E}(u) - \langle \xi, w - u \rangle}{\|w - u\|} \geq 0. \quad (5.9)$$

It is well known that the subdifferential is single-valued and coincides with the usual differential $D\mathcal{E}$ when it exists, *e.g.* if \mathcal{E} is a functional of class C^1 . If \mathcal{E} is convex, then $\partial\mathcal{E}$ can be equivalently characterized by

$$\xi \in \partial\mathcal{E}(u) \Leftrightarrow \mathcal{E}(w) - \mathcal{E}(u) \geq \langle \xi, w - u \rangle \quad \forall w \in B,$$

i.e. the Fréchet subdifferential coincides with the subdifferential in the sense of convex analysis. In fact, in the sequel we shall consider a more general convexity property.

λ -convexity

We recall that a proper functional $\mathcal{E} : B \rightarrow (-\infty, +\infty]$ is λ -convex for some $\lambda \in \mathbb{R}$ if

$$\begin{aligned} \mathcal{E}(u_\theta) &\leq (1 - \theta)\mathcal{E}(u_0) + \theta\mathcal{E}(u_1) - \frac{1}{2}\lambda\theta(1 - \theta)\|u_0 - u_1\|^2 \\ &\forall \theta \in [0, 1] \quad \forall u_0, u_1 \in B, \end{aligned} \quad (5.10)$$

where we have set $u_\theta = (1 - \theta)u_0 + \theta u_1$. The following result extends [5, Proposition 1.4.4, Theorem 2.4.9] to the asymmetric setting and to λ -convex functionals.

Lemma 5.3. *Let $\mathcal{E} : B \rightarrow (-\infty, +\infty]$ be proper, lower semicontinuous, and λ -convex for some $\lambda \in \mathbb{R}$. Then,*

1. *for all $u \in \text{dom}(\mathcal{E})$ the Fréchet subdifferential $\partial\mathcal{E}(u)$ is a convex weakly*-closed set, it can be characterized by*

$$\xi \in \partial\mathcal{E}(u) \Leftrightarrow \mathcal{E}(w) - \mathcal{E}(u) \geq \langle \xi, w - u \rangle + \frac{\lambda}{2}\|w - u\|^2 \quad \forall w \in B, \quad (5.11)$$

and the graph of the operator $\partial\mathcal{E}$ is strongly-weakly closed, namely*

$$u_n \rightarrow u, \quad \xi_n \rightharpoonup^* \xi, \quad \xi_n \in \partial\mathcal{E}(u_n) \Rightarrow \xi \in \partial\mathcal{E}(u). \quad (5.12)$$

2. *Let η be a positively homogeneous functional fulfilling (5.1a,b,c) and inducing the asymmetric distance Δ (5.2); let $|\partial\mathcal{E}|$ be the Δ -local slope of \mathcal{E} . Then,*

$$|\partial\mathcal{E}|(u) = \sup_{v \neq u} \left(\frac{\mathcal{E}(u) - \mathcal{E}(v)}{\eta(v - u)} - \frac{1}{2}|\lambda|K^2\eta(v - u) \right)^+ \quad \forall u \in \text{dom}(\mathcal{E}), \quad (5.13)$$

$$|\partial\mathcal{E}|(u) = \min_{\xi \in \partial\mathcal{E}(u)} \eta_*(-\xi) \quad \forall u \in \text{dom}(\mathcal{E}), \quad (5.14)$$

$$\text{the map } u \mapsto |\partial\mathcal{E}|(u) \text{ is lower semicontinuous.} \quad (5.15)$$

Proof. Easy computations lead to (5.11), which in turn yields (5.12). Further, we note that (5.1c) and (5.10) yield that

$$\mathcal{E}(u_\theta) \leq (1-\theta)\mathcal{E}(u_0) + \theta\mathcal{E}(u_1) + \frac{|\lambda|}{2}K^2\theta(1-\theta)\eta^2(u_1-u_0) \quad \forall \theta \in [0,1] \quad \forall u_0, u_1 \in B.$$

Moving from the above inequality and repeating the very same computations as in the proof of [5, Theorem 2.4.9], one checks (5.13). Finally, (5.11) and (5.1c) again yield that for all $u \in \text{dom}(\mathcal{E})$

$$\mathcal{E}(u) - \mathcal{E}(u+w) - \frac{1}{2}|\lambda|K^2\eta^2(w) \leq \langle -\xi, w \rangle \quad \forall w \in B \quad \forall \xi \in \partial\mathcal{E}(u).$$

Taking into account (5.13), we deduce that

$$|\partial\mathcal{E}|(u) \leq \min_{\xi \in \partial\mathcal{E}(u)} \eta_*(-\xi).$$

To prove the converse inequality, we introduce the quantity

$$\delta\mathcal{E}(u; w) := \limsup_{\varepsilon \downarrow 0} \frac{\mathcal{E}(u + \varepsilon w) - \mathcal{E}(u)}{\varepsilon} \quad \text{for } u \in \text{dom}(\mathcal{E}), w \in B.$$

Using the λ -convexity inequality (5.10) and the definition of $|\partial\mathcal{E}|$ it is not difficult to check that

$$\begin{aligned} & \text{the map } w \mapsto \delta\mathcal{E}(u; w) \text{ is convex for all } u \in \text{dom}(\mathcal{E}), \\ & \begin{cases} \mathcal{E}(u+w) - \mathcal{E}(u) \geq \delta\mathcal{E}(u; w) + \frac{\lambda}{2}\|w\|^2 \\ \delta\mathcal{E}(u; w) \geq -|\partial\mathcal{E}|(u) \eta(w) \end{cases} \quad \forall u \in \text{dom}(\mathcal{E}), w \in B. \end{aligned} \quad (5.16)$$

Now, mimicking the proof of [5, Proposition 1.4.4], we consider the epigraph

$$\mathcal{K}_+ = \{(w, r) \in B \times \mathbb{R} : r \geq \delta\mathcal{E}(u; w)\}$$

of the function $w \mapsto \delta\mathcal{E}(u; w)$ and the open hypograph

$$\mathcal{K}_- = \{(w, r) \in B \times \mathbb{R} : r < -|\partial\mathcal{E}|(u) \eta(w)\}$$

of $w \mapsto -|\partial\mathcal{E}|(u) \eta(w)$. Since \mathcal{K}_+ and \mathcal{K}_- are disjoint by (5.16), a version of the Hahn-Banach theorem yields that there exists $\xi \in B'$ and $\alpha \in \mathbb{R}$ such that

$$-|\partial\mathcal{E}|(u) \eta(w) \leq \langle \xi, w \rangle + \alpha \leq \delta\mathcal{E}(u; w) \quad \forall w \in B. \quad (5.17)$$

A standard argument shows that $\alpha = 0$. Hence, from the first inequality in (5.17) and the arbitrariness of w we deduce that $\eta_*(-\xi) \leq |\partial\mathcal{E}|(u)$. The second of (5.17), combined with (5.16), gives that ξ fulfills (5.11). Thus, $\xi \in \partial\mathcal{E}(u)$, and (5.14) ensues. Finally, in order to check (5.15) we fix a sequence $u_n \rightarrow u$ with $\Lambda :=$

$\liminf_{n \uparrow \infty} |\partial \mathcal{E}|(u_n) < +\infty$. For any $\varepsilon > 0$ there exists a subsequence $\{u_{n'}\}$ and, accordingly, a sequence $\{\xi_{n'}\} \subset B'$, with $\xi_{n'} \in \partial \mathcal{E}(u_{n'})$ for all n' , fulfilling

$$\lim_{n' \uparrow \infty} \eta_*(-\xi_{n'}) = \lim_{n' \uparrow \infty} \min_{\xi \in \partial \mathcal{E}(u_{n'})} \eta_*(-\xi) = \lim_{n' \uparrow \infty} |\partial \mathcal{E}|(u_{n'}) \leq \Lambda + \varepsilon.$$

Due to (5.1c), $\{\xi_{n'}\}$ is bounded in B' , hence, up to a subsequence, we deduce that $\xi_{n'} \rightharpoonup^* \xi$, with $\xi \in \partial \mathcal{E}(u)$ by (5.12). Thus, thanks to (5.14) and the weak*-lower semicontinuity of η_* we deduce

$$|\partial \mathcal{E}|(u) \leq \eta_*(-\xi) \leq \lim_{n' \uparrow \infty} |\partial \mathcal{E}|(u_{n'}) \leq \liminf_{n' \uparrow \infty} |\partial \mathcal{E}|(u_n) + \varepsilon.$$

Being ε arbitrary, (5.15) follows. \square

Admissible functionals

We are now in the position of introducing the broadest class of (energy) functionals which we are going to tackle in the framework of our metric approach to doubly nonlinear evolution equations.

Definition 5.4 (Admissible functionals). We say that a proper and lower semicontinuous functional $\mathcal{E} : B \rightarrow (-\infty, +\infty]$ is *admissible* if it can be decomposed into the sum $\mathcal{E} = \mathcal{E}_1 + \mathcal{E}_2$, the functionals \mathcal{E}_1 and \mathcal{E}_2 satisfying the following conditions

$$\begin{aligned} &\mathcal{E}_1 \text{ is proper, } \lambda\text{-convex for some } \lambda \in \mathbb{R}, \text{ lower semicontinuous,} \\ &\quad \text{and bounded from below,} \\ &\mathcal{E}_2 \text{ is proper and} \\ &\forall \{u_n\} \subset B, (u_n \rightarrow u, \sup_n \mathcal{E}_1(u_n) < +\infty) \Rightarrow \liminf_{n \uparrow \infty} \mathcal{E}_2(u_n) \geq \mathcal{E}_2(u); \end{aligned} \tag{5.18}$$

$$\begin{aligned} &\forall M > 0 \quad \exists 0 < K_1 < 1, K_2 > 0 \text{ s.t.} \\ &\mathcal{E}_2(u) \geq -K_1 \mathcal{E}_1(u) - K_2 \quad \forall u \in B \text{ with } \|u\| \leq M, \end{aligned} \tag{5.19}$$

$$\begin{aligned} &\forall u \in \text{dom}(\mathcal{E}) \exists! \xi =: \tilde{\mathcal{D}}\mathcal{E}_2(u) \in B' \text{ s.t. } \forall \{u_n\} \subset B \text{ with} \\ &u_n \rightarrow u, \sup_n \mathcal{E}_1(u_n) < +\infty \end{aligned} \tag{5.20}$$

$$\lim_{n \uparrow \infty} \frac{\mathcal{E}_2(u_n) - \mathcal{E}_2(u) - \langle \xi, u_n - u \rangle}{\|u_n - u\|} = 0,$$

$$\forall M > 0 \exists K_3 > 0 \text{ s.t. } \|\tilde{\mathcal{D}}\mathcal{E}_2(u)\|_* \leq K_3 \quad \forall u \in B \text{ with } \max(\|u\|, \mathcal{E}_1(u)) \leq M. \tag{5.21}$$

$$\forall \{u_n\} \subset B, u_n \rightarrow u, \sup_n \mathcal{E}_1(u_n) < +\infty \Rightarrow \tilde{\mathcal{D}}\mathcal{E}_2(u_n) \rightharpoonup^* \tilde{\mathcal{D}}\mathcal{E}_2(u). \tag{5.22}$$

Remark 5.5. Let us point out that with (5.18) and (5.20) we require \mathcal{E}_2 to be lower semicontinuous and (Fréchet) differentiable along sequences with bounded \mathcal{E}_1 -energy and, further, (5.21) states that $\tilde{D}\mathcal{E}_2$ is estimated by the functional \mathcal{E}_1 and (5.22) that $\tilde{D}\mathcal{E}_2$ is continuous, again along sequences with bounded \mathcal{E}_1 -energy. In other words, the functional \mathcal{E}_2 is a *dominated perturbation* of the (λ) -convex functional \mathcal{E}_1 . In [45] a similar class of dominated *concave* perturbations of convex functionals was considered.

The following result collects some properties of the Fréchet subdifferential and of the slopes of admissible functionals, extending Lemma 5.3.

Proposition 5.6. *Let $\mathcal{E} : B \rightarrow (-\infty, +\infty]$ be an admissible functional (with $\mathcal{E} = \mathcal{E}_1 + \mathcal{E}_2$ in the sense of Definition 5.4), and let η be a positively homogeneous functional fulfilling (5.1a,b,c) and inducing the asymmetric distance Δ (5.2). Then,*

1. *for all $u \in \text{dom}(\mathcal{E})$ the Fréchet subdifferential $\partial\mathcal{E}(u)$ is a convex and weakly* closed set,*

$$\partial\mathcal{E}(u) = \partial\mathcal{E}_1(u) + \tilde{D}\mathcal{E}_2(u) \quad \forall u \in \text{dom}(\partial\mathcal{E}), \tag{5.23}$$

and $\partial\mathcal{E}$ satisfies the strong-weak closedness property along sequences with bounded energy*

$$u_n \rightarrow u, \quad \xi_n \rightharpoonup^* \xi, \quad \xi_n \in \partial\mathcal{E}(u_n) \quad \sup_n |\mathcal{E}(u_n)| < +\infty \Rightarrow \xi \in \partial\mathcal{E}(u); \tag{5.24}$$

2. *for all $u \in \text{dom}(\mathcal{E})$*

$$\begin{aligned} \partial\mathcal{E}(u) \neq \emptyset &\Leftrightarrow |\partial\mathcal{E}|(u) < +\infty \quad \text{and} \quad |\partial\mathcal{E}|(u) = \min_{\xi \in \partial\mathcal{E}(u)} \eta_*(-\xi), \\ |\partial^-\mathcal{E}|(u) &= |\partial\mathcal{E}|(u) \quad \forall u \in \text{dom}(\partial\mathcal{E}). \end{aligned} \tag{5.25}$$

Proof. First of all, we show that

$$\partial\mathcal{E}(u) - \tilde{D}\mathcal{E}_2(u) \subset \partial\mathcal{E}_1(u) \quad \forall u \in \text{dom}(\partial\mathcal{E}).$$

Indeed, let us fix any $\zeta \in \partial\mathcal{E}(u)$: since \mathcal{E}_1 is convex, in order to show that $\zeta - \tilde{D}\mathcal{E}_2(u) \in \partial\mathcal{E}_1(u)$ it is sufficient to check that for all sequence $\{w_n\}$ with $w_n \rightarrow u$ we have

$$\begin{aligned} &\liminf_{n \uparrow \infty} \frac{\mathcal{E}_1(w_n) - \mathcal{E}_1(u) - \langle \zeta - \tilde{D}\mathcal{E}_2(u), w_n - u \rangle}{\|w_n - u\|} \\ &= \liminf_{n \uparrow \infty} \left(\frac{\mathcal{E}(w_n) - \mathcal{E}(u) - \langle \zeta, w_n - u \rangle}{\|w_n - u\|} - \frac{\mathcal{E}_2(w_n) - \mathcal{E}_2(u) - \langle \tilde{D}\mathcal{E}_2(u), w_n - u \rangle}{\|w_n - u\|} \right) \\ &\geq 0. \end{aligned} \tag{5.26}$$

Now, we may suppose that $\sup_n \mathcal{E}_1(w_n) < +\infty$, hence (5.26) trivially ensues from the fact that $\zeta \in \partial\mathcal{E}(u)$ and from the definition of $\widetilde{\mathcal{D}}\mathcal{E}_2(u)$. The proof of the converse inclusion $\partial\mathcal{E}_1(u) + \widetilde{\mathcal{D}}\mathcal{E}_2(u) \subset \partial\mathcal{E}(u)$ for all $u \in \text{dom}(\partial\mathcal{E})$ follows the same lines. Thanks to (5.23) and to Lemma 5.3, we immediately have that $\partial\mathcal{E}(u)$ is a convex and weakly* closed subset of B' . Further, (5.24) is a consequence of (5.12) and of (5.22).

In order to show the first of (5.25) at a point $u \in \text{dom}(\mathcal{E})$, we may suppose without loss of generality that $\widetilde{\mathcal{D}}\mathcal{E}_2(u) = 0$ and that $|\partial\mathcal{E}|(u) > 0$. Then, using (5.19) one easily checks that there exists some constant $C > 0$ such that

$$|\partial\mathcal{E}|(u) = \limsup_{v \rightarrow u, \mathcal{E}_1(v) \leq C} \frac{(\mathcal{E}_1(u) - \mathcal{E}_1(v) + \mathcal{E}_2(u) - \mathcal{E}_2(v))^+}{\eta(v - u)}.$$

Observing that

$$\lim_{v \rightarrow u, \mathcal{E}_1(v) \leq C} \frac{(\mathcal{E}_2(u) - \mathcal{E}_2(v))^+}{\eta(v - u)} = 0,$$

we conclude

$$|\partial\mathcal{E}|(u) = \limsup_{v \rightarrow u, \mathcal{E}_1(v) \leq C} \frac{(\mathcal{E}_1(u) - \mathcal{E}_1(v))^+}{\eta(v - u)} = \min_{\xi \in \partial\mathcal{E}_1(u)} \eta_*(-\xi) = \min_{\xi \in \partial\mathcal{E}(u)} \eta_*(-\xi),$$

the second identity due to (5.14) for the λ -convex functional \mathcal{E}_1 and the third one to (5.23). As for the second of (5.25), one clearly has $|\partial^-\mathcal{E}|(u) \leq |\partial\mathcal{E}|(u)$; in order to prove the converse inequality, we argue in the same way as for proving (5.15). \square

Remark 5.7. Combining (5.23) with the representation (5.25) of the slope of functionals \mathcal{E} and \mathcal{E}_1 , one deduces that

$$\begin{aligned} |\partial\mathcal{E}_1|(u) &= \min_{\xi \in \partial\mathcal{E}(u) - \widetilde{\mathcal{D}}\mathcal{E}_2(u)} \eta_*(-\xi) \leq \min_{\xi \in \partial\mathcal{E}(u)} \eta_*(-\xi) + \eta_*(\widetilde{\mathcal{D}}\mathcal{E}_2(u)) \\ &\leq |\partial\mathcal{E}|(u) + K \|\widetilde{\mathcal{D}}\mathcal{E}_2(u)\|_* \quad \forall u \in B, \end{aligned} \quad (5.27)$$

where the first inequality follows from the sublinearity of η_* and the second one from (5.5).

For later convenience, we also state a version of the mean-value theorem for the functional \mathcal{E}_2 which can be proved exactly in the same way as [2, Chapter 1, Theorem 1.8], to which we refer the reader.

Lemma 5.8. *Let $\mathcal{E} : B \rightarrow (-\infty, +\infty]$ be an admissible functional. Then, for all $u, v \in \text{dom}(\mathcal{E})$ such that the segment $[u, v] \subset \text{dom}(\mathcal{E})$ one has*

$$|\mathcal{E}_2(u) - \mathcal{E}_2(v)| \leq \sup_{z \in [u, v]} \|\widetilde{\mathcal{D}}\mathcal{E}_2(z)\|_* \|u - v\|. \quad (5.28)$$

We conclude the section with a technical result, which will turn out to be useful in the sequel.

Lemma 5.9 (Selection of optimal directions). *Let us suppose that*

$$B \text{ is reflexive,} \tag{5.29}$$

let \mathcal{E} be an admissible functional and let $\xi \in \partial\mathcal{E}(u)$ with $0 < \eta_*(-\xi) = |\partial\mathcal{E}|(u) < +\infty$. Then, there exist a sequence of directions $\{v_n\}$, $v \in B$ and a positive vanishing sequence $h_n \in (0, +\infty)$ such that

$$\eta(v_n) = \eta(v) = 1, \quad \langle -\xi, v \rangle = \eta_*(-\xi), \quad v_n \rightharpoonup v, \tag{5.30}$$

and the sequence $u_n := u + h_n v_n$ satisfies

$$\lim_{n \uparrow +\infty} \frac{\mathcal{E}(u) - \mathcal{E}(u_n)}{\eta(u_n - u)} = \lim_{n \uparrow +\infty} \frac{\mathcal{E}(u) - \mathcal{E}(u + h_n v_n)}{h_n} = |\partial\mathcal{E}|(u) = \eta_*(-\xi). \tag{5.31}$$

Proof. By the definition of slope and by (5.25), we can find a sequence $u_n \neq u$ strongly converging to u such that

$$\lim_{n \uparrow +\infty} \frac{\mathcal{E}(u) - \mathcal{E}(u_n)}{\eta(u_n - u)} = |\partial\mathcal{E}|(u) = \eta_*(-\xi) > 0.$$

We thus set

$$h_n := \eta(u_n - u), \quad v_n := \frac{u_n - u}{h_n},$$

and, owing to the reflexivity of B , we can extract a subsequence (still labeled v_n) weakly converging to $v \in B$ with $\eta(v) \leq 1$. By the subdifferentiability assumption, we have

$$\mathcal{E}(u_n) - \mathcal{E}(u) \geq \langle \xi, u_n - u \rangle + o(h_n) \quad \text{as } n \uparrow +\infty;$$

dividing by h_n and inverting the direction of the inequality, we can pass to the limit as $n \uparrow +\infty$, obtaining

$$\eta_*(-\xi) \leq \langle -\xi, v \rangle \leq \eta_*(-\xi) \cdot \eta(v),$$

thus proving $\eta(v) = 1$ and the second identity of (5.30). □

5.3. Chain rule for admissible families of time-dependent functionals

In this section, we shall establish a general chain-rule formula for a family of time-dependent functionals $\mathcal{E}_t(\cdot)$, $t \in [0, T]$. The natural assumptions combine the admissibility conditions given in Definition 5.4, the conditions on the time-dependence discussed in Section 2.3, and some of the topological assumptions of Section 2.5. We recall them in a unique definition.

Definition 5.10 (Admissible family of time-dependent functionals). We say that a family of (proper, lower semicontinuous) functionals $\mathcal{E}_t : B \rightarrow (-\infty, +\infty]$, $t \in [0, T]$, is *admissible* if each functional \mathcal{E}_t is admissible according to Definition 5.4, with the decomposition $\mathcal{E}_t = \mathcal{E}_t^1 + \mathcal{E}_t^2$ for all $t \in [0, T]$, and

1. $\text{dom}(\mathcal{E}_t) \equiv D$ does not depend on time,
2. the functionals \mathcal{E}_t^1 are uniformly bounded from below with respect to t and λ -uniformly convex, namely

$$\begin{aligned} \exists \lambda \in \mathbb{R} : \quad & \forall t \in [0, T] \quad \forall u_0, u_1 \in B \quad \forall \theta \in [0, 1] \\ & \mathcal{E}_t^1((1 - \theta)u_0 + \theta u_1) \leq (1 - \theta)\mathcal{E}_t^1(u_0) + \theta\mathcal{E}_t^1(u_1) - \frac{1}{2}\lambda\theta(1 - \theta)\|u_0 - u_1\|^2, \end{aligned} \tag{5.32}$$

3. conditions (5.19) and (5.21) hold with constants K_1, K_2 , and K_3 independent of t ,
4. for every sequences $v_n, v \in D, t_n, t \in [0, T]$

$$v_n \rightarrow v, \quad t_n \rightarrow t, \quad \sup_n \mathcal{E}_{t_n}(v) < +\infty \quad \Rightarrow \quad \exists \lim_{n \rightarrow \infty} \frac{\mathcal{E}_{t_n}(v_n) - \mathcal{E}_t(v_n)}{t_n - t} =: \partial_t \mathcal{E}_t(v), \tag{5.33}$$

which satisfies

$$|\partial_t \mathcal{E}_t(v)| \leq K_4(\mathcal{E}_t(v) + \|v\| + 1) \quad \forall t \in [0, T], \quad v \in D \tag{5.34}$$

for a suitable constant $K_4 \geq 0$.

In the following formula we choose a positively homogeneous and convex functional η satisfying (5.1a,b,c) and, given an absolutely continuous curve v , we denote by $|v'| (t)$ its metric derivative with respect to the asymmetric distance Δ (5.2) induced by η .

Proposition 5.11 (Chain rule). *Let $\mathcal{E} : [0, T] \times B \rightarrow (-\infty, +\infty]$ be an admissible family of functionals according to Definition 5.10, let η be a positively homogeneous functional fulfilling (5.1a,b,c) and inducing the asymmetric distance Δ (5.2), and let $v \in \text{AC}(0, T; B)$ be an absolutely continuous curve satisfying*

$$\sup_{t \in [0, T]} \mathcal{E}_t(v(t)) < +\infty, \quad \int_0^T |v'| (t) \cdot |\partial \mathcal{E}_t| (v(t)) \, dt < +\infty. \tag{5.35}$$

Then, the map $t \mapsto \mathcal{E}_t(v(t))$ is absolutely continuous and

$$\frac{d}{dt} \mathcal{E}_t(v(t)) \geq \partial_t \mathcal{E}_t(v(t)) - |\partial \mathcal{E}_t| (v(t)) \cdot |v'| (t) \quad \text{for a.e. } t \in (0, T). \tag{5.36}$$

Moreover, if v is (weakly) differentiable a.e., we have

$$\frac{d}{dt} \mathcal{E}_t(v(t)) = \partial_t \mathcal{E}_t(v(t)) + \langle \xi, v'(t) \rangle \quad \forall \xi \in \partial \mathcal{E}_t(v(t)) \quad \text{for a.e. } t \in (0, T). \tag{5.37}$$

Proof. Up to a suitable reparametrization (see [5, Lemma 1.1.4]), it is possible to assume that the curve is 1-Lipschitz (with respect to the norm of B) and

$$|v'(t)| \leq K \quad \text{for a.e. } t \in (0, T). \quad (5.38)$$

Since v is uniformly bounded and the energies $\mathcal{E}_t(v(t))$ are uniformly bounded, using (5.19) we get

$$\sup_{t \in [0, T]} \mathcal{E}_t^1(v(t)) < +\infty, \quad (5.39)$$

as well as

$$\mathcal{F}(v(s)) + |\partial_t \mathcal{F}_t(v(s))| \leq S < +\infty \quad \forall s, t \in [0, T], \quad (5.40)$$

where \mathcal{F} is defined as in (2.21). In order to show the absolute continuity of the energy map $t \mapsto \mathcal{E}_t(v(t))$, we need to estimate

$$\begin{aligned} \mathcal{E}_t(v(t)) - \mathcal{E}_s(v(s)) &= (\mathcal{E}_t(v(t)) - \mathcal{E}_t(v(s))) + (\mathcal{E}_t(v(s)) - \mathcal{E}_s(v(s))) \\ &\quad \text{for } 0 \leq s < t \leq T. \end{aligned} \quad (5.41)$$

Thanks to (5.40), we have

$$\mathcal{E}_t(v(s)) - \mathcal{E}_s(v(s)) \leq S|t - s|. \quad (5.42)$$

In order to estimate the first summand on the right-hand side of (5.41), we notice that, thanks to (5.39), the convexity of \mathcal{E}_t^1 , and (5.21),

$$\sup_{z \in [v(s), v(t)]} \mathcal{E}_t^1(z) < +\infty, \quad \text{whence} \quad \sup_{z \in [v(s), v(t)]} \|\tilde{\mathcal{D}}\mathcal{E}_t^2(z)\|_* \leq S_1 < +\infty, \quad (5.43)$$

for a positive constant S_1 . Hence, Lemma 5.8 and the 1-Lipschitz continuity of v yield

$$\begin{aligned} \mathcal{E}_t^2(v(t)) - \mathcal{E}_t^2(v(s)) &\leq \sup_{z \in [v(s), v(t)]} \|\tilde{\mathcal{D}}\mathcal{E}_t^2(z)\|_* \|v(t) - v(s)\| \leq S_1|t - s| \\ &\quad \text{for } 0 \leq s < t \leq T. \end{aligned} \quad (5.44)$$

On the other hand, thanks to (5.13)

$$\begin{aligned} \mathcal{E}_t^1(v(t)) - \mathcal{E}_t^1(v(s)) &\leq |\partial \mathcal{E}_t^1|(v(t))\eta(v(s) - v(t)) + \frac{1}{2}\lambda^- K^2 \eta^2(v(s) - v(t)) \\ &\leq \left(K|\partial \mathcal{E}_t^1|(v(t)) + K^2 S_1 + \frac{1}{2}\lambda^- K^4 \right) |t - s|, \end{aligned} \quad (5.45)$$

the latter inequality due to (5.27), (5.38) and again (5.43). Combining (5.41), (5.42), (5.44), and (5.45), and inverting the role of s and t we easily get the following estimate

$$|\mathcal{E}_t(v(t)) - \mathcal{E}_s(v(s))| \leq (K|\partial \mathcal{E}_t^1|(v(t)) + K|\partial \mathcal{E}_s^1|(v(s)) + C)|t - s| \quad (5.46)$$

for some suitable constant C . Arguing as in [5, Theorem 1.2.5], we get the absolute continuity of the energy.

Let us now fix a point $s \in (0, T)$ such that $|v'(s)$ and $\frac{d}{dt}\mathcal{E}_s(v(s))$ exist, and $|\partial\mathcal{E}_s|(v(s)) < +\infty$. Equality (5.41) and the definition of slope yield when $t \rightarrow s$

$$\mathcal{E}_t(v(t)) - \mathcal{E}_s(v(s)) \geq -|\partial\mathcal{E}_s|(v(s))\eta(v(t) - v(s)) + \partial_t\mathcal{E}_s(v_s)(t - s) + o(|t - s|)$$

so that, dividing the inequality by $t - s > 0$, we get (5.36). When v is also weakly differentiable at s , we can use the definition of Fréchet subdifferential to obtain

$$\begin{aligned} \mathcal{E}_t(v(t)) - \mathcal{E}_s(v(s)) &\geq \langle \xi, v(t) - v(s) \rangle + \partial_t\mathcal{E}_s(v_s)(t - s) + o(|t - s|) \\ &\quad \forall \xi \in \partial\mathcal{E}_s(v(s)). \end{aligned}$$

Dividing by $t - s$ and passing to the limit first as $t \downarrow s$ and then as $t \uparrow s$, we conclude. \square

6. Finsler metrics

In this section, we want to extend some of the previous results to the case in which Δ is an *nondegenerate asymmetric Finsler distance* induced by a family of convex and positively homogeneous (sublinear) functionals η_u , depending on $u \in B$ (and again we take as σ the norm topology of B).

We consider the case in which

$$B \text{ is a separable and reflexive Banach space,} \tag{6.1}$$

endowed with a family of functionals

$$\begin{aligned} \eta_u : B \rightarrow [0, +\infty), \quad u \in B, \\ \text{satisfying conditions (5.1a,b,c) with } K \text{ independent of } u. \end{aligned} \tag{6.2}$$

We are assuming that the dependence of η with respect to u is continuous in the sense of Mosco (see, e.g., [9, Section 3.3, page 295]), i.e., whenever a sequence u_n is strongly convergent to u in B as $n \uparrow \infty$, the corresponding sequence of functionals η_{u_n} Mosco-converges to η_u . This means two conditions:

$$u_n \rightarrow u, \quad v_n \rightharpoonup v \text{ in } B \quad \Rightarrow \quad \liminf_{n \rightarrow \infty} \eta_{u_n}(v_n) \geq \eta_u(v), \tag{6.3}$$

and

$$u_n \rightarrow u, \quad v \in B \quad \Rightarrow \quad \exists v_n \rightarrow v : \quad \lim_{n \rightarrow \infty} \eta_{u_n}(v_n) = \eta_u(v). \tag{6.4}$$

Let us recall a well-known consequence of this assumption:

Theorem 6.1 (Duality for Mosco-convergence). *If $u_n \rightarrow u$ in B and $\xi_n \rightharpoonup^* \xi$ in B' , then*

$$\liminf_{n \rightarrow \infty} \eta_{u_n^*}(\xi_n) \geq \eta_{u^*}(\xi). \tag{6.5}$$

Proof. We fix $v \in B$ with $\eta_u(v) = 1$ and we take a sequence v_n satisfying (6.4). We have

$$\liminf_{n \uparrow +\infty} \eta_{u_n^*}(\xi_n) \geq \liminf_{n \uparrow +\infty} \frac{\langle \xi_n, v_n \rangle}{\eta_{u_n}(v_n)} = \langle \xi, v \rangle.$$

Since v can be arbitrarily chosen with $\eta_u(v) = 1$, taking the supremum of the last duality with respect to v we conclude. \square

The induced asymmetric Finsler distance

We introduce Δ through the formula

$$\Delta(v, w) := \inf \left\{ \int_0^1 \eta_{u(t)}(u'(t)) dt : u \in AC(0, 1; B), u(0) = v, u(1) = w \right\} \tag{6.6}$$

$\forall v, w \in B.$

Note that (6.6) makes sense (the map $t \mapsto \eta_{u(t)}(u'(t))$ is integrable for all $u \in AC(0, 1; B)$) and defines a (possibly *non-symmetric*) distance (in the sense of (2.2)) on B , associated with the family $\{\eta_u\}_{u \in B}$. Since (5.1c) holds uniformly with respect to $u \in B$, we have

$$K^{-1} \|v - w\| \leq \Delta(v, w) \leq K \|v - w\| \quad \forall v, w \in B. \tag{6.7}$$

Therefore, the class of absolutely continuous curves with respect to Δ coincides with the usual one (*i.e.* with respect to the norm of B). Again, we shall use the notation (5.3) for slopes with respect to Δ .

The main problem is to characterize the metric velocity associated with Δ ; here is the main result:

Theorem 6.2 (Metric velocity). *Assume (6.1)–(6.4), and let Δ be the asymmetric distance (6.6); let $u \in AC(a, b; B)$ and let $|u'|$ be its (*a.e.* defined) metric velocity, induced by Δ . We have*

$$|u'| (t) = \eta_{u(t)}(u'(t)) \quad \text{for a.e. } t \in (a, b). \tag{6.8}$$

More precisely, the identity in (6.8) holds at each point \bar{t} fulfilling the following three conditions:

- i) u is differentiable at \bar{t} ,
- ii) \bar{t} is a Lebesgue point for the map $t \mapsto \eta_{u(t)}(u'(t))$,
- iii) $\exists \lim_{h \downarrow 0} \frac{\Delta(u(\bar{t}), u(\bar{t} + h))}{h} =: |u'|(\bar{t})$.

We split the *proof* in various steps.

Lemma 6.3. *Under the same assumptions as in Theorem 6.2, let \bar{t} be satisfying conditions i) · · · iii). We have*

$$|u'(\bar{t})| \leq \eta_{u(\bar{t})}(u'(\bar{t})). \tag{6.9}$$

Proof. For $h > 0$ let us consider the curve $r \in [0, 1] \mapsto \gamma(r) := u(\bar{t} + rh)$ connecting $u(\bar{t})$ and $u(\bar{t} + h)$. By definition of Δ and a trivial change of variables, we obtain

$$\Delta(u(\bar{t}), u(\bar{t} + h)) \leq \int_{\bar{t}}^{\bar{t}+h} \eta_{u(r)}(u'(r)) \, dr.$$

Dividing by $h > 0$ we get (6.9), being \bar{t} a Lebesgue point of the map $r \mapsto \eta_{u(r)}(u'(r))$. □

The next lemma provides the crucial technical result for the proof of Theorem 6.2, which will also be useful later on.

Lemma 6.4. *Let $u, u_n \in B$ and $h_n > 0$ such that as $n \uparrow +\infty$*

$$u_n \rightarrow u, \quad \frac{u_n - u}{h_n} \rightarrow v \neq 0, \quad \frac{\eta_u(u_n - u)}{h_n} \rightarrow \eta_u(v). \tag{6.10}$$

Then,

$$\liminf_{n \uparrow +\infty} \frac{\Delta(u, u_n)}{h_n} \geq \eta_u(v), \quad \liminf_{n \uparrow +\infty} \frac{\Delta(u, u_n)}{\eta_u(u_n - u)} \geq 1. \tag{6.11}$$

Proof. By the definition (6.6) of Δ and a standard reparametrization argument, we find Lipschitz continuous curves $\gamma_n : [0, 1] \rightarrow B$ connecting u to u_n and a vanishing positive sequence $\varepsilon_n \in (0, 1/2)$ such that

$$\Delta(u, u_n) \geq (1 - \varepsilon_n) \int_0^1 \eta_{\gamma_n(t)}(\gamma_n'(t)) \, dt, \quad \|\gamma_n'(t)\| \leq 4K \Delta(u, u_n) \tag{6.12}$$

for a.e. $t \in (0, T)$.

Dividing by h_n , we can assume that $h_n^{-1} \Delta(u, u_n) \leq A < +\infty$ for some constant $A > 0$; by introducing the curve

$$\hat{\gamma}_n(t) := u + \frac{\gamma_n(t) - u}{h_n}, \quad \text{with} \quad \hat{\gamma}_n'(t) = h_n^{-1} \gamma_n'(t),$$

we get

$$\frac{\Delta(u, u_n)}{h_n} \geq (1 - \varepsilon_n) \int_0^1 \eta_{\gamma_n(t)}(\hat{\gamma}_n'(t)) \, dt, \quad \|\hat{\gamma}_n'(t)\| \leq 4K \frac{\Delta(u, u_n)}{h_n} \leq 4KA$$

for a.e. $t \in (0, T)$,

so that

$$\liminf_{n \uparrow +\infty} \frac{\Delta(u, u_n)}{h_n} \geq \liminf_{n \uparrow +\infty} \int_0^1 \eta_{\gamma_n(t)}(\hat{\gamma}'_n(t)) dt. \tag{6.13}$$

After the extraction of a suitable subsequence (not relabeled), we can assume that the last \liminf is in fact a limit and, since $\hat{\gamma}'_n$ is uniformly bounded, that $\hat{\gamma}'_n \rightharpoonup z$ weakly in $L^2(0, 1; B)$, which is still a reflexive and separable Banach space. Since $\gamma_n(t) \rightarrow u$ uniformly as $n \rightarrow \infty$, general lower semicontinuity results for normal integrands applied to the strongly-weakly lower semicontinuous functional $(u, v) \mapsto \eta_u(v)$ (see [11, Theorem 3.2], as well as [45, Theorem 3.2] and [35, Theorem B.1]) yield

$$\liminf_{n \uparrow +\infty} \int_0^1 \eta_{\gamma_n(t)}(\hat{\gamma}'_n(t)) dt \geq \int_0^1 \eta_u(z(t)) dt \geq \eta_u(Z), \quad Z := \int_0^1 z(t) dt, \tag{6.14}$$

where the last passage follows by the convexity of η_u and Jensen inequality.

On the other hand, we have

$$\int_0^1 \hat{\gamma}'_n(t) dt = \hat{\gamma}_n(1) - \hat{\gamma}_n(0) = \frac{u_n - u}{h_n}, \tag{6.15}$$

and therefore for every $y \in B'$

$$\begin{aligned} \langle y, Z \rangle &= \int_0^1 \langle y, z(t) \rangle dt \\ &= \lim_{n \rightarrow \infty} \int_0^1 \langle y, \hat{\gamma}'_n(t) \rangle dt = \lim_{n \rightarrow \infty} \langle y, h_n^{-1}(u_n - u) \rangle = \langle y, v \rangle, \end{aligned} \tag{6.16}$$

which yields $Z = v$ and, by (6.13),

$$\liminf_{n \uparrow +\infty} \frac{\Delta(u, u_n)}{h_n} \geq \eta_u(v). \tag{6.17}$$

We conclude that

$$\liminf_{n \uparrow +\infty} \frac{\Delta(u, u_n)}{\eta_u(u_n - u)} = \liminf_{n \uparrow +\infty} \frac{\Delta(u, u_n)}{h_n} \cdot \frac{h_n}{\eta_u(u_n - u)} \geq \eta_u(v) \frac{1}{\eta_u(v)} = 1. \quad \square$$

Proof of Theorem 6.2. We can conclude now the proof of Theorem 6.2 by proving the opposite inequality

$$|u'|(\bar{t}) \geq \eta_{u(\bar{t})}(u'(\bar{t})) \tag{6.18}$$

at each point \bar{t} satisfying conditions i)–iii).

It is obviously not restrictive to assume $u'(\bar{t}) \neq 0$: we can thus apply the previous Lemma, choosing a positive vanishing sequence $h_n \downarrow 0$ and $u := u(\bar{t})$, $u_n := u(\bar{t} + h_n)$, $v = u'(\bar{t})$. \square

We apply now Lemma 6.4 to prove a useful property of the Δ -slope of an admissible functional.

Theorem 6.5. *Let \mathcal{E} be an admissible functional in the sense of Definition 5.4, let $|\partial\mathcal{E}|$ be the slope associated with the asymmetric distance (6.6), and let $\partial\mathcal{E}$ be its Fréchet subdifferential. Then, for every $u \in \text{dom}(\mathcal{E})$*

$$\begin{aligned} |\partial\mathcal{E}|(u) < +\infty &\Leftrightarrow \partial\mathcal{E}(u) \neq \emptyset, \\ |\partial\mathcal{E}|(u) \leq K \|\xi\| &\quad \forall \xi \in \partial\mathcal{E}(u), \end{aligned} \quad (6.19)$$

and, in this case,

$$|\partial\mathcal{E}|(u) \geq \min_{\xi \in \partial\mathcal{E}(u)} \eta_{u^*}(-\xi). \quad (6.20)$$

Proof. Since the asymmetric distance Δ satisfies the uniform bound (6.7), it is immediate to check that the Δ -slope of a functional \mathcal{E} is finite if and only if the slope of \mathcal{E} with respect to the norm of B is finite: (5.25) thus yields (6.19), the second estimate following from (6.2).

In order to check (6.20), we fix $u \in \text{dom}(\partial\mathcal{E})$, we choose an element $\xi_0 \in \partial\mathcal{E}(u)$ which attains the minimum in (6.20) (it is not restrictive to assume $\xi_0 \neq 0$) and we apply Lemma 5.9: we then find a sequence $u_n \in \text{dom}(\mathcal{E})$ such that

$$\begin{aligned} h_n := \eta_u(u_n - u) &\rightarrow 0, \quad \frac{u_n - u}{h_n} \rightarrow v, \quad \eta_u(v) = 1, \\ \lim_{n \uparrow +\infty} \frac{\mathcal{E}(u) - \mathcal{E}(u_n)}{h_n} &= \eta_{u^*}(-\xi_0) > 0. \end{aligned}$$

On the other hand, Lemma 6.4 yields

$$\begin{aligned} |\partial\mathcal{E}|(u) &\geq \limsup_{n \rightarrow \infty} \frac{\mathcal{E}(u) - \mathcal{E}(u_n)}{\Delta(u, u_n)} = \lim_{n \uparrow +\infty} \frac{\mathcal{E}(u) - \mathcal{E}(u_n)}{h_n} \cdot \limsup_{n \uparrow +\infty} \frac{h_n}{\Delta(u, u_n)} \\ &\geq \eta_{u^*}(-\xi_0) \cdot \eta_u(v) = \eta_{u^*}(-\xi_0). \quad \square \end{aligned}$$

Taking into account Theorem 6.1 and Proposition 5.6, we easily get

Corollary 6.6. *Let \mathcal{E} be an admissible functional and let $|\partial^-\mathcal{E}|$ be the relaxed slope associated with the asymmetric distance (6.6), i.e.*

$$|\partial^-\mathcal{E}|(u) := \inf \left\{ \liminf_{n \uparrow \infty} |\partial\mathcal{E}|(u_n) : u_n \rightarrow u, \quad \sup_n \mathcal{E}(u_n) < +\infty \right\}. \quad (6.21)$$

Then, for every $u \in \text{dom}(\mathcal{E})$

$$|\partial^-\mathcal{E}|(u) < +\infty \Leftrightarrow \partial\mathcal{E}(u) \neq \emptyset, \quad (6.22)$$

and, in this case,

$$|\partial^-\mathcal{E}|(u) \geq \min_{\xi \in \partial\mathcal{E}(u)} \eta_{u^*}(-\xi). \quad (6.23)$$

Theorem 6.7 (Relaxed slope and chain rule for admissible functionals). *Let us consider an admissible family of functionals (according to Definition 5.10) $\mathcal{E}_t : B \rightarrow (-\infty, +\infty]$, $t \in [0, T]$, and let Δ be the asymmetric Finsler distance induced by (6.6) under the assumptions of Section 6. Then, the relaxed slope $|\partial^- \mathcal{E}_t|$ satisfies the chain rule condition of Definition 2.5: for any curve $v \in AC(0, T; B)$ with*

$$\int_0^T |v'(t)| \cdot |\partial^- \mathcal{E}_t|(v(t)) \, dt < +\infty, \quad \sup_{t \in (0, T)} \mathcal{E}_t(v(t)) < +\infty, \tag{6.24}$$

the map $t \mapsto \mathcal{E}_t(v(t))$ is absolutely continuous, and

$$\frac{d}{dt} \mathcal{E}_t(v(t)) \geq \partial_t \mathcal{E}(t, v(t)) - |v'(t)| \cdot |\partial^- \mathcal{E}_t|(v(t)) \quad \text{for a.e. } t \in (0, T). \tag{6.25}$$

Proof. Since the asymmetric distance Δ is metrically equivalent to the distance induced by the norm, also on account of Proposition 5.6 inequality (6.24) yields (5.35) and we may apply Proposition 5.11. Being B reflexive, v is differentiable a.e., and therefore (5.37) yields for a.e. $t \in (0, T)$ and every $\xi \in \partial \mathcal{E}_t(v(t))$

$$\begin{aligned} \frac{d}{dt} \mathcal{E}_t(v(t)) &= \partial_t \mathcal{E}_t(v(t)) + \langle \xi, v'(t) \rangle \\ &\geq \partial_t \mathcal{E}_t(v(t)) - \eta_{v(t)}(v'(t)) \cdot \min_{\xi \in \partial \mathcal{E}_t(v(t))} \eta_{v(t)*}(-\xi) \\ &\geq \partial_t \mathcal{E}_t(v(t)) - |v'(t)| \cdot |\partial^- \mathcal{E}_t|(v(t)), \end{aligned} \tag{6.26}$$

the last inequality being a consequence of (6.8) and (6.23). □

7. Metric evolutions in $L^1(\Omega)$

Notation

In this section and in the next one, we shall denote by Ω a bounded domain of \mathbb{R}^d , $d \geq 1$, by $\|\cdot\|_r$ the norm of the space $L^r(\Omega)$, $1 \leq r \leq \infty$, and by $\langle \cdot, \cdot \rangle$ the duality pairing between $H^{-1}(\Omega)$ and $H_0^1(\Omega)$.

Setup

Throughout this section, we shall drop the reflexivity assumption (6.1) and we shall focus on the prototypical case in which

$$\text{the ambient Banach space } B \text{ is } L^1(\Omega), \text{ and } \eta \text{ is the norm functional } \|\cdot\|_1. \tag{7.1}$$

As we already mentioned in the Introduction, $L^1(\Omega)$ does not enjoy the Radon–Nikodým property. A simple example of an absolutely continuous curve $u : [0, T] \rightarrow$

$L^1(\Omega)$ which is not a.e. differentiable can be constructed, in the case $\Omega = (0, 1)$, in the following way: we take an absolutely continuous map $s : [0, T] \rightarrow [0, 1]$ and a function $a \in L^1(0, 1)$, and we let

$$u(x, t) := \begin{cases} 0 & \text{if } x \in [0, s(t)], \\ a(x) & \text{if } x \in (s(t), 1] \end{cases} \quad \forall (x, t) \in [0, 1] \times [0, T].$$

However, we may compute the metric derivative

$$|u'|_1(t) := \lim_{h \rightarrow 0} \frac{\|u(t+h) - u(t)\|_1}{h} \quad \text{for a.e. } t \in (0, T), \quad (7.2)$$

of the above curve, obtaining $|u'|_1(t) = |a(s(t))s'(t)|$ for a.e. $t \in (0, T)$.

Throughout this section, we shall analyze the metric Problem 2.6 for a given lower semicontinuous functional $\mathcal{E} : [0, T] \times L^1(\Omega) \rightarrow (-\infty, +\infty]$ in the *gradient flow* case, namely with the quadratic dissipation functional (1.16).

We shall start with some simple examples of (time-independent) energy functionals \mathcal{E} , in which it is possible to calculate explicitly a solution of the (Cauchy problem for the) associated differential inclusion (DNE) (driven by the energy \mathcal{E} and the dissipation Ψ (1.19)). Indeed, we shall show that the constructed solution also complies with the metric formulation of Problem 2.6.

Next, in Section 7.2 we shall focus on the sole metric evolution of a more general class of energy functionals (*cf.* (7.19)). Exploiting the preliminary results obtained in Sections 5.2–5.3, we shall deduce from Theorem 3.5 the existence of a solution to the associated metric formulation, see Theorem 7.5 later on.

7.1. Examples

Example 7.1. We consider $\Omega = (0, 1)$ and the quadratic energy functional \mathcal{E} (1.17). We recall that the associated differential inclusion is (1.20), which we supplement with the initial datum

$$u_0(x) := 1 - x \quad \forall x \in [0, 1]. \quad (7.3)$$

We look for a solution of the Cauchy problem (1.20, 7.3) having the form

$$u(x, t) := \begin{cases} u_0(\zeta(t)) & \text{if } x \in [0, \zeta(t)], \\ u_0(x) & \text{if } x \in (\zeta(t), 1] \end{cases} \quad \forall (x, t) \in [0, 1] \times [0, T], \quad (7.4)$$

where we require of the “free boundary” $\zeta : [0, T] \rightarrow [0, 1]$ that

$$\zeta \in C^1(0, T) \text{ and is strictly increasing, with } \zeta(0) = 0. \quad (7.5)$$

In fact, we have $u \in W^{1,1}(0, T; L^1(0, 1))$, with

$$u_t(x, t) := \begin{cases} -\zeta'(t) & \text{if } x \in (0, \zeta(t)), \\ 0 & \text{if } x \in (\zeta(t), 1) \end{cases} \quad \text{for a.e. } (x, t) \in (0, 1) \times (0, T),$$

so that $\|u_t(\cdot, t)\|_1 = \zeta(t)\zeta'(t)$ for a.e. $t \in (0, T)$. Now, (1.20) is trivially fulfilled for $x \in (\zeta(t), 1)$, $t \in (0, T)$, hence it reduces to

$$-\zeta(t)\zeta'(t) + 1 - \zeta(t) = 0 \quad t \in (0, T).$$

Namely, the function u given by (7.4) solves the Cauchy problem (1.20, 7.3) if and only if ζ fulfills

$$\zeta'(t) = \frac{1}{\zeta(t)} - 1 \quad \forall t \in (0, T), \quad \zeta(0) = 0. \tag{7.6}$$

On the other hand, we may interpret the function u as a curve $u : (0, T) \rightarrow L^1(0, 1)$: in this setting, its metric derivative is computed via (7.2). Taking into account that

$$\begin{aligned} & |u(x, t+h) - u(x, t)| \\ &= \begin{cases} \zeta(t+h) - \zeta(t) & \text{for } x \in [0, \zeta(t)], \\ \zeta(t+h) - x & \text{for } x \in (\zeta(t), \zeta(t+h)], \\ 0 & \text{for } x \in (\zeta(t+h), 1] \end{cases} \quad \forall (x, t) \in [0, 1] \times [0, T], \end{aligned}$$

formula (7.2) yields

$$|u'|_1(t) = \zeta(t)\zeta'(t) \quad \text{for a.e. } t \in (0, T) \tag{7.7}$$

(indeed, in this case $|u'|_1(t)$ coincides with the L^1 -norm of the function $u_t(\cdot, t)$ for a.e. $t \in (0, T)$). Now, we calculate the energy \mathcal{E} (1.17) along the curve u and find

$$\mathcal{E}(u(t)) = \frac{(1 - \zeta(t))^2}{6} (2\zeta(t) - 1) \quad \forall t \in [0, T], \tag{7.8}$$

while, also thanks to the representation formula (5.13) in Lemma 5.3,

$$\begin{aligned} |\partial^- \mathcal{E}|(u(t)) &= |\partial \mathcal{E}|(u(t)) \\ &= \frac{1}{2} \sup_{w \in L^1(0,1), w \neq 0} \frac{(\int_{\Omega} (u^2(x, t) - (u(x, t) + w(x))^2) dx)^+}{\|w\|_1} \\ &= \|u(\cdot, t)\|_{\infty} = 1 - \zeta(t) \quad \forall t \in [0, T]. \end{aligned} \tag{7.9}$$

In view of (7.7)–(7.9), with elementary calculations it is possible to see that, if (7.6) holds, the curve u fulfills the metric formulation (2.31)–(2.32), the latter in fact with an equality sign.

Example 7.2. We let $\Omega = (-1, 1)$ and choose as energy functional $\mathcal{E} : L^1(-1, 1) \rightarrow [0, +\infty]$ the *Dirichlet integral*

$$\mathcal{E}(u) := \begin{cases} \frac{1}{2} \int_0^1 |u'(x)|^2 dx & \text{if } u \in H_0^1(-1, 1), \\ +\infty & \text{otherwise} \end{cases} \quad \forall u \in L^1(-1, 1). \tag{7.10}$$

In fact, the above functional is a particular case of functional (7.19) below. The corresponding evolution equation is

$$\|u_t(t)\|_1 \text{Sign}(u_t(x, t)) - u_{xx}(x, t) \ni 0 \quad \text{for a.e. } (x, t) \in (-1, 1) \times (0, T), \quad (7.11)$$

(where we denote by u_x, u_{xx} the partial derivatives of u with respect to the variable x), which we supplement with the initial datum

$$u_0(x) := 1 - |x| \quad \forall x \in [-1, 1]. \quad (7.12)$$

We now look for a solution of the Cauchy problem (7.11)–(7.12) of the form

$$u(x, t) := \begin{cases} \alpha(t) + c(t) \frac{x^2}{2} & \text{if } |x| \leq \zeta(t), \\ u_0(x) & \text{if } \zeta(t) < |x| \leq 1 \end{cases} \quad \forall (x, t) \in [-1, 1] \times [0, T], \quad (7.13)$$

under the requirements that $\zeta : [0, T] \rightarrow [0, 1]$ complies with (7.5), the functions $\alpha, c \in C^1(0, T)$, c takes strictly negative values and is strictly increasing, and for all $t \in (0, T)$

the maps $x \mapsto u(x, t), x \mapsto u_t(x, t), x \mapsto u_x(x, t)$ are continuous on $[-1, 1]$. (7.14)

Since for a.e. $(x, t) \in (-1, 1) \times (0, T)$

$$u_t(x, t) := \begin{cases} \alpha'(t) + c'(t) \frac{x^2}{2} & \text{if } |x| < \zeta(t), \\ 0 & \text{if } \zeta(t) < |x| < 1 \end{cases},$$

$$u_x(x, t) := \begin{cases} c(t)x & \text{if } |x| < \zeta(t), \\ -\text{Sign}(x) & \text{if } \zeta(t) < |x| < 1 \end{cases},$$

(7.14) leads to the conditions

$$\alpha(t) + c(t) \frac{\zeta^2(t)}{2} = 1 - \zeta(t), \quad c(t) = -\frac{1}{\zeta(t)} \quad \forall t \in (0, T). \quad (7.15)$$

Hence, we compute

$$\|u_t(\cdot, t)\|_1 = \frac{c'(t)}{2} \int_{-\zeta(t)}^{\zeta(t)} (\zeta^2(t) - x^2) dx = \frac{2c'(t)}{3} \zeta^3(t) \quad \text{for a.e. } t \in (0, T). \quad (7.16)$$

Being

$$u_{xx}(x, t) := \begin{cases} c(t) & \text{if } |x| < \zeta(t), \\ 0 & \text{if } \zeta(t) < |x| < 1 \end{cases} \quad \text{for a.e. } (x, t) \in (-1, 1) \times (0, T),$$

and taking into account the second of (7.15), we conclude that u solves (7.11) if and only if c solves the Cauchy problem

$$c(t) = \frac{3}{2}c^4(t) \quad \forall t \in (0, T), \quad \text{with } \lim_{t \searrow 0} c(t) = -\infty, \quad (7.17)$$

so that

$$c(t) = -\frac{9}{2}t^{-1/3}, \quad \zeta(t) = \frac{2}{9}t^{1/3}, \quad \alpha(t) = 1 - \frac{1}{9}t^{1/3} \quad \forall t \in (0, T).$$

From the metric viewpoint, the existence of a solution to the (Cauchy problem for) the metric formulation follows from Theorem 7.5 later on. Nonetheless, we may directly check that the function u defined by (7.13) (seen as a curve on $(0, T)$ with values in $L^1(-1, 1)$) complies with (2.31)–(2.32). Indeed, using (7.15) one easily checks that the metric derivative of u again coincides with the $L^1(-1, 1)$ -norm of $u_t(\cdot, t)$ for a.e. $t \in (0, T)$, and it is thus given by (7.16). On the other hand, thanks to the forthcoming Lemma 7.3 we have that

$$|\partial^- \mathcal{E}|(u(t)) = |\partial \mathcal{E}|(u(t)) = \|u_{xx}(\cdot, t)\|_\infty \quad \text{for a.e. } t \in (0, T). \quad (7.18)$$

Then, we calculate the energy (7.10) along the curve u and, using (7.15) and (7.17) as well, we easily conclude that (2.32) holds, again as an equality.

7.2. An existence result

We consider the following energy functional $\mathcal{E} : [0, T] \times L^1(\Omega) \rightarrow (-\infty, +\infty]$, defined for all $(t, u) \in [0, T] \times L^1(\Omega)$ by

$$\mathcal{E}_t(u) := \begin{cases} \int_\Omega \left(\frac{1}{2} |\nabla u(x)|^2 + W(u(x)) \right) dx - \langle \ell(t), u \rangle & \text{if } u \in H_0^1(\Omega) \\ & \text{and } W(u) \in L^1(\Omega), \\ +\infty & \text{otherwise.} \end{cases} \quad (7.19)$$

Here, we suppose that

$$\ell \in C^1([0, T]; H^{-1}(\Omega)). \quad (7.20)$$

and that the function W fulfills

$$W \in C^2(\mathbb{R}) \quad \text{and } \exists C_W > 0 \text{ s.t. } \forall r \in \mathbb{R} \quad W''(r) \geq -C_W; \quad (7.21)$$

for instance, one may think of the double-well potential

$$W(u) := \frac{1}{4}(u^2 - 1)^2 \quad \forall u \in \mathbb{R}. \quad (7.22)$$

Note that functional \mathcal{E} (7.19) is in fact a particular case of the class of functionals (8.22) which shall be tackled in Section 8.2 later on. The following result is crucial for understanding to which equation the metric formulation of Problem 2.6 (with the quadratic dissipation (1.16) and the energy (7.19)) leads.

Lemma 7.3.

1. The functionals \mathcal{E}_t are λ -uniformly convex on $L^1(\Omega)$ for some $\lambda < 0$.
2. For every $(t, u) \in \text{dom}(\mathcal{E})$

$$|\partial\mathcal{E}_t|(u), |\partial^-\mathcal{E}_t|(u) < +\infty \text{ if and only if } -\Delta u + W'(u) - \ell(t) \in L^\infty(\Omega). \quad (7.23)$$

In this case, $|\partial\mathcal{E}_t|(u) = |\partial^-\mathcal{E}_t|(u) = \|-\Delta u + W'(u) - \ell(t)\|_\infty$.

Proof of Claim 1. In order to check the convexity inequality (5.32), we fix $u_0, u_1 \in \text{dom}(\mathcal{E})$, $\theta \in [0, 1]$, and calculate

$$\begin{aligned} \mathcal{E}_t(u_\theta) &= \int_\Omega \left(\frac{1}{2} |\nabla u_\theta|^2 + W(u_\theta) \right) - \langle \ell(t), u_\theta \rangle \\ &\leq \frac{1-\theta}{2} \int_\Omega |\nabla u_0|^2 + \frac{\theta}{2} \int_\Omega |\nabla u_1|^2 - \frac{\theta(1-\theta)}{2} \int_\Omega |\nabla(u_0 - u_1)|^2 \\ &\quad + (1-\theta) \int_\Omega W(u_0) + \theta \int_\Omega W(u_1) \\ &\quad + \frac{C_W \theta(1-\theta)}{2} \int_\Omega |u_0 - u_1|^2 - (1-\theta) \langle \ell(t), u_0 \rangle - \theta \langle \ell(t), u_1 \rangle \\ &= (1-\theta) \mathcal{E}_t(u_0) + \theta \mathcal{E}_t(u_1) \\ &\quad + \frac{\theta(1-\theta)}{2} \int_\Omega \left(-|\nabla(u_0 - u_1)|^2 + C_W |u_0 - u_1|^2 \right), \end{aligned} \quad (7.24)$$

the first inequality following from the fact that W itself is $(-C_W)$ -convex (cf. (7.21)). In order to estimate the remainder term on the right-hand side of (7.24), we apply the Gagliardo-Nirenberg inequality (see [44])

$$\|v\|_2 \leq C_{GN} \|v\|_1^{2/(d+2)} \|\nabla v\|_2^{d/(d+2)} \quad \forall v \in H_0^1(\Omega), \quad (7.25)$$

where C_{GN} is a positive constant only depending on Ω . Hence,

$$\begin{aligned} C_W \|u_0 - u_1\|_2^2 - \|\nabla(u_0 - u_1)\|_2^2 &\leq C_W C_{GN}^2 \|u_0 - u_1\|_1^{4/(d+2)} \|\nabla(u_0 - u_1)\|_2^{2d/(d+2)} \\ &\quad - \|\nabla(u_0 - u_1)\|_2^2 \\ &\leq C_d \left(C_W C_{GN}^2 \right)^{(d+2)/2} \|u_0 - u_1\|_1^2, \end{aligned}$$

for a positive constant C_d only depending on d , the latter passage following from the Young inequality. Combining this estimate with (7.24), we deduce that the convexity inequality (5.32) holds with $\lambda = -C_d (C_W C_{GN}^2)^{(d+2)/2}$. \square

Proof of Claim 2. Thanks to Claim 1 and to (5.15), it is sufficient to prove that for every $(t, u) \in \text{dom}(\mathcal{E})$

$$\begin{aligned} |\partial\mathcal{E}_t|(u) < +\infty &\Leftrightarrow -\Delta u + W'(u) - \ell(t) \in L^\infty(\Omega), \text{ and} \\ |\partial\mathcal{E}_t|(u) &= \|-\Delta u + W'(u) - \ell(t)\|_\infty \end{aligned} \quad (7.26)$$

Indeed, we set

$$\mathcal{D}(u, w) := \frac{(\mathcal{E}_t(u) - \mathcal{E}_t(u + w))^+}{\|w\|_1} \quad \text{for } u, w \in H_0^1(\Omega)$$

and note that for all $w \in H_0^1(\Omega)$

$$\mathcal{D}(u, rw) \rightarrow \mathcal{H}(u, w) := \frac{\left(\int_{\Omega} (-\nabla u \cdot \nabla w - W'(u)w) + \langle \ell(t), w \rangle \right)^+}{\|w\|_1} \quad \text{as } r \searrow 0.$$

Then, integrating by parts we find

$$|\partial \mathcal{E}_t|(u) \geq \limsup_{r \searrow 0} \mathcal{D}(u, rw) \geq \frac{\langle \Delta u - W'(u) + \ell(t), w \rangle}{\|w\|_1},$$

so that, being w arbitrary,

$$|\partial \mathcal{E}_t|(u) \geq \sup_{w \in H_0^1(\Omega)} \frac{\langle \Delta u - W'(u) + \ell(t), w \rangle}{\|w\|_1} = \|\Delta u - W'(u) + \ell(t)\|_{\infty}, \quad (7.27)$$

the latter identity by the density of $H_0^1(\Omega)$ in $L^1(\Omega)$. On the other hand, we set

$$\mathcal{G}(x, y) := W(x + y) - W(x) - W'(x)y \quad \text{for } x, y \in \mathbb{R}$$

and note that, by (7.21),

$$-\mathcal{G}(x, y) \leq \frac{C_W}{2} y^2 \quad \forall x, y \in \mathbb{R}. \quad (7.28)$$

Now, trivial computations yield that

$$\begin{aligned} |\partial \mathcal{E}_t|(u) &= \limsup_{\|w\|_1 \rightarrow 0} \mathcal{D}(u, w) \\ &\leq \limsup_{\|w\|_1 \rightarrow 0} \mathcal{H}(u, w) + \limsup_{\|w\|_1 \rightarrow 0} \frac{\left(-\frac{1}{2} \int_{\Omega} |\nabla w|^2 - \int_{\Omega} \mathcal{G}(u, w) \right)^+}{\|w\|_1}. \end{aligned} \quad (7.29)$$

We have

$$\begin{aligned} &\limsup_{\|w\|_1 \rightarrow 0} \frac{\left(-\frac{1}{2} \int_{\Omega} |\nabla w|^2 - \int_{\Omega} \mathcal{G}(u, w) \right)^+}{\|w\|_1} \\ &\leq \frac{1}{2} \limsup_{\|w\|_1 \rightarrow 0} \frac{(-\|\nabla w\|_2^2 + C_W \|w\|_2^2)^+}{\|w\|_1} \\ &\leq \frac{1}{2} \limsup_{\|w\|_1 \rightarrow 0} \frac{\left(-\|\nabla w\|_2^2 + C_W C_{GN} \|w\|_1^{4/(d+2)} \|\nabla w\|_2^{2d/(d+2)} \right)^+}{\|w\|_1} \\ &\leq \tilde{C} \limsup_{\|w\|_1 \rightarrow 0} \frac{\|w\|_1^2}{\|w\|_1} = 0, \end{aligned}$$

the first passage following from (7.28), the second one from the Gagliardo-Nirenberg inequality (7.25) and the last one by trivial calculations. Combining (7.29) and the above inequality, and again integrating by parts, we readily deduce the reverse inequality of (7.27), so that (7.26) follows. \square

Remark 7.4. In fact, the same argument as in the proof of Lemma 7.3 allows to prove that the Fréchet subdifferential of \mathcal{E} has the following structure

$$u \in \text{dom}(\partial\mathcal{E}_t) \Leftrightarrow -\Delta u + W'(u) - \ell(t) \in L^\infty(\Omega) \tag{7.30}$$

and in this case $\partial\mathcal{E}_t(u) = \{-\Delta u + W'(u) - \ell(t)\}.$

We are now in the position of proving the following existence result.

Theorem 7.5. *Assume (7.20), (7.21), and that*

$$W \text{ is bounded from below on } \mathbb{R}. \tag{7.31}$$

Then, for every $u_0 \in H_0^1(\Omega)$ with $W(u_0) \in L^1(\Omega)$ there exists a solution $u \in \text{AC}(0, T; L^1(\Omega))$ of Problem 2.6 fulfilling $u(0) = u_0$, and we have the energy identity

$$\begin{aligned} \frac{1}{2} \int_s^t |u'|_1^2(r) \, dr + \frac{1}{2} \int_s^t \| -\Delta u(r) + W'(u(r)) - \ell(r) \|_\infty^2 \, dr + \mathcal{E}_t(u(t)) \\ = \mathcal{E}_s(u(s)) + \int_s^t \langle \ell'(r), u(r) \rangle \, dr \quad \forall 0 \leq s \leq t \leq T. \end{aligned} \tag{7.32}$$

Proof. It follows from Lemma 7.3 and from (7.20) that the functional \mathcal{E} (7.19) yields an admissible family of functionals in the sense of Definition 5.10. Hence, thanks to Proposition 5.11 \mathcal{E} complies with the chain rule (5.36). Using (7.31) and arguing as in the proof of Lemma 8.10 later on, it is possible to check that the other assumptions on \mathcal{E} (2.19a)–(2.19b), and (2.34)–(2.38) of Theorem 3.5 are satisfied. Then, the statement is a direct consequence of Theorem 3.5. \square

Remark 7.6. In fact, condition (7.31) on W could be weakened, but here we prefer to keep the presentation as simple as possible, leaving to Section 8.2 the discussion of a more general example. In the particular case of the double well potential (7.22), we can infer some further regularity of the curve u from (7.32). For instance, if $\ell \in L^2(0, T; L^p(\Omega))$ for some $1 \leq p < \infty$, we deduce that $-\Delta u + u^3 - u \in L^2(0, T; L^p(\Omega))$, hence by elliptic regularity $u \in L^2(0, T; W_0^{2,p}(\Omega))$.

8. Quasivariational doubly nonlinear evolution equations in reflexive Banach spaces

In this section, we deduce from our main Theorem 3.5 an existence result (Theorem 8.3 below) for a family of abstract quasivariational doubly nonlinear equations

in the Banach space setup of Section 6. In particular, hereafter we shall assume that

$$B \text{ is a reflexive and separable Banach space.} \tag{8.1}$$

As an application, in Section 8.2 we prove the existence of solutions to initial-boundary value problems for a class of doubly nonlinear parabolic evolution equations.

8.1. A general existence result

Throughout this section, besides (8.1) we assume that

$$\begin{aligned} \eta_u : B \rightarrow [0, +\infty) \text{ is a family of convex and positively homogeneous} \\ \text{functionals, complying with (6.2), (6.3), (6.4),} \\ \text{and inducing the Finsler asymmetric distance } \Delta \end{aligned} \tag{N}$$

$$\begin{aligned} \mathcal{E}_t : B \rightarrow (-\infty, +\infty] \text{ is an } \textit{admissible family} \text{ of functionals according} \\ \text{to Definition 5.10, with sublevels locally compact with respect} \\ \text{to the strong topology of } B \text{ (cf. (2.38))} \\ \text{and the time derivative } \partial_t \mathcal{E}_t \text{ fulfils (2.37) with respect to } \Delta; \end{aligned} \tag{E}$$

$$\begin{aligned} \psi : [0, +\infty) \rightarrow [0, +\infty] \text{ is a convex, lower semicontinuous function} \\ \text{fulfilling (2.30), inducing the family of functionals} \\ \Psi_u(v) := \psi(\eta_u(v)) \in [0, +\infty], \quad \forall u, v \in B, \end{aligned} \tag{\Psi}$$

Statement of the problem

We focus on the Cauchy problem

$$\partial \Psi_{u(t)}(u'(t)) + \partial \mathcal{E}_t(u(t)) \ni 0 \quad \text{for a.e. } t \in (0, T), \quad u(0) = u_0, \tag{8.2}$$

where $u_0 \in D$ is some initial datum and $u \in AC(0, T; B)$.

This problem admits the following *metric formulation*, where $|u'|$ and $|\partial^- \mathcal{E}_t|(u)$ respectively denote the metric velocity and the (relaxed) metric slope induced by the asymmetric distance Δ :

Problem 8.1. Find a curve $u \in AC(0, T; B)$ such that

$$\begin{aligned} u(0) = u_0, \text{ the map } t \mapsto \mathcal{E}_t(u(t)) \text{ is absolutely continuous on } (0, T), \text{ and} \\ \frac{d}{dt} \mathcal{E}_t(u(t)) - \partial_t \mathcal{E}_t(u(t)) \leq -\psi(|u'|) - \psi^*(|\partial^- \mathcal{E}_t|(u(t))) \quad \text{for a.e. } t \in (0, T). \end{aligned} \tag{8.3}$$

In the sequel, we shall first of all investigate to which extent a solution u to Problem 8.1 turns out to be a solution of the Cauchy problem (8.2). Secondly, we shall deduce from the “metric” existence Theorem 3.5 an existence result for (8.2).

Links between the metric and the Banach space formulation

We have the following result, which extends [5, Proposition 1.4.1] to the doubly nonlinear setting.

Proposition 8.2. *Let $u_0 \in \mathsf{D}$ and $u \in \text{AC}(0, T; B)$ fulfill (8.3). Then, u solves the Cauchy problem (8.2). In particular, there holds*

$$\partial \Psi_{u(t)}(u'(t)) \supset \text{Argmin} \left\{ \eta_{u(t)*}(-\xi) : \xi \in \partial \mathcal{E}_t(u(t)) \right\} \quad \text{for a.e. } t \in (0, T). \quad (8.4)$$

Conversely, if u solves (8.2) and if the map $t \mapsto \mathcal{E}_t(u(t))$ is absolutely continuous on $(0, T)$, then u also fulfills (8.3).

Proof. Suppose that $u \in \text{AC}(0, T; B)$ fulfills (8.3): then, there exists a negligible set $\mathcal{N} \subset (0, T)$ such that for all $t \in (0, T) \setminus \mathcal{N}$ the derivatives $\frac{d}{dt} \mathcal{E}_t(u(t))$ and $|u'|_t = \eta_{u(t)}(u'(t))$ (see Theorem 6.2) exist, with $|\partial^- \mathcal{E}_t|(u(t)) \geq \min_{\xi \in \partial \mathcal{E}_t(u(t))} \eta_{u(t)*}(-\xi)$ by Corollary 6.6. Hence, (8.3) yields

$$\begin{aligned} \frac{d}{dt} \mathcal{E}_t(u(t)) - \partial_t \mathcal{E}_t(u(t)) &\leq -\psi(\eta_{u(t)}(u'(t))) - \psi^*(\eta_{u(t)*}(-\xi)) \\ \forall \xi &\in \text{Argmin} \left\{ \eta_{u(t)*}(-\xi) : \xi \in \partial \mathcal{E}_t(u(t)) \right\} \quad \forall t \in (0, T) \setminus \mathcal{N}. \end{aligned}$$

Combining this inequality with (6.26), we deduce that for a.e. $t \in (0, T)$

$$\begin{aligned} \eta_{u(t)}(u'(t)) \cdot \eta_{u(t)*}(-\xi) &= \psi(\eta_{u(t)}(u'(t))) + \psi^*(\eta_{u(t)*}(-\xi)), \quad \text{whence} \\ \eta_{u(t)*}(-\xi) &\in \partial \psi(\eta_{u(t)}(u'(t))) \quad \forall \xi \in \text{Argmin} \left\{ \eta_{u(t)*}(-\xi) : \xi \in \partial \mathcal{E}_t(u(t)) \right\}. \end{aligned}$$

Thanks to Lemma 5.1, we conclude (8.4).

The second part of the statement follows by the same argument. \square

An existence result

The following Theorem 8.3 extends [5, Theorem 2.3.7], of which we closely follow the proof.

Theorem 8.3. *Under assumptions (8.1), (N), (E), and (Ψ), for every $u_0 \in \mathsf{D}$ there exists a curve $u \in \text{AC}(0, T; B)$, with $u(0) = u_0$, satisfying the differential inclusion (8.4). Moreover, u fulfils the energy identity*

$$\begin{aligned} \int_s^t \Psi_{u(r)}(u'(r)) \, dr + \int_s^t \psi^*(|\partial^- \mathcal{E}_r|(u(r))) \, dr + \mathcal{E}_t(u(t)) \\ = \mathcal{E}_s(u(s)) + \int_s^t \partial_t \mathcal{E}_r(u(r)) \, dr \quad \forall 0 \leq s \leq t \leq T. \end{aligned} \quad (8.5)$$

Proof. It is straightforward to check that the functionals \mathcal{E} and ψ comply with all the assumptions of Theorem 3.5 (in particular, the chain rule of Definition 2.5 holds thanks to Theorem 6.7). Then, there exists a solution $u \in AC(0, T; B)$ to (8.3), fulfilling the energy identity (3.9). By Proposition 8.2, u solves (8.4), while, in view of (6.8), the energy identity (3.9) yields (8.5). \square

8.2. Applications to doubly nonlinear parabolic evolutions

Setup of the problem

In the sequel, we shall examine the following evolution equation (cf. with (1.15))

$$\rho_{\text{sign}(u_t)}(u) |u_t|^{p-2} u_t - \text{div}(\beta(\nabla u)) + W'(u) = h \quad \text{in } \Omega \times (0, T), \quad (8.6)$$

Here, $1 < p < \infty$, $\Omega \subset \mathbb{R}^d$, $d \geq 1$, is a bounded domain with sufficiently smooth boundary and exterior unit normal \mathbf{n} . Further, we are given two functions ρ_+ , $\rho_- : \mathbb{R} \rightarrow (0, +\infty)$, and we adopt the following notation

$$\rho_{\text{sign}(v)}(u) = \begin{cases} \rho_+(u) & \text{if } v \geq 0, \\ \rho_-(u) & \text{if } v < 0 \end{cases} \quad \forall u, v \in \mathbb{R}. \quad (8.7)$$

Moreover, $\beta : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is the gradient of some smooth function j on \mathbb{R}^d , $W : \mathbb{R} \rightarrow \mathbb{R}$ a differentiable function and $h : \Omega \times (0, T) \rightarrow \mathbb{R}$ some source term. In particular, when $\beta(\zeta) = |\zeta|^{q-2}\zeta$ for some $q > 1$, the elliptic operator in (8.6) is indeed the q -Laplacian and we recover (1.15).

We consider the following initial-boundary value problem for (8.6).

Problem 8.4. Given $u_0 \in L^p(\Omega)$, find a function $u \in W^{1,p}(0, T; L^p(\Omega))$ satisfying (8.6) a.e. on $\Omega \times (0, T)$, the homogeneous Dirichlet boundary condition

$$u = 0 \quad \text{a.e. in } \partial\Omega \times (0, T), \quad (8.8)$$

and the initial condition

$$u(x, 0) = u_0(x) \quad \text{for a.e. } x \in \Omega. \quad (8.9)$$

Further notation

Before stating our existence result for Problem 8.4, let us fix some notation. For a fixed $q \in (1, +\infty)$ we set

$$q^* := \begin{cases} \frac{dq}{d-q} & \text{if } q \in (1, d), \\ +\infty & \text{if } q \geq d. \end{cases}$$

Henceforth, we shall consider on the space $W_0^{1,q}(\Omega)$ the norm $\|u\|_{1,q} := \|\nabla u\|_q$ for all $u \in W_0^{1,q}(\Omega)$ (equivalent to the usual Sobolev norm by the Poincaré inequality);

we shall denote by $\|\cdot\|_{-1,q'}$ the norm of the dual space $W^{-1,q'}(\Omega)$ (q' being the conjugate exponent of q), and by $\langle \cdot, \cdot \rangle$ the duality pairing between $W^{-1,q'}(\Omega)$ and $W_0^{1,q}(\Omega)$. It is well known (see, e.g., [1]) that

$$W_0^{1,q}(\Omega) \subset L^{q^*}(\Omega) \text{ and } \begin{cases} W_0^{1,q}(\Omega) \subset\subset L^{q^*-\varepsilon}(\Omega) & \forall \varepsilon > 0 & \text{if } d > q, \\ W_0^{1,q}(\Omega) \subset\subset L^r(\Omega) & \forall 1 \leq r < \infty & \text{if } d = q, \\ W_0^{1,q}(\Omega) \subset\subset L^\infty(\Omega) & & \text{if } d < q. \end{cases} \quad (8.10)$$

Finally, we shall denote by $C_w^0([0, T]; W_0^{1,q}(\Omega))$ the space of weakly continuous functions with values in $W_0^{1,q}(\Omega)$.

An existence result

Let us enlist our main assumptions on the data of Problem 8.4:

$$\begin{aligned} & \text{the functions } \rho_+, \rho_- : \mathbb{R} \rightarrow (0, +\infty) \text{ are continuous, and} \\ & \exists R_0, R_1 > 0 : \quad R_0 \leq \rho_-(x), \rho_+(x) \leq R_1 \quad \forall x \in \mathbb{R}; \end{aligned} \quad (8.11)$$

there exists a function $j \in C^1(\mathbb{R}^d)$ such that $\beta = \nabla j : \mathbb{R}^d \rightarrow \mathbb{R}^d$ and

$$\begin{aligned} & \exists 1 < q < \infty \text{ with } p < q^*, \quad \exists M_1, M_2, M_3 > 0 : \\ & \begin{cases} j(\zeta) \geq M_1|\zeta|^q - M_2, \\ |\beta(\zeta)| \leq M_3(1 + |\zeta|^{q-1}) \end{cases} \quad \forall \zeta \in \mathbb{R}^d; \end{aligned} \quad (8.12)$$

further, we have

$$\begin{aligned} & W = W_c + g, \quad \text{where} \\ & W_c \text{ is a convex and differentiable function, and} \\ & g \in C^1(\mathbb{R}) \text{ satisfies the growth conditions:} \\ & \exists \alpha > 0 \text{ with } \alpha p' < q^*, \quad \exists M_4 > 0 : |g'(u)| \leq M_4(|u|^\alpha + 1) \quad \forall u \in \mathbb{R}. \end{aligned} \quad (8.13)$$

Finally, we require that

$$h \in C^1([0, T]; W^{-1,q'}(\Omega)), \quad u_0 \in W_0^{1,q}(\Omega), \quad \text{and} \quad W_c(u_0) \in L^1(\Omega). \quad (8.14)$$

Theorem 8.5. *Assume (8.11)–(8.14). Then, Problem 8.4 admits a solution*

$$\begin{aligned} & u \in W^{1,p}(0, T; L^p(\Omega)) \cap L^\infty(0, T; W_0^{1,q}(\Omega)) \subset C_w^0([0, T]; W_0^{1,q}(\Omega)), \\ & \text{with } g'(u) \in L^\infty(0, T; L^{p'}(\Omega)). \end{aligned} \quad (8.15)$$

Furthermore, if $h \in L^{p'}(0, T; L^{p'}(\Omega))$ as well, then u has the further regularity

$$-\operatorname{div}(\beta(\nabla u)) + W'_c(u) \in L^{p'}(0, T; L^{p'}(\Omega)). \quad (8.16)$$

Remark 8.6. Let us point out that, if $q \geq d$, condition (8.13) allows the non convex part of the potential g to have any polynomial growth at infinity. Furthermore, note that, in the case $d = 3$ and $p = q = 2$, the double well potential $W(u) := (u^2 - 1)^2/4$ fits in this framework. In fact, in that case the non convex function g is allowed to have a polynomial growth of order $4 - \varepsilon$ for all $\varepsilon > 0$.

Remark 8.7. Slight modifications in the assumptions, which we are not going to detail, would also allow us to prove an existence result for Problem 8.4 with homogeneous Neumann boundary conditions on u .

We shall prove Theorem 8.5 by going over to the formulation of Problem 8.4 as a doubly nonlinear evolution inclusion of the type (8.2) in the (reflexive) Banach space

$$B = L^p(\Omega), \quad 1 < p < \infty,$$

endowed with a suitable Finsler metric.

The Banach space formulation

In order to introduce the formulation of Problem 8.4 as a doubly nonlinear equation in $L^p(\Omega)$, we consider the function $\mathcal{R} : \mathbb{R}^2 \rightarrow [0, +\infty)$ given by

$$\mathcal{R}(w, z) := \begin{cases} \rho_+(w) z^p & \text{if } z \geq 0, \\ \rho_-(w) |z|^p & \text{if } z < 0 \end{cases} = \rho_{\text{sign}(z)}(w) |z|^p \quad \forall (w, z) \in \mathbb{R}^2. \tag{8.17}$$

We associate with \mathcal{R} the following family of positive functionals on $L^p(\Omega)$:

$$\eta_u(v) := \left(\int_{\Omega} \mathcal{R}(u(x), v(x)) \, dx \right)^{1/p} \quad \forall u, v \in L^p(\Omega). \tag{8.18}$$

Further, let us consider the function $\psi(x) := \frac{x^p}{p}$, $x \geq 0$, inducing (see (Ψ)) the functionals

$$\Psi_u(v) := \frac{1}{p} (\eta_u(v))^p = \frac{1}{p} \int_{\Omega} \mathcal{R}(u(x), v(x)) \, dx \quad \forall u, v \in L^p(\Omega). \tag{8.19}$$

Finally, let us define $\mathcal{E}^1 : [0, T] \times L^p(\Omega) \rightarrow (-\infty, +\infty]$ by

$$\mathcal{E}_t^1(u) := \begin{cases} \int_{\Omega} (j(\nabla u(x)) + W_c(u(x))) \, dx - \langle h(t), u \rangle & \text{if } u \in W_0^{1,q}(\Omega) \\ & \text{and } W_c(u) \in L^1(\Omega), \\ +\infty & \text{otherwise} \end{cases} \tag{8.20}$$

for all $(t, u) \in [0, T] \times L^p(\Omega)$, and $\mathcal{E}^2 : [0, T] \times L^p(\Omega) \rightarrow (-\infty, +\infty]$ by

$$\mathcal{E}_t^2(u) := \begin{cases} \int_{\Omega} g(u(x)) \, dx & \text{if } g(u) \in L^1(\Omega), \\ +\infty & \text{otherwise} \end{cases} \quad \forall (t, u) \in [0, T] \times L^p(\Omega), \tag{8.21}$$

and let us set

$$\mathcal{E}_t(u) := \mathcal{E}_t^1(u) + \mathcal{E}_t^2(u) \quad \forall (t, u) \in [0, T] \times L^p(\Omega). \quad (8.22)$$

We have the following

Proposition 8.8. *Assume (8.11)–(8.14). Then, every solution $u \in \text{AC}(0, T; L^p(\Omega))$ of the Cauchy problem (8.2) associated with the functionals $\{\Psi_u\}_{u \in L^p(\Omega)}$ and $\mathcal{E}_t : L^p(\Omega) \rightarrow (-\infty, +\infty]$, $t \in [0, T]$, respectively given by (8.19) and (8.22), is a solution of Problem 8.4.*

The proof of Proposition 8.8 ensues from the following results, which shed light on the properties of the functionals $\{\eta_u\}_{u \in L^p(\Omega)}$ (8.18) and \mathcal{E}_t (8.22).

Lemma 8.9. *Under assumption (8.11), $\{\eta_u\}_{u \in L^p(\Omega)}$ is a family of sublinear functionals complying with (6.2), (6.3), (6.4), and for all $u \in L^p(\Omega)$ we have*

$$\eta_{u*}(\xi) = \left(\int_{\Omega} \mathcal{R}_*(u(x), \xi(x)) \, dx \right)^{1/p'} \quad \forall \xi \in L^{p'}(\Omega) \quad (8.23)$$

where $\mathcal{R}_* : \mathbb{R}^2 \rightarrow (0, +\infty)$ is defined by

$$\mathcal{R}_*(w, z) := \begin{cases} \rho_+(w)^{-p'/p} z^{p'} & \text{if } z \geq 0 \\ \rho_-(w)^{-p'/p} |z|^{p'} & \text{if } z < 0 \end{cases} = \rho_{\text{sign}(z)}^{-p'/p}(w) |z|^{p'} \quad \forall (w, z) \in \mathbb{R}^2.$$

Further, for all $u \in L^p(\Omega)$ and $v \in \text{dom}(\partial\Psi_u)$ we have

$$\xi \in \partial\Psi_u(v) (\subset L^{p'}(\Omega)) \quad \Leftrightarrow \quad \xi(x) = \rho_{\text{sign}(v(x))}(u(x)) v(x)^{p-1} \quad \text{for a.e. } x \in \Omega. \quad (8.24)$$

Note that, thanks to (8.11),

$$R_1^{-p'/p} |z|^{p'} \leq \mathcal{R}_*(w, z) \leq R_0^{-p'/p} |z|^{p'} \quad \forall (w, z) \in \mathbb{R}^2. \quad (8.25)$$

Proof of Lemma 8.9. Conditions (5.1a) and (5.1c) (with K independent of u) are trivial to check.

Concerning (5.1b), let us first note that

$$\mathcal{R}(s, t_1 + t_2) \leq (\mathcal{R}(s, t_1 + t_2))^{(p-1)/p} \cdot \left(\mathcal{R}(s, t_1)^{1/p} + \mathcal{R}(s, t_2)^{1/p} \right) \quad \forall s, t_1, t_2 \in \mathbb{R}. \quad (8.26)$$

Indeed, to fix ideas let us suppose that $t_1 + t_2 \geq 0$ (the other case can be treated exactly in the same way). Then,

$$\begin{aligned} \mathcal{R}(s, t_1 + t_2) &= \rho_+(s) (t_1 + t_2)^p \\ &= \rho_+(s)^{1/p} t_1 \cdot \left(\rho_+(s)^{(p-1)/p} \cdot (t_1 + t_2)^{p-1} \right) \\ &\quad + \rho_+(s)^{1/p} t_2 \left(\rho_+(s)^{(p-1)/p} \cdot (t_1 + t_2)^{p-1} \right). \end{aligned}$$

If $t_1, t_2 \geq 0$, (8.26) follows. If, e.g., $t_1 \geq 0$ and $t_2 \leq 0$, using that $\rho_+(s)^{1/p} t_2 \leq 0 \leq \rho_-(s)^{1/p} |t_2|$ we again deduce (8.26). Therefore, by the Hölder inequality we have for all $u, v_1, v_2 \in L^p(\Omega)$:

$$\begin{aligned} \eta_u(v_1 + v_2)^p &= \int_{\Omega} \mathcal{R}(u(x), v_1(x) + v_2(x)) \, dx \\ &\leq \int_{\Omega} \mathcal{R}(u(x), v_1(x))^{1/p} \cdot (\mathcal{R}(u(x), v_1(x) + v_2(x)))^{(p-1)/p} \, dx \\ &\quad + \int_{\Omega} \mathcal{R}(u(x), v_2(x))^{1/p} \cdot (\mathcal{R}(u(x), v_1(x) + v_2(x)))^{(p-1)/p} \, dx \\ &\leq \eta_u(v_1) \cdot \eta_u(v_1 + v_2)^{(p-1)/p} + \eta_u(v_2) \cdot \eta_u(v_1 + v_2)^{(p-1)/p}, \end{aligned}$$

whence (5.1b).

We shall now prove that for all $\{u_n\}, \{v_n\} \subset L^p(\Omega)$

$$\left(u_n \rightarrow u, v_n \rightarrow v \text{ in } L^p(\Omega) \right) \Rightarrow \eta_{u_n}(v_n) \rightarrow \eta_u(v) \quad \text{as } n \uparrow \infty, \quad (8.27)$$

which clearly implies (6.4). Indeed, there exist two subsequences $\{u_{n_k}\}$ and $\{v_{n_k}\}$ such that $u_{n_k} \rightarrow u$ and $v_{n_k} \rightarrow v$ a.e. on Ω . Then it can be easily checked that

$$\mathcal{R}(u_{n_k}(x), v_{n_k}(x)) \rightarrow \mathcal{R}(u(x), v(x)) \quad \text{for a.e. } x \in \Omega.$$

From (8.11) we infer that

$$\begin{aligned} \mathcal{R}(u_{n_k}(x), v_{n_k}(x)) &\leq R_1^p |v_{n_k}(x)|^p \\ &\leq 2^{p-1} R_1^p (|v_{n_k}(x) - v(x)|^p + |v(x)|^p) \quad \text{for a.e. } x \in \Omega. \end{aligned}$$

Using a generalized version of the Lebesgue theorem (see e.g. [23]), we deduce that $\eta_{u_{n_k}}(v_{n_k}) \rightarrow \eta_u(v)$ as $k \uparrow \infty$. As the limit does not depend on the extracted subsequence, (8.27) follows.

Further, let $\{u_n\}$ and $\{v_n\}$ fulfill $u_n \rightarrow u$ and $v_n \rightarrow v$ in $L^p(\Omega)$. Again applying the aforementioned lower semicontinuity results [11, Theorem 3.2] or [35, Theorem B.1] to the functional $(u, v) \mapsto \mathcal{R}(u, v)$, we deduce that

$$\liminf_{n \uparrow \infty} \int_{\Omega} \mathcal{R}(u_n(x), v_n(x)) \, dx \geq \int_{\Omega} \mathcal{R}(u(x), v(x)) \, dx,$$

whence the lower semicontinuity property (6.3).

Finally, (8.23) follows from trivial computations and, in order to check (8.24), we fix $u \in L^p(\Omega)$ and $v \in \text{dom}(\partial\Psi_u)$, supposing without loss of generality that

$\eta_u(v) \neq 0$ (if $\eta_u(v) = 0$, necessarily $v = 0$ and the check of (8.24) simplifies). By Lemma 5.1 and the definition (8.19) of Ψ_u , we have

$$\begin{aligned} \xi \in \partial \Psi_u(v) &\Leftrightarrow \eta_{u*}(\xi) = \eta_u(v)^{p-1} \text{ and } \eta_{u*}(\xi) = \frac{\int_{\Omega} \xi(x)v(x) \, dx}{\eta_u(v)} \\ &\Leftrightarrow \left(\int_{\Omega} \mathcal{R}(u(x), v(x)) \, dx \right)^{(p-1)p} = \eta_{u*}(\xi) = \frac{\int_{\Omega} \xi(x)v(x) \, dx}{\left(\int_{\Omega} \mathcal{R}(u(x), v(x)) \, dx \right)^{1/p}} \\ &\Leftrightarrow \xi(x) = \rho_{\text{sign}(v(x))}(u(x))|v(x)|^{p-2}v(x) \quad \text{for a.e. } x \in \Omega. \quad \square \end{aligned}$$

Lemma 8.10. *Assume (8.12)–(8.14). Then, the functional $\mathcal{E} : [0, T] \times L^p(\Omega)$ defined by (8.22) yields an admissible family of functionals (according to Definition 5.10), fulfilling condition (E) of Section 8.1. Furthermore, for all $t \in [0, T]$ the Fréchet subdifferential $\partial \mathcal{E}_t(u) \neq \emptyset$ if and only if $-\text{div}(\beta(\nabla(u))) + W'(u) - h(t) \in L^{p'}(\Omega)$ and, in that case,*

$$\partial \mathcal{E}_t(u) := \{-\text{div}(\beta(\nabla(u))) + W'(u) - h(t)\}. \tag{8.28}$$

Proof. Hereafter, we focus on the case in which $q < d$, as the proof in the other case is analogous and slightly simpler. Note that

$$\text{dom}(\mathcal{E}_t) = \text{D} = \left\{ u \in W_0^{1,q}(\Omega) : W_c(u) \in L^1(\Omega) \right\} \quad \forall t \in [0, T].$$

It follows from [26, Theorem 2.5, p. 22] that for all $t \in [0, T]$ the functional \mathcal{E}_t^1 is convex and lower semicontinuous. Moreover, recalling that

$$\exists l_1, l_2 > 0 : \quad W_c(u) \geq -l_1 u - l_2 \quad \forall u \in \mathbb{R},$$

we find that

$$\begin{aligned} \mathcal{E}_t^1(u) &\geq M_1 \|\nabla u\|_q^q - l_1 \|u\|_1 - \|h(t)\|_{-1,q'} \|u\|_{1,q} - C \\ &\geq \frac{M_1}{2} \|u\|_{1,q}^q - C \|h\|_{L^\infty(0,T;W^{-1,q'}(\Omega))}^{q'} - C' \end{aligned} \tag{8.29}$$

for all $(t, u) \in [0, T] \times W_0^{1,q}(\Omega)$, due to (8.12) and an elementary application of the Young inequality. Hence, the functionals \mathcal{E}_t^1 are uniformly bounded from below with respect to t . Arguing as in [46], it can be readily checked that for all $(t, u) \in [0, T] \times W_0^{1,q}(\Omega)$

$$\partial \mathcal{E}_t^1(u) = \begin{cases} \{-\text{div}(\nabla \beta(u)) + W'_c(u) - h(t)\} & \text{if } \text{div}(\nabla \beta(u)) - W'_c(u) + h(t) \in L^{p'}(\Omega), \\ \emptyset & \text{otherwise.} \end{cases} \tag{8.30}$$

On the other hand, one trivially sees that the functional \mathcal{E}^2 is lower semicontinuous; further, using the growth condition for g' in (8.13), the Sobolev embedding (8.10), as well as the Hölder and the Young inequalities, one has for all $\nu > 0$

$$\begin{aligned} |\mathcal{E}_t^2(u)| &\leq M_4 \int_{\Omega} |u(x)|^{\alpha+1} dx + C \leq M_4 \| |u|^\alpha \|_{p'} \|u\|_p + C \\ &\leq C' \|u\|_{q^*} \|u\|_p + C \leq \nu \|u\|_{q^*}^q + C_\nu \|u\|_p^{q'} + C, \end{aligned}$$

so that (5.19) follows by combining the above estimate with (8.29) and choosing ν in such a way that $2\nu/M_1 < 1$. Moreover, (8.29) yields that the sublevels of $\mathcal{E}_t(\cdot)$ are bounded in $W_0^{1,q}(\Omega)$ (which is compactly embedded in $L^p(\Omega)$), uniformly with respect to $t \in [0, T]$, hence (2.38) is fulfilled.

Let us now check that \mathcal{E}_t^2 fulfills the “differentiability” property (5.20) with

$$\tilde{D}\mathcal{E}_t^2(u) = g'(u) \quad \forall u \in W_0^{1,q}(\Omega) \quad \forall t \in [0, T]. \tag{8.31}$$

Indeed, arguing as above we see that by (8.13) and (8.29) there exists a positive constant M_5 such that for all $u \in W_0^{1,q}(\Omega)$

$$g'(u) \in L^{p'}(\Omega) \text{ and } \|g'(u)\|_{p'} \leq C \left(\|u\|_{q^*}^{q^*} + 1 \right)^{1/p'} \leq M_5 \left(\mathcal{E}_t^1(u)^{q^*/qp'} + 1 \right). \tag{8.32}$$

In order to check (5.20), let us fix a sequence $\{u_n\} \subset W_0^{1,q}(\Omega)$ fulfilling $\sup_n \mathcal{E}_t(u_n)$ and converging to u in $L^p(\Omega)$: it follows from (8.29) and from (8.10) that

$$u_n \rightarrow u \quad \text{in } L^{q^*-\varepsilon}(\Omega) \text{ for all } \varepsilon > 0. \tag{8.33}$$

By the mean value theorem, for a.e. $x \in \Omega$

$$g(u_n(x)) - g(u(x)) = \left(\int_0^1 g'((1-t)u_n(x) + tu(x)) dt \right) (u_n(x) - u(x)). \tag{8.34}$$

Therefore,

$$\begin{aligned} &\lim_{n \uparrow \infty} \frac{\left| \int_{\Omega} g(u_n(x)) - g(u(x)) - g'(u(x))(u_n(x) - u(x)) dx \right|}{\|u_n - u\|_p} \\ &\leq \lim_{n \uparrow \infty} \frac{\int_{\Omega} \left| \int_0^1 (g'((1-t)u_n(x) + tu(x)) - g'(u(x))) dt \right| |u_n(x) - u(x)| dx}{\|u_n - u\|_p} \\ &\leq \lim_{n \uparrow \infty} \int_0^1 \|g'((1-t)u_n + tu) - g'(u)\|_{p'} dt. \end{aligned}$$

the first inequality following from (8.34) and the second one from the Hölder inequality. Using the growth condition (8.13), (8.33) and a version of the Dominated Convergence theorem (see [23]), we infer that

$$\int_0^1 \|g'((1-t)u_n + tu) - g'(u)\|_{p'} dt \rightarrow 0 \quad \text{as } n \uparrow \infty,$$

hence (8.31) follows. Then, (5.21) follows from (8.32). Noting that $\partial_t \mathcal{E}_t(u) = -\langle h'(t), u \rangle$ for every $u \in W_0^{1,q}(\Omega)$, we readily conclude from the previous computations that (5.34) holds. Hence, (2.37) follows from the fact that the sublevels of \mathcal{E}_t are weakly compact in $W_0^{1,q}(\Omega)$ and that $h' \in C^0([0, T]; W^{-1,q'}(\Omega))$. Finally, (8.28) follows from the representation formula (5.23) of the Fréchet subdifferential of admissible functionals, joint with (8.30) and (8.31). \square

Proof of Theorem 8.5. It follows from Lemma 8.9 and Lemma 8.10 that for any $u_0 \in W_0^{1,q}(\Omega)$ every solution $u \in AC(0, T; L^p(\Omega))$ of the Cauchy problem (8.2) associated with the functionals (8.19) and (8.22) is indeed a solution to Problem 8.4. Since conditions (N)–(Ψ) of Section 8.1 are fulfilled, Theorem 8.3 thus yields the existence of a solution u to the latter initial-boundary value problem. As a consequence of the energy identity (8.5), of (8.19), (8.23), (6.23), and (8.28), u fulfils the energy inequality

$$\begin{aligned} & \frac{1}{p'} \int_s^t \int_{\Omega} \mathcal{R}_*(u(x, r), \operatorname{div}(\beta(\nabla u(x, r))) - W'(u(x, r)) + h(x, r)) \, dx \, dr \\ & + \frac{1}{p} \int_s^t \int_{\Omega} \mathcal{R}(u(x, r), u_t(x, r)) \, dx \, dr + \mathcal{E}_t(u(t)) \\ & = \mathcal{E}_s(u(s)) + \int_s^t \langle h'(r), u(r) \rangle \, dr \quad \forall 0 \leq s \leq t \leq T. \end{aligned} \tag{8.35}$$

In particular, thanks to (8.11) we conclude that $u \in W^{1,p}(0, T; L^p(\Omega))$, while estimates (8.29), (8.32) and $\sup_{t \in [0, T]} \mathcal{E}_t(u(t)) < +\infty$ yield (8.15). Finally, recalling (8.25) we also deduce an estimate for $-\operatorname{div}(\beta(\nabla u)) + W'_c(u) - h$ in $L^{p'}(0, T; L^{p'}(\Omega))$, and (8.16) ensues. \square

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